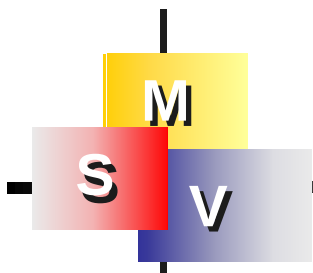


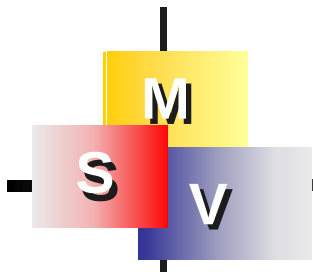
Part III

Plate vibration



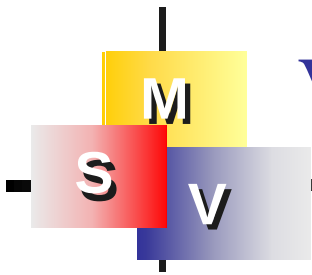
Outlines

1. Introduction
2. Plate vibration
3. Derivation by Circulants
4. SVD updating terms
5. Conclusions



Outlines

- 1. Introduction**
- 2. Plate vibration**
- 3. Derivation by Circulants**
- 4. SVD updating terms**
- 5. Conclusions**



Vibration of plates

Governing Equation:

$$\nabla^4 u(x) = \lambda^4 u(x), x \in \Omega$$

$$\lambda^4 = \frac{\omega^2 \rho h}{D}$$

$$D = \frac{E h^3}{12 (1 - \nu^2)}$$

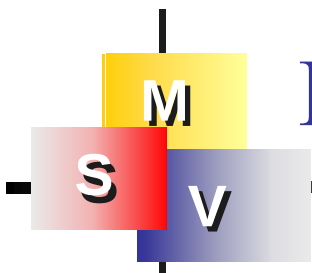
ω is the angle frequency
 ρ is the surface density
 D is the bending rigidity
 h is the plate thickness
 E is the Young's modulus
 ν is the Poisson ratio

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Field representation using RBF

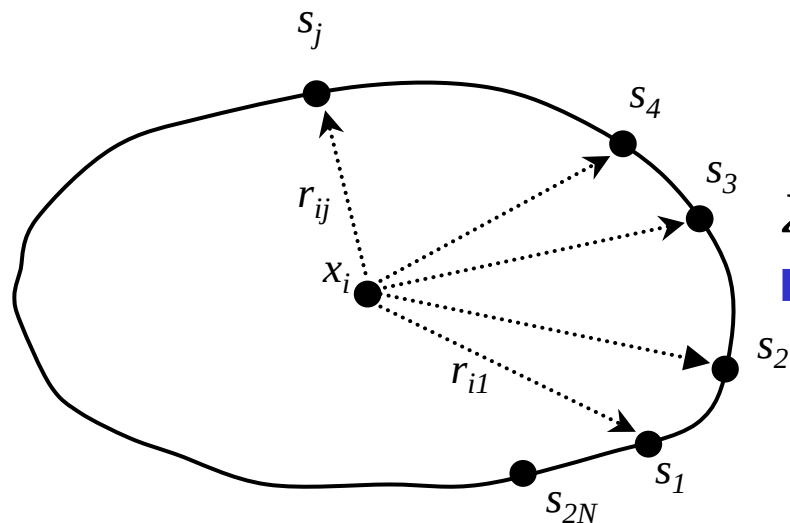
$$u(x) = \sum c_j \psi(x_i, s_j)$$

$$\psi(x, s) = \psi(r)$$

$$\{u\} = \begin{bmatrix} \cdot & \cdot & * & * & * & * \\ * & \cdot & \cdot & * & * & * \\ * & * & \cdot & * & * & * \\ * & * & * & \cdot & * & * \\ * & * & * & * & \cdot & * \\ * & * & * & * & * & \cdot \end{bmatrix} \{c\}$$

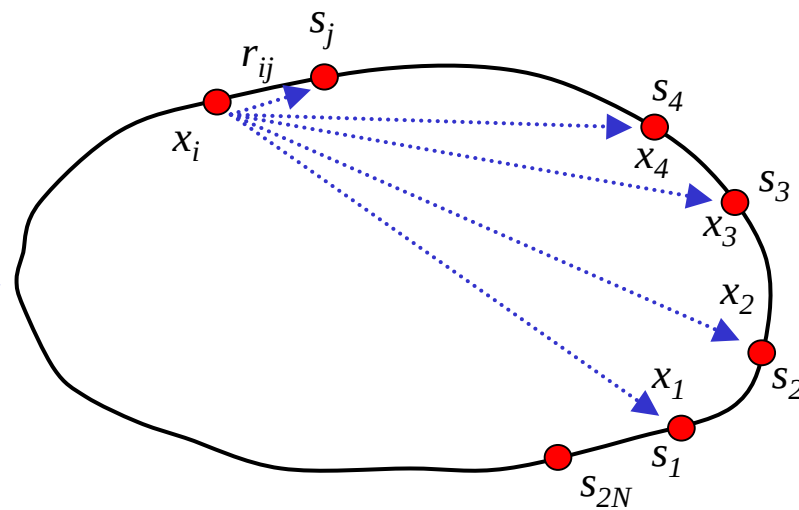
$r \neq 0$

$r = 0$

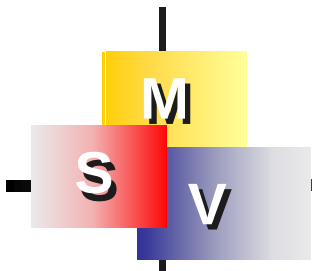


Field representation

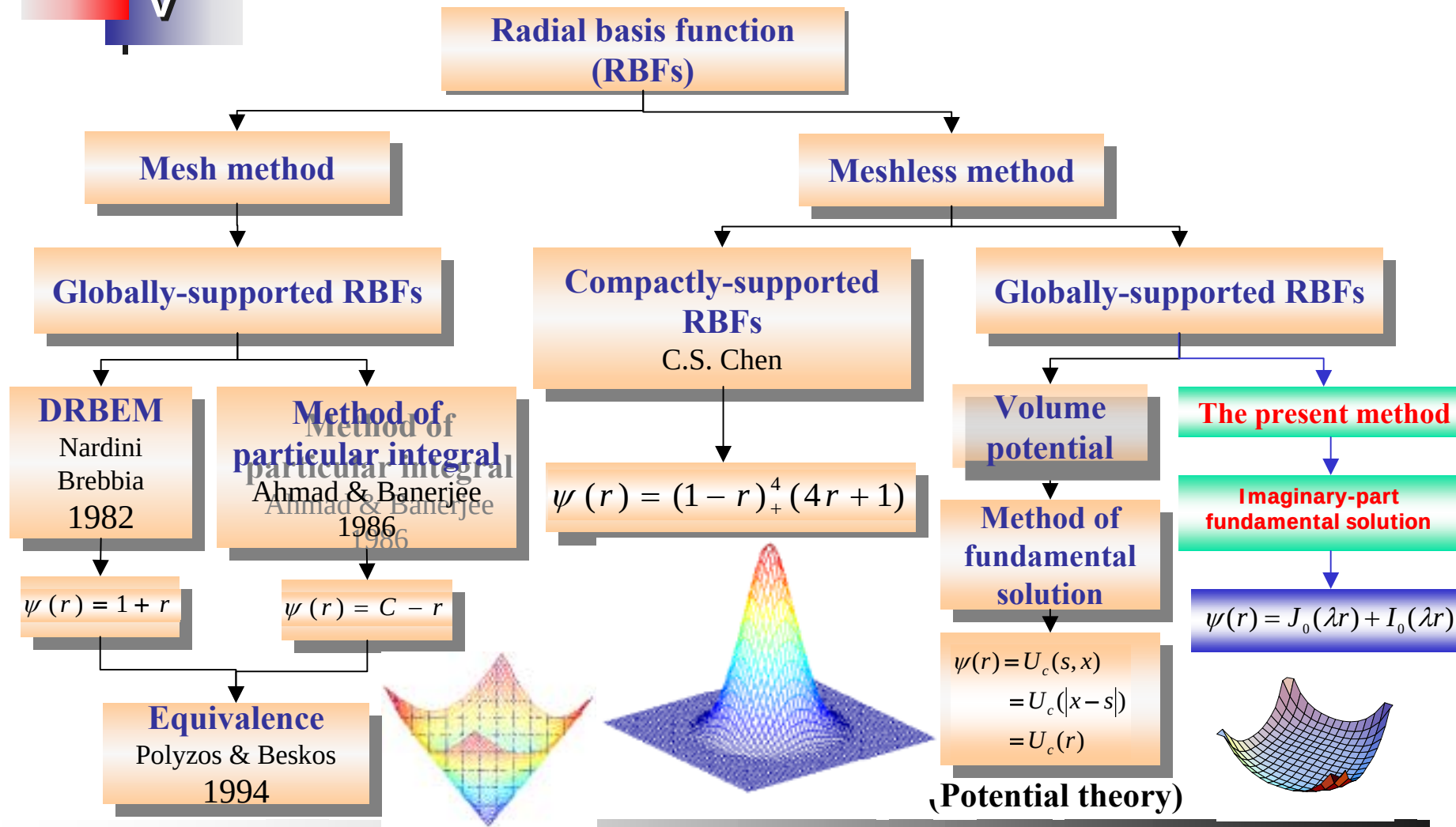
$x \rightarrow B$



To match B.C.



Data bank of RBF

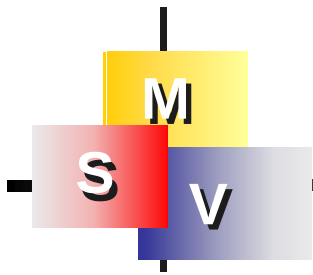


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Outlines

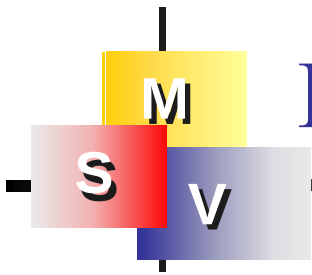
1. Introduction

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Displacement field of plate vibration

$$u(s, x) = \sum_{j=1}^{2N} P(s_j, x) \phi_j + \sum_{j=1}^{2N} Q(s_j, x) \psi_j$$

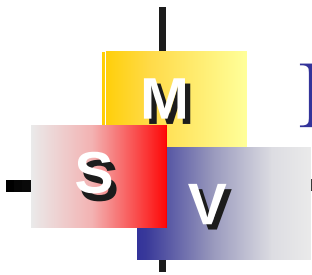
$2N$ is the number of boundary nodes

s is the source point

x is the collocation point

$\mathbf{f}_j$ and $\mathbf{y}_j$ are the unknown densities

P and Q can be obtained from either two combinations of U , Q , M and V

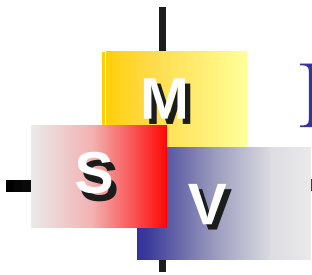


Four kernels

Imaginary-part fundamental solution

$$U(s, x) = \text{Im} \left\{ \frac{i}{8\lambda^2} (H_0^{(2)}(\lambda r) + H_0^{(1)}(i\lambda r)) \right\}$$

$$U(s, x) = \frac{1}{8\lambda^2} (J_0(\lambda r) + I_0(\lambda r))$$

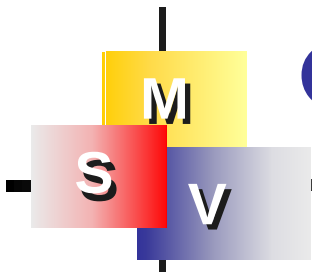


Four kernels

$$\Theta(s, x) = K_{\theta}(U(s, x))$$

$$M(s, x) = K_m(U(s, x))$$

$$V(s, x) = K_v(U(s, x))$$

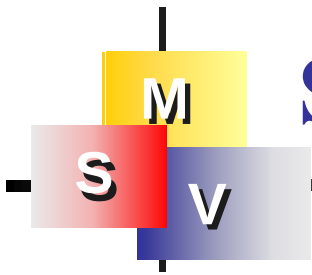


Operators

$$K_{\theta}(\cdot) = \frac{\partial(\cdot)}{\partial n}$$

$$K_m(\cdot) = \nu \nabla^2(\cdot) + (1 - \nu) \frac{\partial^2(\cdot)}{\partial n^2}$$

$$K_v(\cdot) = \frac{\partial \nabla^2(\cdot)}{\partial n} + (1 - \nu) \frac{\partial}{\partial t} \left(\frac{\partial^2(\cdot)}{\partial n \partial t} \right)$$

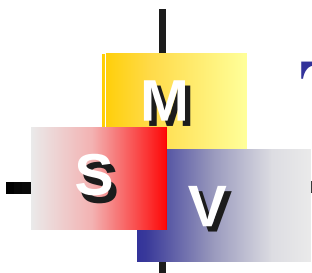


Slope, Moment and Shear

Slope $\theta(x) = K_{\theta}(u(x))$

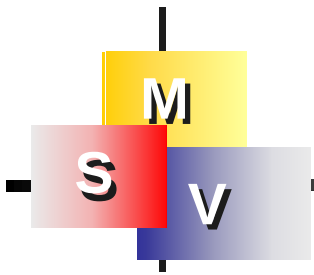
Moment $m(x) = K_m(u(x))$

Shear $v(x) = K_v(u(x))$



True eigenequation of three cases

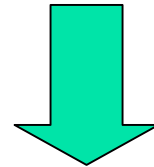
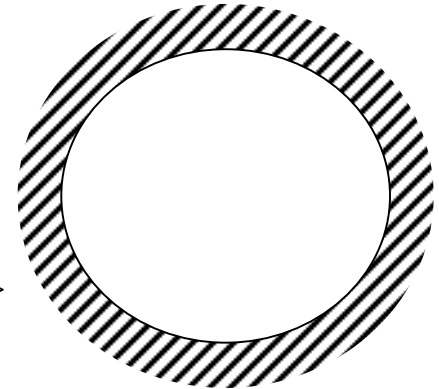
	B.C.	True eigenequation
Clamped plate	$u(x)=0$ $q(x)=0$	$J'_\ell(\lambda\rho)I_\ell(\lambda\rho) - I'_\ell(\lambda\rho)J_\ell(\lambda\rho) = 0$
Simply-supported plate	$u(x)=0$ $m(x)=0$	$\frac{I_{\ell+1}(\lambda\rho)}{I_\ell(\lambda\rho)} + \frac{J_{\ell+1}(\lambda\rho)}{J_\ell(\lambda\rho)} = \frac{2\lambda\rho}{(1-\nu)}$
Free plate	$m(x)=0$ $v(x)=0$	$(\ell^2(\ell^2-1)(-1+\nu)^2 + \lambda^4 a^4)(J_{\ell+1}(\lambda a)I_\ell(\lambda a) + J_\ell(\lambda a)I_{\ell+1}(\lambda a))$ $+ 2\ell\lambda^2 a^2(1-\ell)(-1+\nu)(J_{\ell+1}(\lambda a)I_\ell(\lambda a) - J_\ell(\lambda a)I_{\ell+1}(\lambda a))$ $+ \lambda a(-1+\nu)(2\lambda^2 a^2 J_{\ell+1}(\lambda a)I_{\ell+1}(\lambda a) + 4\ell^2(-1+\ell)J_\ell(\lambda a)I_\ell(\lambda a)) = 0$



Clamped plate

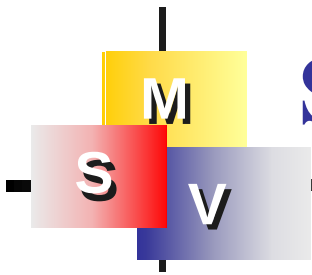
$$u(x) = 0 \Rightarrow [U]\{\phi\} + [\Theta]\{\psi\} = \{0\}$$

$$\theta(x) = 0 \Rightarrow [U_\theta]\{\phi\} + [\Theta_\theta]\{\psi\} = \{0\}$$



Nontrivial

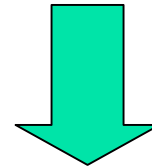
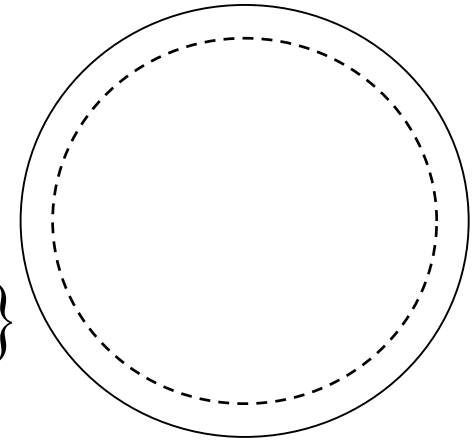
$$0 = \det[SM^c] \quad \leftarrow \quad \begin{bmatrix} U & \Theta \\ U_\theta & \Theta_\theta \end{bmatrix} \begin{Bmatrix} \phi \\ \psi \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$



Simply-supported plate

$$u(x) = 0 \longrightarrow [U]\{\phi\} + [\Theta]\{\psi\} = \{0\}$$

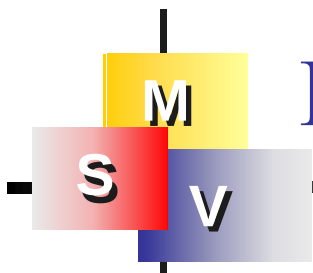
$$m(x) = 0 \longrightarrow [U_m]\{\phi\} + [\Theta_m]\{\psi\} = \{0\}$$



Nontrivial

$$0 = [SM^s]$$

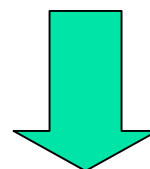
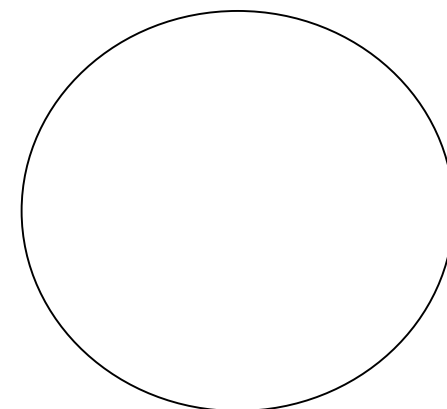
$$\begin{bmatrix} U & \Theta \\ U_m & \Theta_m \end{bmatrix} \begin{Bmatrix} \phi \\ \psi \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$



Free plate

$$m(x) = 0 \Rightarrow [U_m]\{\phi\} + [\Theta_m]\{\psi\} = \{0\}$$

$$v(x) = 0 \Rightarrow [U_v]\{\phi\} + [\Theta_v]\{\psi\} = \{0\}$$

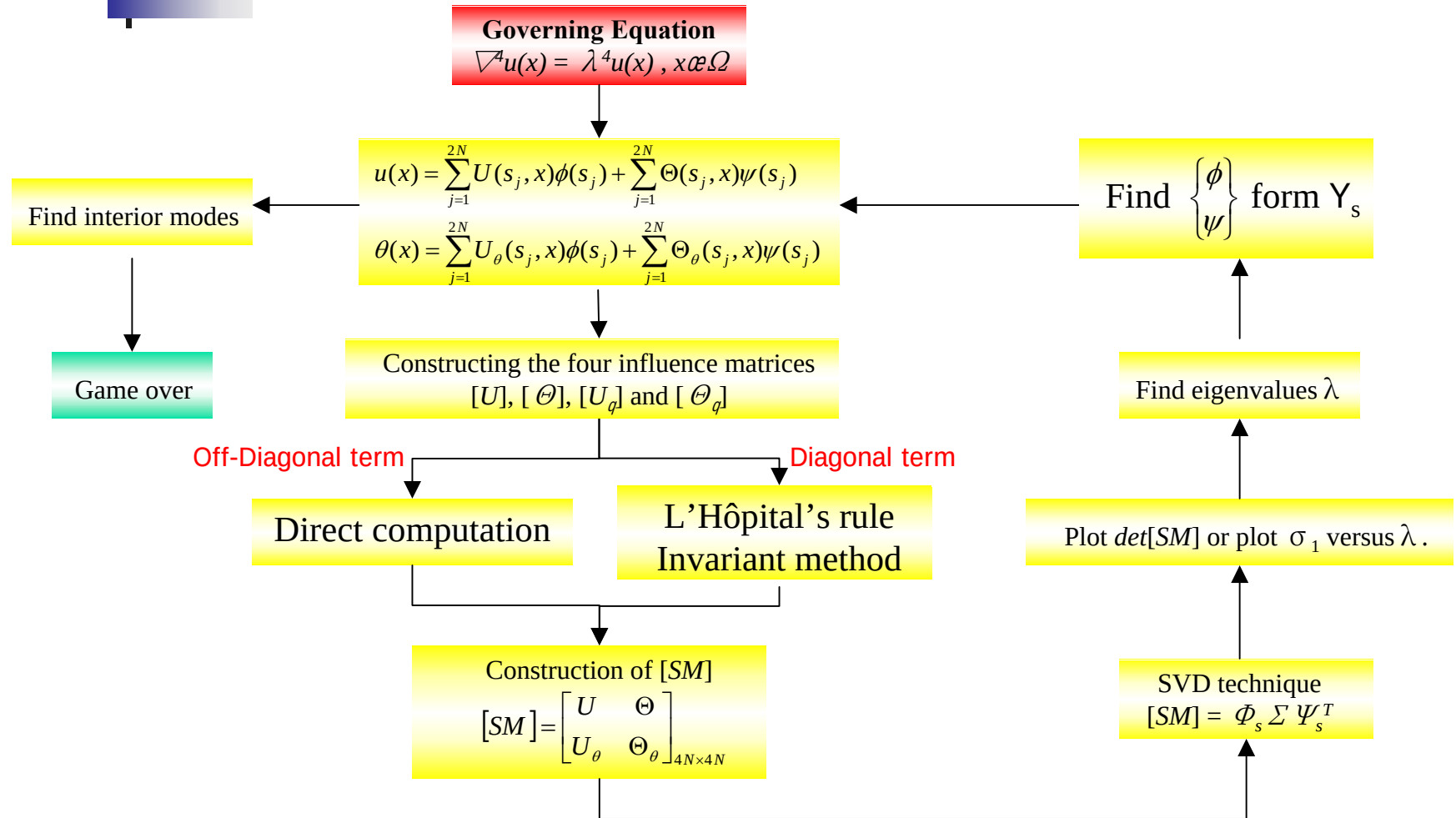


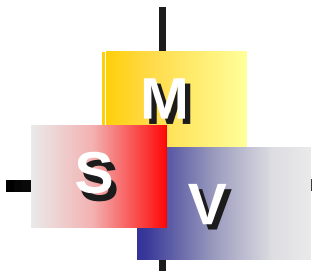
Nontrivial

$$0 = [SM^F]$$

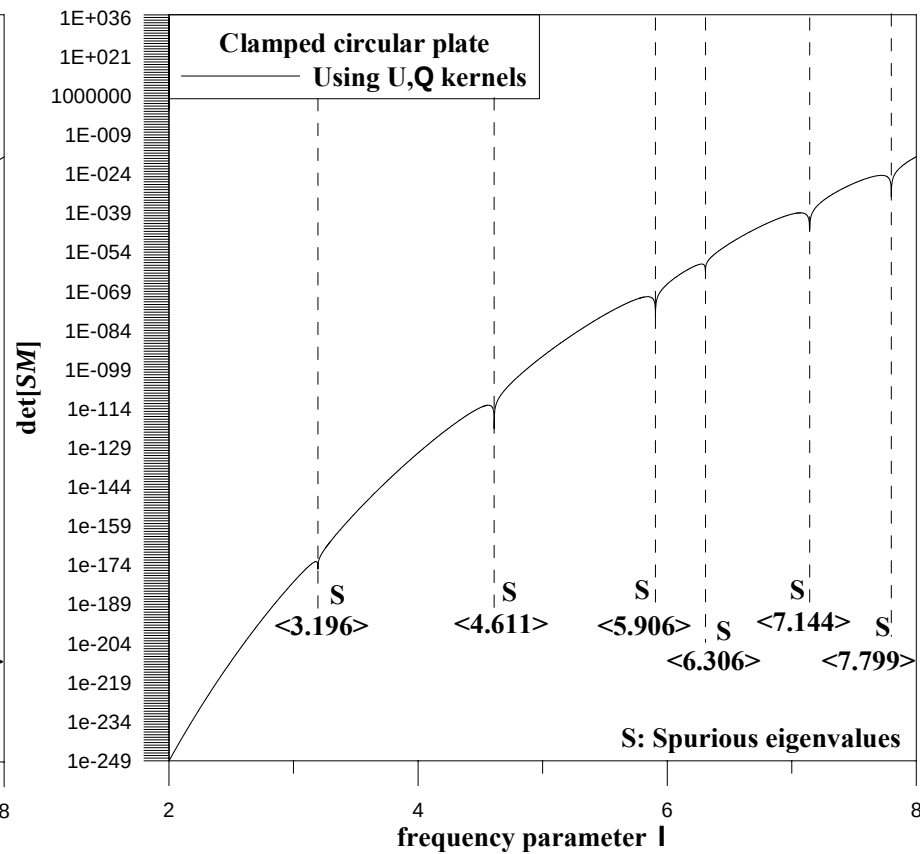
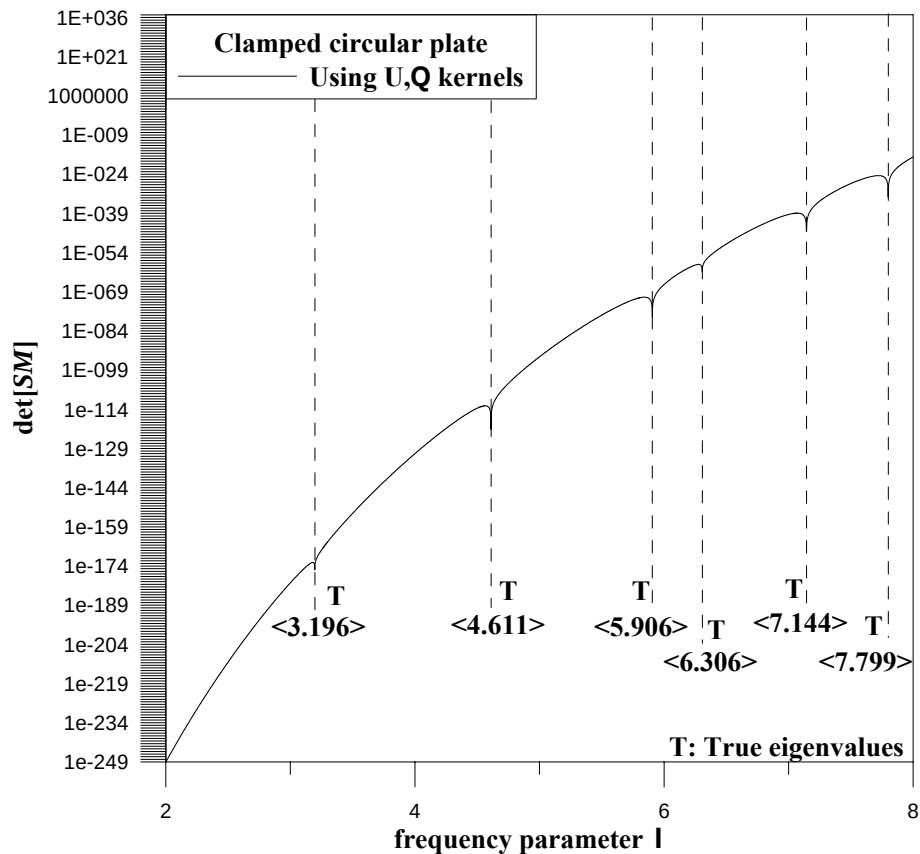
$$\begin{bmatrix} U_m & \Theta_m \\ U_v & \Theta_v \end{bmatrix} \begin{Bmatrix} \phi \\ \psi \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$

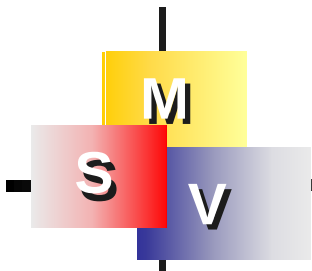
Flow chart of the present method for clamped case by using U and Q kernels



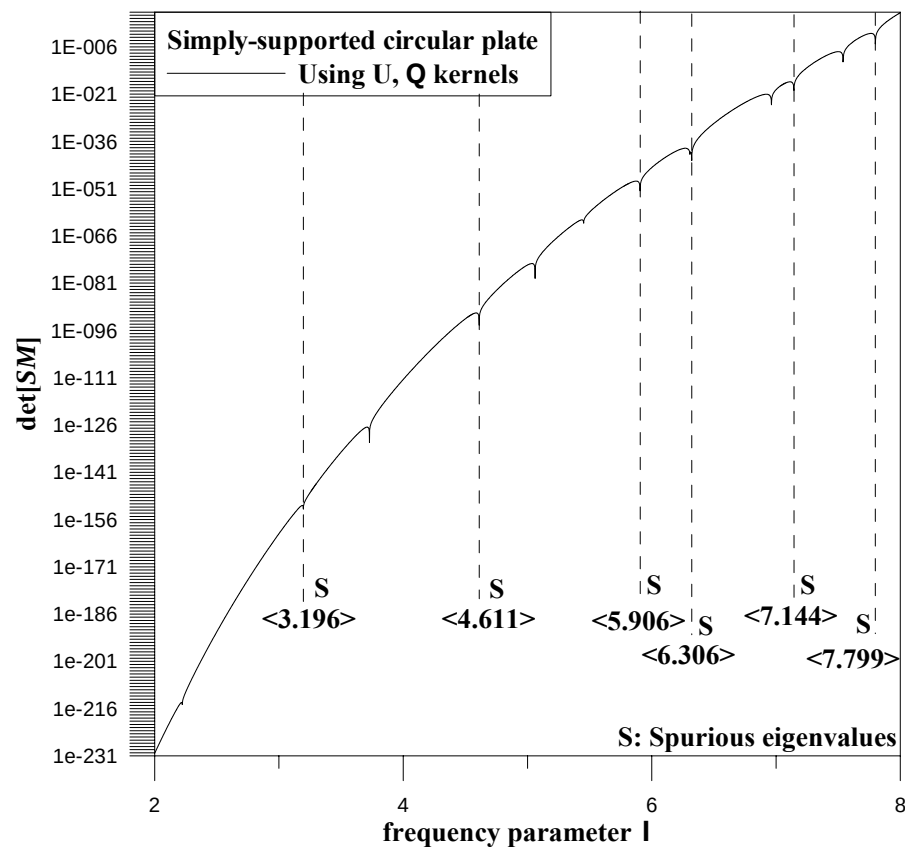
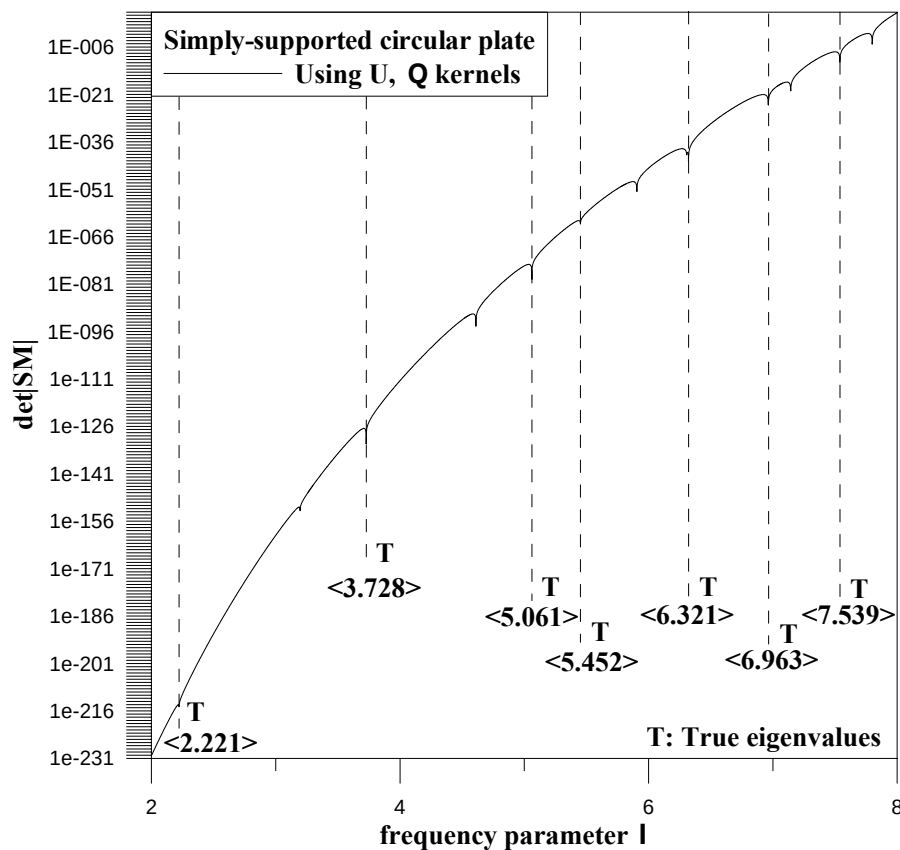


Case 1: Circular clamped plate using the present method





Case 2: Circular simply-supported plate using the present method

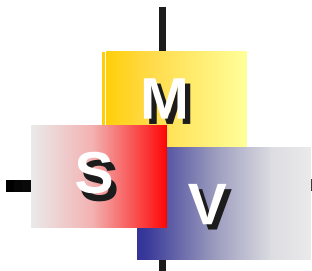


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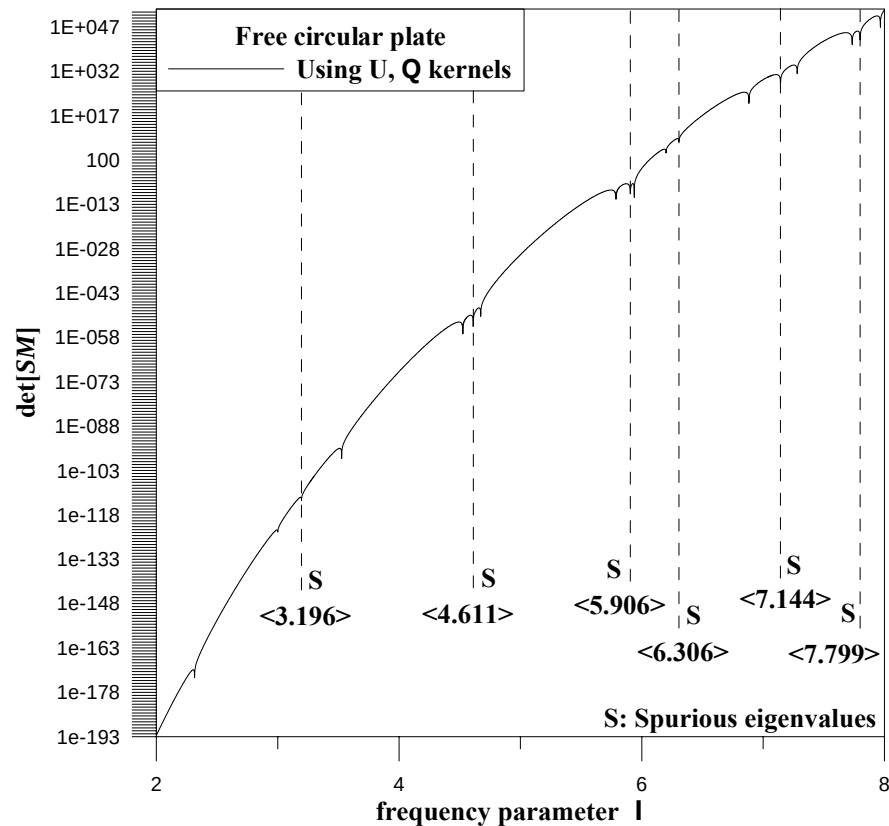
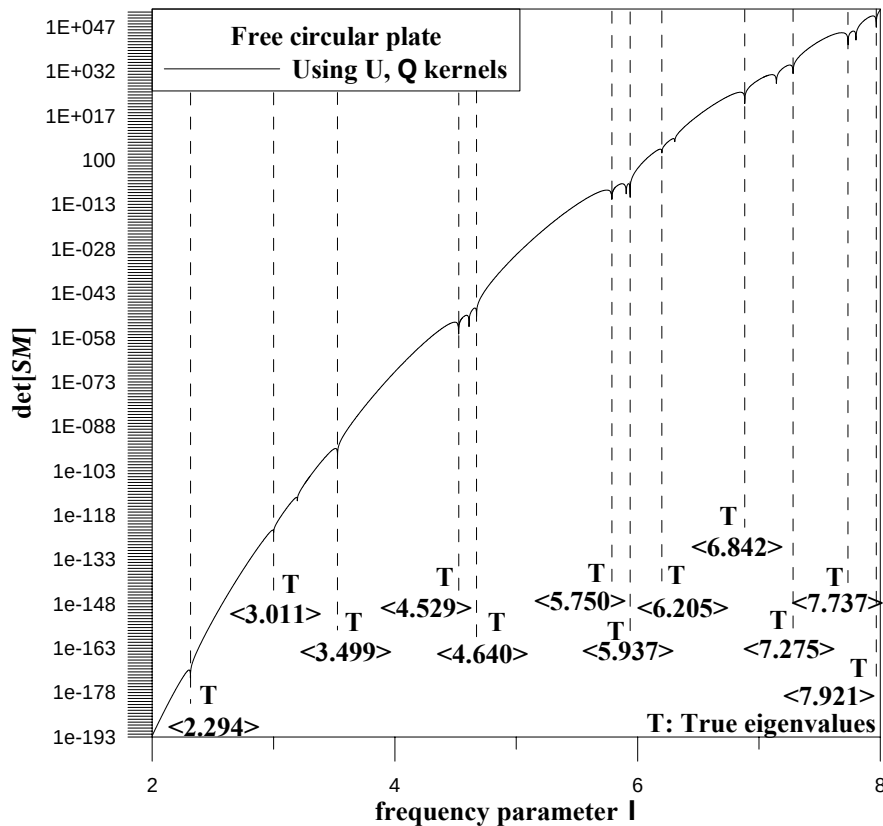


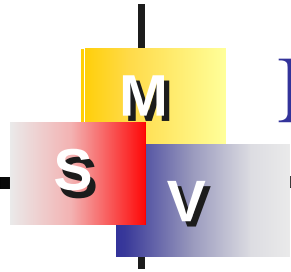
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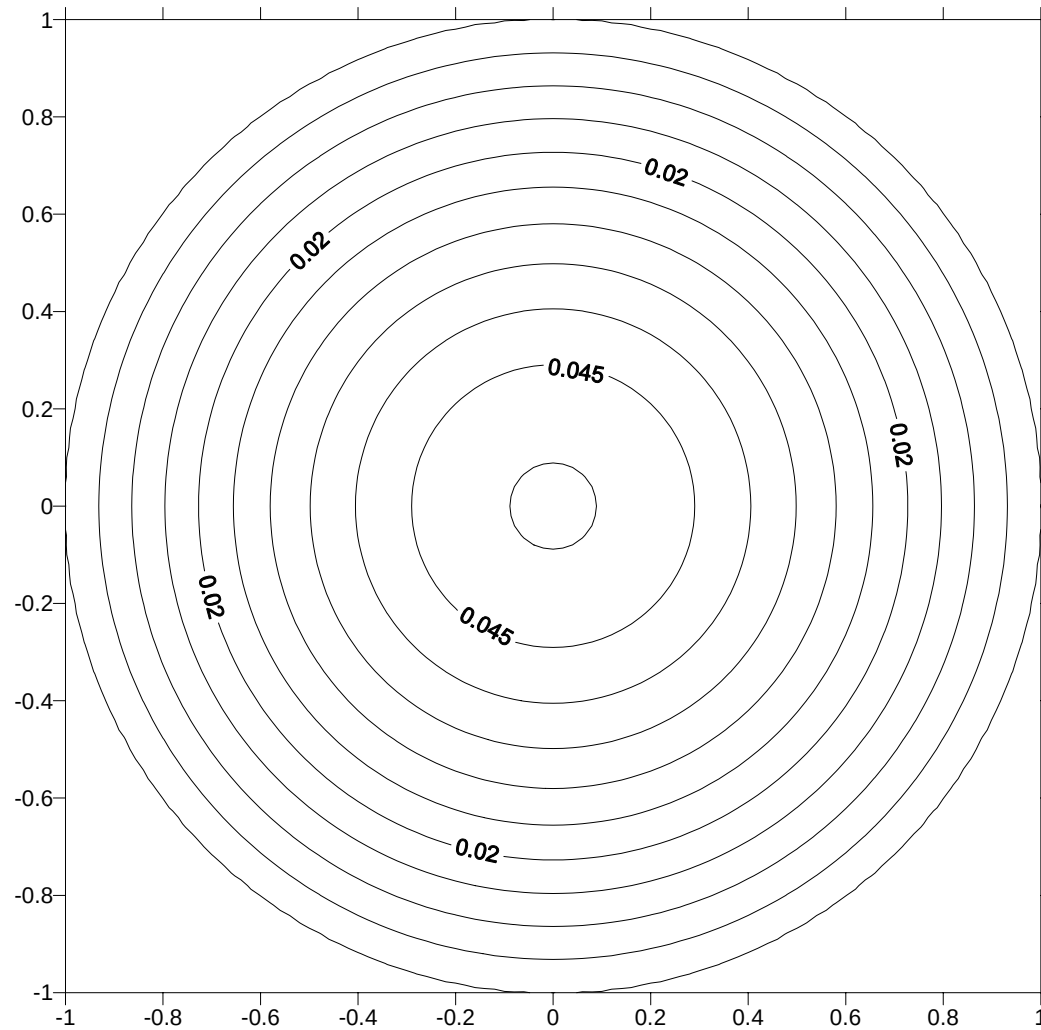


Case 3: Circular free plate using the present method





Mode 1 ($\lambda = 2.221$)

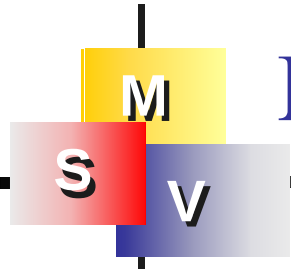


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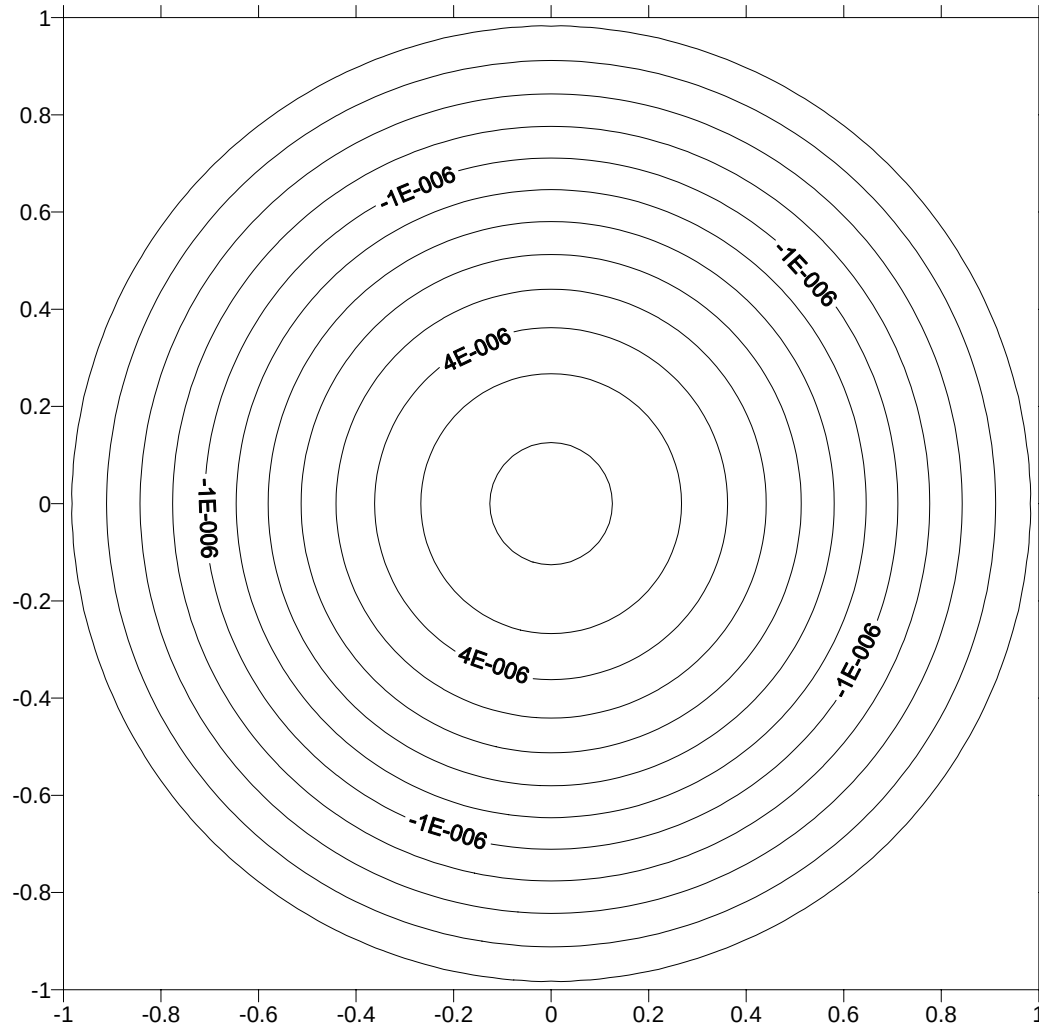


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Mode 2 ($\lambda=3.196$)

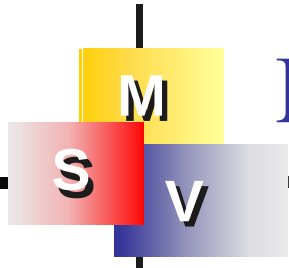


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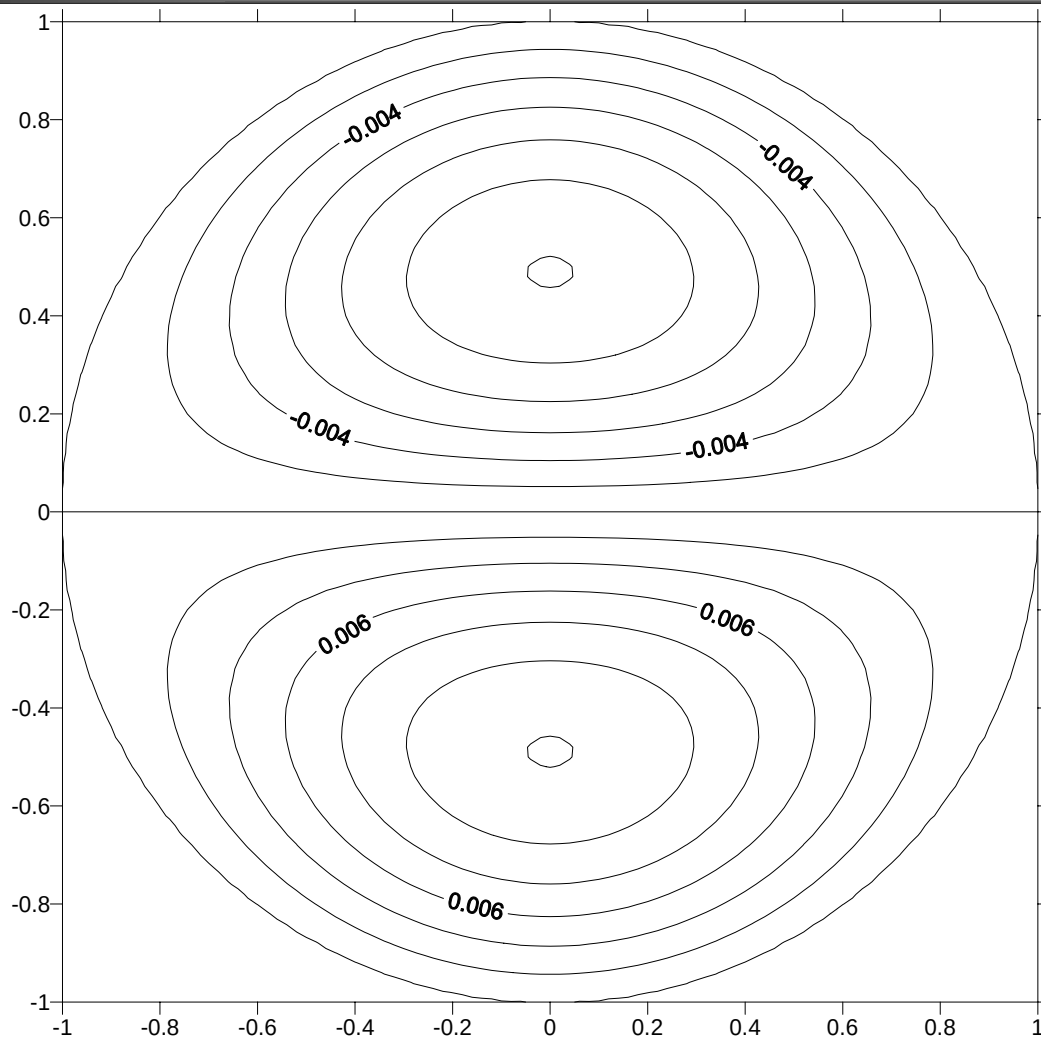


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Mode 3 ($\lambda = 3.728$)

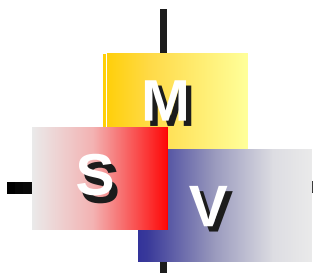


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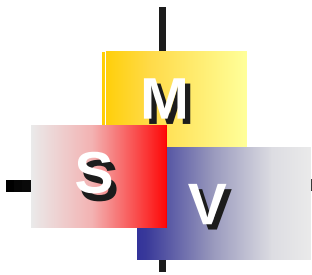
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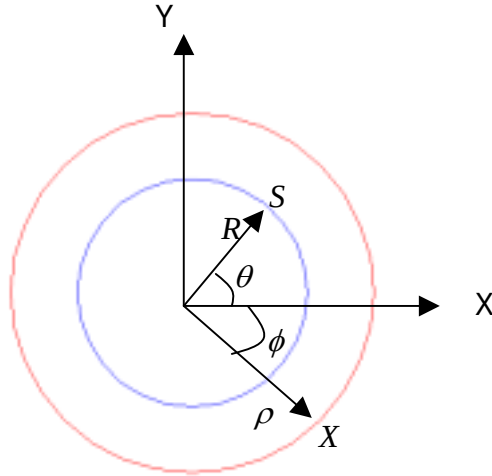
Outlines

1. Introduction
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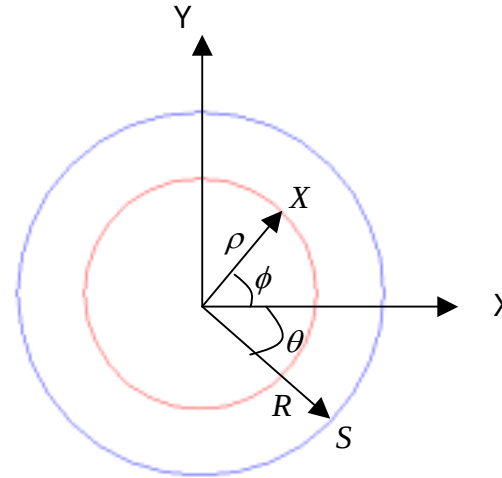


Degenerate kernels for circular case

The degenerate kernels for interior and exterior problems:



Exterior problem



Interior problem

Blue: field points
Red: source points

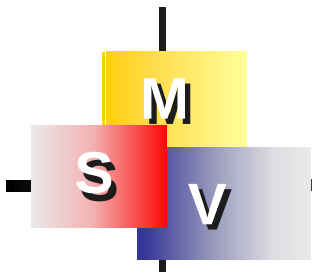
$$U(s, x) = \begin{cases} U^I(R, \theta; \rho, \phi) = \frac{1}{8\lambda^2} \sum_{m=-\infty}^{\infty} [J_m(\lambda R)J_m(\lambda \rho) + (-1)^m I_m(\lambda R)I_m(\lambda \rho)](\cos(m(\theta - \phi))), & R > \rho \\ U^E(R, \theta; \rho, \phi) = \frac{1}{8\lambda^2} \sum_{m=-\infty}^{\infty} [J_m(\lambda \rho)J_m(\lambda R) + (-1)^m I_m(\lambda \rho)I_m(\lambda R)](\cos(m(\theta - \phi))), & R < \rho \end{cases}$$

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Circulants

$$[K] = \begin{bmatrix} a_0 & a_1 & a_2 & \cdots & a_{2N-2} & a_{2N-1} \\ a_{2N-1} & a_0 & a_1 & \cdots & a_{2N-3} & a_{2N-2} \\ a_{2N-2} & a_{2N-1} & a_0 & \cdots & a_{2N-4} & a_{2N-3} \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ a_2 & a_3 & a_4 & \cdots & a_0 & a_1 \\ a_1 & a_2 & a_3 & \cdots & a_{2N-1} & a_0 \end{bmatrix}$$

$$a_{j-i} = K(s_j, x_i)$$

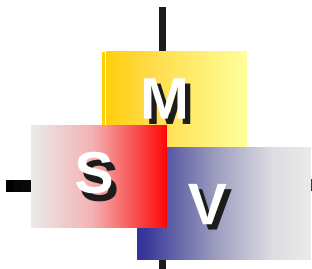
$$[K] = a_0 I + a_1 (C_{2N})^1 + a_2 (C_{2N})^2 + \cdots + a_{2N-1} (C_{2N})^{2N-1}$$

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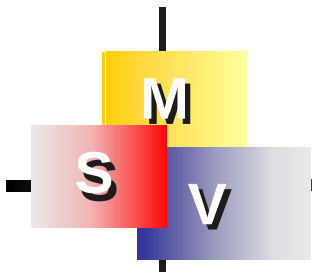


Circulants

$$C_{2N} = \begin{bmatrix} 0 & 1 & 0 & \cdots & 0 & 0 \\ 0 & 0 & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 0 & 1 \\ 1 & 0 & 0 & \cdots & 0 & 0 \end{bmatrix}_{2N \times 2N}$$

$$\alpha^{2N} - 1 = 0$$

$$\alpha_\ell = e^{i\frac{2\pi\ell}{2N}} = \cos\left(\frac{2\pi\ell}{2N}\right) + i \sin\left(\frac{2\pi\ell}{2N}\right)$$

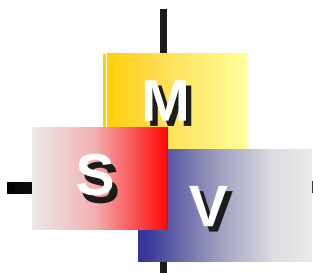


Circulants

$$\lambda_\ell^{[U]} = a_0 + a_1 \alpha_\ell + a_2 \alpha_\ell^2 + \cdots + a_{2N-1} \alpha_\ell^{2N-1}$$

$$\ell = 0, \pm 1, \pm 2, \cdots, \pm (N-1), N$$

$$\lambda_\ell^{[U]} = \frac{N}{4\lambda^2} [J_\ell(\lambda\rho)J_\ell(\lambda\rho) + (-1)^\ell I_\ell(\lambda\rho)I_\ell(\lambda\rho)]$$



The eigenvalues of matrices

$$[U] = \Phi \Sigma_U \Phi^T$$

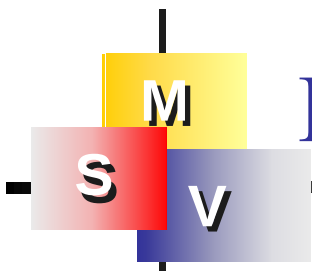
$$= \Phi \begin{bmatrix} \lambda_0^{[U]} & 0 & 0 & \cdots & 0 & 0 & 0 \\ 0 & \lambda_1^{[U]} & 0 & \cdots & 0 & 0 & 0 \\ 0 & 0 & \lambda_{-1}^{[U]} & \cdots & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & \lambda_{(N-1)}^{[U]} & 0 & 0 \\ 0 & 0 & 0 & \cdots & 0 & \lambda_{-(N-1)}^{[U]} & 0 \\ 0 & 0 & 0 & \cdots & 0 & 0 & \lambda_N^{[U]} \end{bmatrix}_{2N \times 2N} \Phi^T$$

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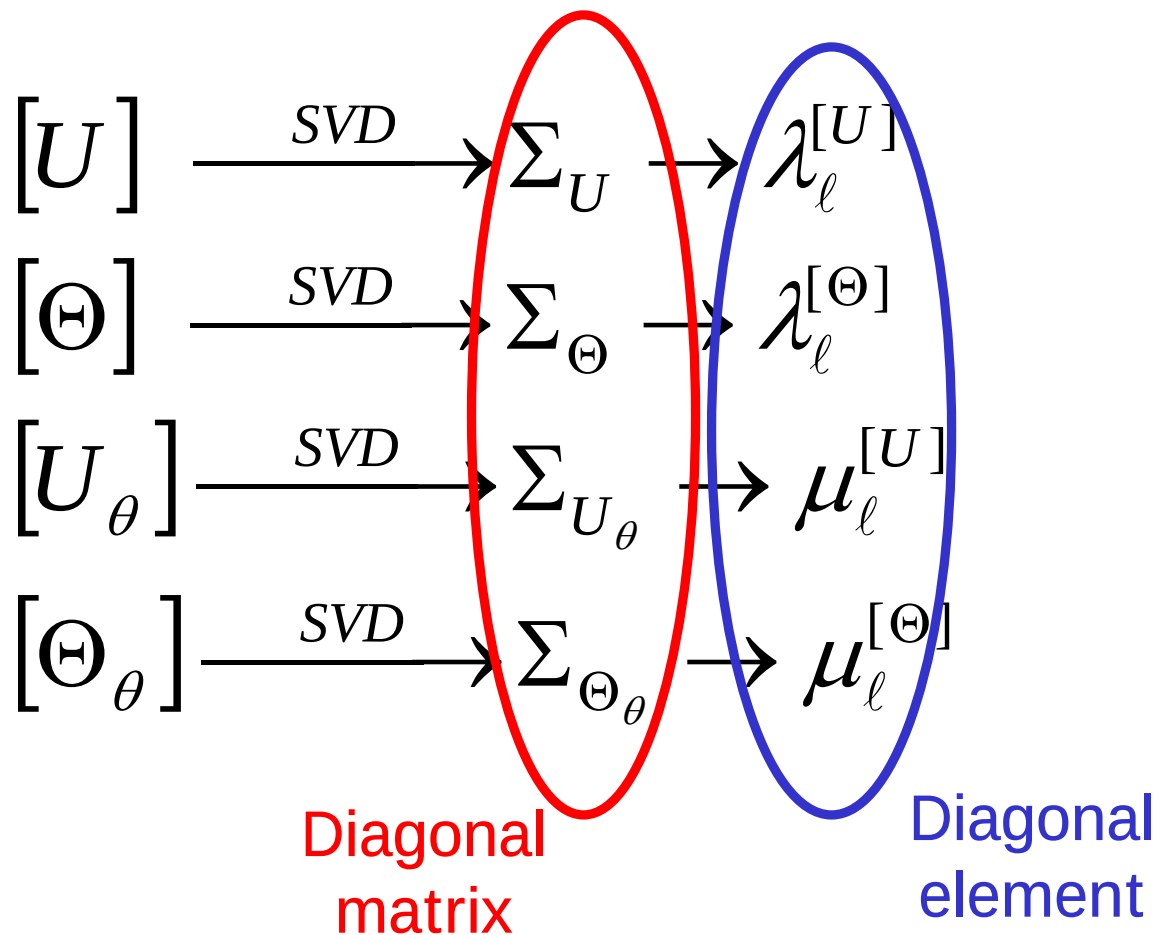


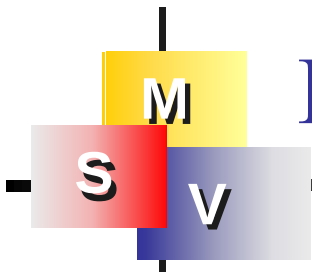
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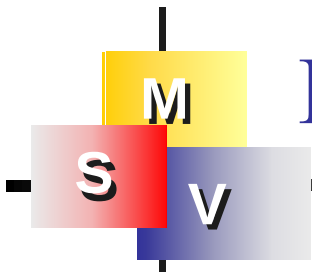
Relationships





Determinant (for clamped)

$$\begin{aligned} [SM^C] &= \begin{bmatrix} \Phi \Sigma_U \Phi^T & \Phi \Sigma_{\Theta} \Phi^T \\ \Phi \Sigma_{U_{\theta}} \Phi^T & \Phi \Sigma_{\Theta_{\theta}} \Phi^T \end{bmatrix}_{2N \times 2N} \\ &= \begin{bmatrix} \Phi & 0 \\ 0 & \Phi \end{bmatrix} \begin{bmatrix} \Sigma_U & \Sigma_{\Theta} \\ \Sigma_{U_{\theta}} & \Sigma_{\Theta_{\theta}} \end{bmatrix} \begin{bmatrix} \Phi & 0 \\ 0 & \Phi \end{bmatrix}^T \end{aligned}$$



Eigenequation for clamped boundary

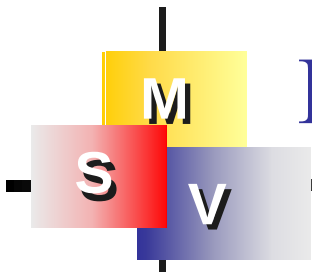
$$\det[SM^C]$$

$$= \prod_{\ell=-(N+1)}^N (\lambda_{\ell}^{[U]} \mu_{\ell}^{[\Theta]} - \lambda_{\ell}^{[\Theta]} \mu_{\ell}^{[U]})$$

$$= \prod_{\ell=-(N+1)}^N \frac{(-1)^{\ell} N^2}{16 \lambda^2} [J_{\ell+1}(\lambda \rho) I_{\ell}(\lambda \rho) + I_{\ell+1}(\lambda \rho) J_{\ell}(\lambda \rho)]$$

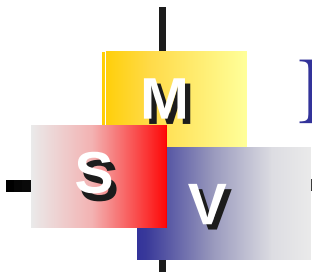
$$\{J_{\ell+1}(\lambda \rho) I_{\ell}(\lambda \rho) + I_{\ell+1}(\lambda \rho) J_{\ell}(\lambda \rho)\} = 0,$$

$$\ell = 0, \pm 1, \pm 2, \dots, \pm (N-1), N$$



Determinant (for simply-supported)

$$\begin{aligned} [SM^S] &= \begin{bmatrix} \Phi \Sigma_U \Phi^T & \Phi \Sigma_{\Theta} \Phi^T \\ \Phi \Sigma_{U_m} \Phi^T & \Phi \Sigma_{\Theta_m} \Phi^T \end{bmatrix} \\ &= \begin{bmatrix} \Phi & 0 \\ 0 & \Phi \end{bmatrix} \begin{bmatrix} \Sigma_U & \Sigma_{\Theta} \\ \Sigma_{U_m} & \Sigma_{\Theta_m} \end{bmatrix} \begin{bmatrix} \Phi & 0 \\ 0 & \Phi \end{bmatrix}^T \end{aligned}$$



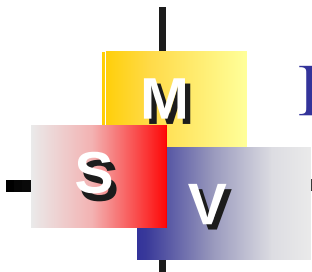
Relationships

$$[U] \xrightarrow{SVD} \Sigma_U \rightarrow \lambda_\ell^{[U]}$$

$$[\Theta] \xrightarrow{SVD} \Sigma_\Theta \rightarrow \lambda_\ell^{[\Theta]}$$

$$[U_m] \xrightarrow{SVD} \Sigma_{U_m} \rightarrow \nu_\ell^{[U]}$$

$$[\Theta_m] \xrightarrow{SVD} \Sigma_{\Theta_m} \rightarrow \nu_\ell^{[\Theta]}$$



Eigenequation for simply-supported boundary

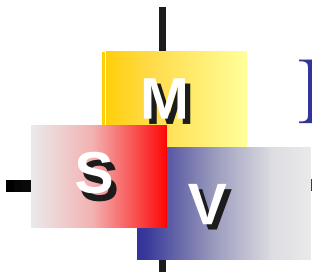
$$\det[SM^S]$$

$$= \prod_{\ell=-(N+1)}^N (\lambda_\ell^{[U]} \nu_\ell^{[\Theta]} - \lambda_\ell^{[\Theta]} \nu_\ell^{[U]})$$

$$= \prod_{\ell=-(N+1)}^N \frac{(-1)^\ell N^2}{16\lambda^2 \rho} [J_\ell(\lambda\rho) I_{\ell+1}(\lambda\rho) + I_\ell(\lambda\rho) J_{\ell+1}(\lambda\rho)]$$

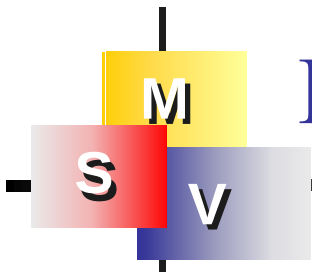
$$\{(-1+\nu)(J_{\ell+1}(\lambda\rho) I_\ell(\lambda\rho) + J_\ell(\lambda\rho) I_{\ell+1}(\lambda\rho)) + 2\lambda\rho J_\ell(\lambda\rho) I_\ell(\lambda\rho)\} = 0$$

$$\ell = 0, \pm 1, \pm 2, \dots, \pm(N-1), N$$



Determinant (for simply-supported)

$$\begin{aligned} [SM^F] &= \begin{bmatrix} \Phi \Sigma_{U_m} \Phi^T & \Phi \Sigma_{\Theta_m} \Phi^T \\ \Phi \Sigma_{U_v} \Phi^T & \Phi \Sigma_{\Theta_v} \Phi^T \end{bmatrix} \\ &= \begin{bmatrix} \Phi & 0 \\ 0 & \Phi \end{bmatrix} \begin{bmatrix} \Sigma_{U_m} & \Sigma_{U_m} \\ \Sigma_{U_v} & \Sigma_{\Theta_v} \end{bmatrix} \begin{bmatrix} \Phi & 0 \\ 0 & \Phi \end{bmatrix}^T \end{aligned}$$



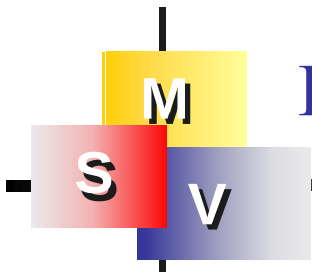
Relationships

$$[U_m] \xrightarrow{SVD} \Sigma_{U_m} \rightarrow \nu_\ell^{[U]}$$

$$[\Theta_m] \xrightarrow{SVD} \Sigma_{\Theta_m} \rightarrow \nu_\ell^{[\Theta]}$$

$$[U_v] \xrightarrow{SVD} \Sigma_{U_v} \rightarrow \delta_\ell^{[U]}$$

$$[\Theta_v] \xrightarrow{SVD} \Sigma_{\Theta_v} \rightarrow \delta_\ell^{[\Theta]}$$



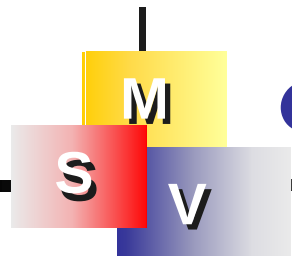
Eigenequation for free boundary

$$\det[SM^F]$$

$$= \prod_{\ell=-(N+1)}^N (\nu_\ell^{[U]} \delta_\ell^{[\Theta]} - \nu_\ell^{[\Theta]} \delta_\ell^{[U]})$$

$$= \prod_{\ell=-(N+1)}^N \frac{(-1)^\ell N^2}{16\lambda^2 \rho^4} [J_{\ell+1}(\lambda\rho)I_\ell(\lambda\rho) + J_\ell(\lambda\rho)I_{\ell+1}(\lambda\rho)]$$

$$\begin{aligned} & \{\ell^2(\ell^2-1)(-1+\nu)^2 + \lambda^4 \rho^4\} (J_{\ell+1}(\lambda\rho)I_\ell(\lambda\rho) + J_\ell(\lambda\rho)I_{\ell+1}(\lambda\rho)) \\ & + 2\ell\lambda^2 \rho^2 (1-\ell)(-1+\nu) (J_{\ell+1}(\lambda\rho)I_\ell(\lambda\rho) - J_\ell(\lambda\rho)I_{\ell+1}(\lambda\rho)) \\ & + \lambda\rho(-1+\nu) (2\lambda^2 \rho^2 J_{\ell+1}(\lambda\rho)I_{\ell+1}(\lambda\rho) + 4\ell^2(-1+\ell)J_\ell(\lambda\rho)I_\ell(\lambda\rho)) = 0, \\ & \ell = 0, \pm 1, \pm 2, \dots, \pm(N-1), N \end{aligned}$$



Comparisons of the NDIF and present method

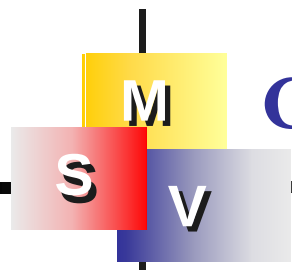
	Kang	Present method
Base	$U(s, x) = J_0(\lambda r)$ $\Theta(s, x) = I_0(\lambda r)$	$U(s, x) = \frac{1}{8\lambda^2}(J_0(\lambda r) + I_0(\lambda r))$ $\Theta(s, x) = \frac{\partial U(s, x)}{\partial n_s}$
Clamped plate	$J_\ell(\lambda r)I_{\ell+1}(\lambda r) + J_{\ell+1}(\lambda r)I_\ell(\lambda r) = 0$	$J_\ell(\lambda r)I_{\ell+1}(\lambda r) + J_{\ell+1}(\lambda r)I_\ell(\lambda r) = 0$
	$J_\ell(\lambda r) = 0$	$J_\ell(\lambda r)I_{\ell+1}(\lambda r) + J_{\ell+1}(\lambda r)I_\ell(\lambda r) = 0$
Simply-supported plate	$\frac{I_{\ell+1}(\lambda r)}{I_\ell(\lambda r)} + \frac{J_{\ell+1}(\lambda r)}{J_\ell(\lambda r)} = \frac{2\lambda r}{(1-\nu)}$	$\frac{I_{\ell+1}(\lambda r)}{I_\ell(\lambda r)} + \frac{J_{\ell+1}(\lambda r)}{J_\ell(\lambda r)} = \frac{2\lambda r}{(1-\nu)}$
	$J_\ell(\lambda r) = 0$	$J_\ell(\lambda r)I_{\ell+1}(\lambda r) + J_{\ell+1}(\lambda r)I_\ell(\lambda r) = 0$
Treatment	Net approach	Dual formulation with SVD updating

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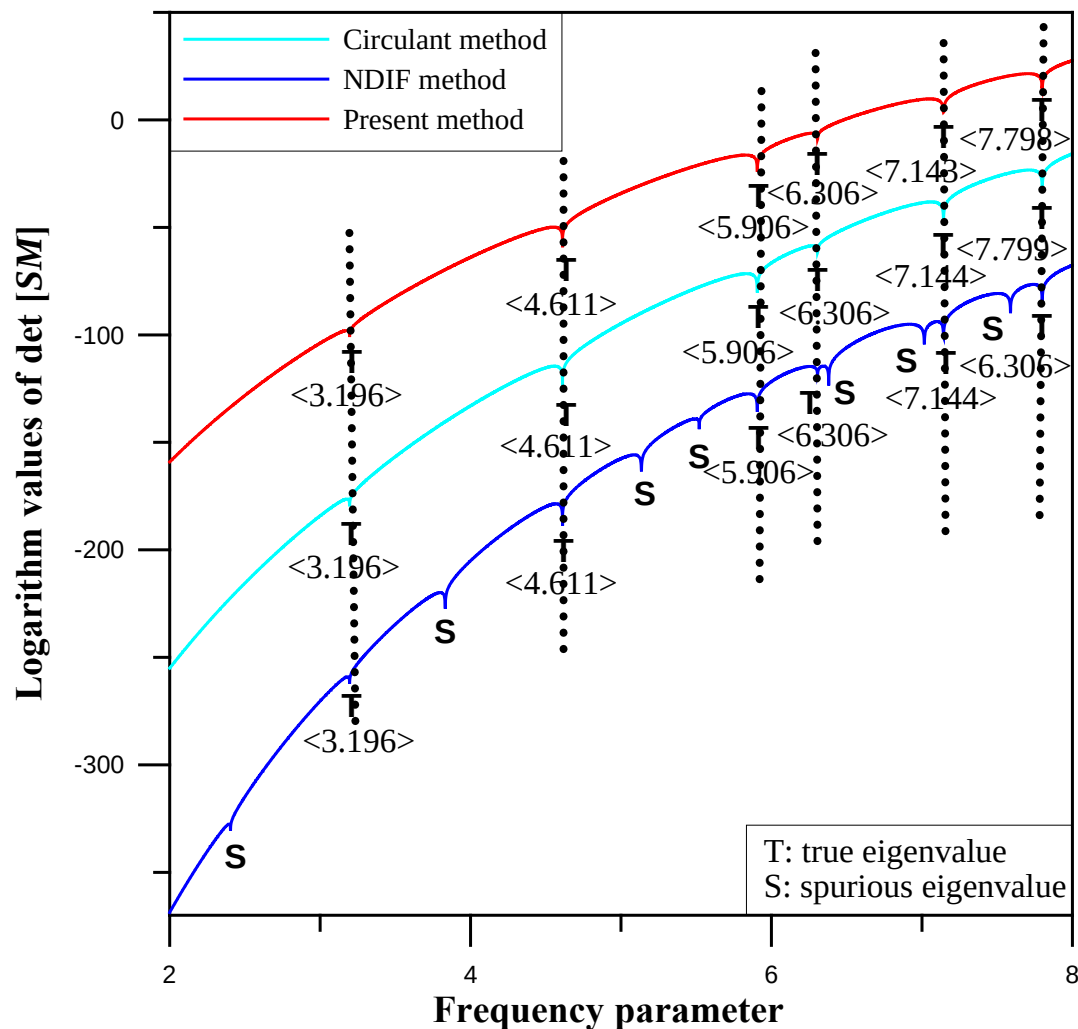


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Circular clamped plate using different methods

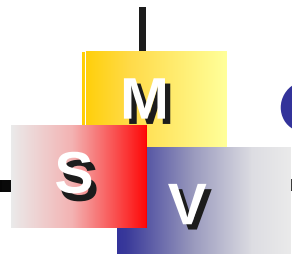


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Comparisons of Leissa and present method

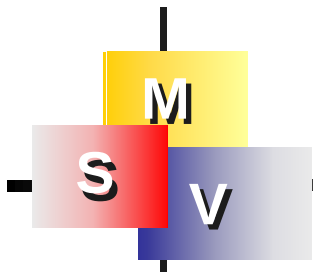
	Leissa (Kitahara)	Present method
Clamped plate	$J_\ell(\lambda r)I_{\ell+1}(\lambda r) + J_{\ell+1}(\lambda r)I_\ell(\lambda r) = 0$	$J_\ell(\lambda r)I_{\ell+1}(\lambda r) + J_{\ell+1}(\lambda r)I_\ell(\lambda r) = 0$
Simply-supported plate	$\frac{I_{\ell+1}(\lambda r)}{I_\ell(\lambda r)} + \frac{J_{\ell+1}(\lambda r)}{J_\ell(\lambda r)} = \frac{2\lambda r}{(1-\nu)}$	$\frac{I_{\ell+1}(\lambda r)}{I_\ell(\lambda r)} + \frac{J_{\ell+1}(\lambda r)}{J_\ell(\lambda r)} = \frac{2\lambda r}{(1-\nu)}$
Free plate J ←	$\frac{\lambda^2 J_\ell(\lambda \rho) + (1-\nu)[\lambda J'_\ell(\lambda \rho) - \ell^2 J_\ell(\lambda \rho)]}{\lambda^2 I_\ell(\lambda \rho) - (1-\nu)[\lambda I'_\ell(\lambda \rho) - \ell^2 I_\ell(\lambda \rho)]}$ $= \frac{\lambda^3 I'_\ell(\lambda \rho) + (1-\nu)\ell^2[\lambda J'_\ell(\lambda \rho) - J_\ell(\lambda \rho)]}{\lambda^3 I'_\ell(\lambda \rho) - (1-\nu)\ell^2[\lambda I'_\ell(\lambda \rho) - I_\ell(\lambda \rho)]}$	$\{\ell^2(\ell^2-1)(-1+\nu)^2 + \lambda^4 \rho^4\}(J_{\ell+1}(\lambda \rho)I_\ell(\lambda \rho) + J_\ell(\lambda \rho)I_{\ell+1}(\lambda \rho)) + 2\ell\lambda^2 \rho^2(1-\ell)(-1+\nu)$ $(J_{\ell+1}(\lambda \rho)I_\ell(\lambda \rho) - J_\ell(\lambda \rho)I_{\ell+1}(\lambda \rho)) + \lambda \rho(-1+\nu)$ $(2\lambda^2 \rho^2 J_{\ell+1}(\lambda \rho)I_{\ell+1}(\lambda \rho) + 4\ell^2(-1+\ell)J_\ell(\lambda \rho)I_\ell(\lambda \rho)) = 0$

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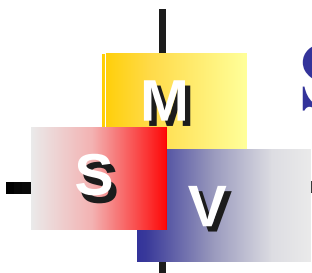
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Outlines

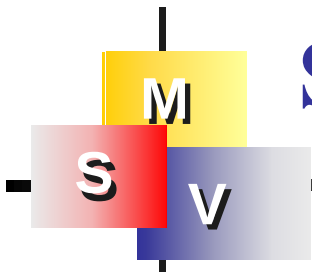
1. Introduction
2. Plate vibration
3. Derivation by Circulants
4. **SVD updating terms**
5. Conclusions



SVD updating terms (clamped case)

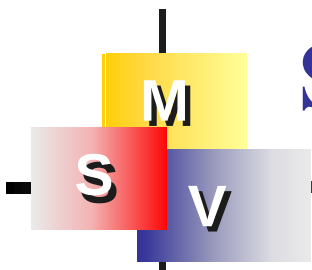
$$\begin{bmatrix} SM^C \end{bmatrix} \begin{Bmatrix} \phi \\ \psi \end{Bmatrix} = \begin{bmatrix} U & \Theta \\ U_\theta & \Theta_\theta \end{bmatrix} \begin{Bmatrix} \phi \\ \psi \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$

$$\begin{bmatrix} SM_1^C \end{bmatrix} \begin{Bmatrix} \phi' \\ \psi' \end{Bmatrix} = \begin{bmatrix} M & V \\ M_\theta & V_\theta \end{bmatrix} \begin{Bmatrix} \phi' \\ \psi' \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$



SVD updating terms (clamped case)

$$\begin{aligned}
 [C] &= \begin{bmatrix} (SM^C)^T \\ (SM_1^C)^T \end{bmatrix} \\
 &= \begin{bmatrix} \Phi & 0 & 0 & 0 \\ 0 & \Phi & 0 & 0 \\ 0 & 0 & \Phi & 0 \\ 0 & 0 & 0 & \Phi \end{bmatrix} \begin{bmatrix} \Sigma_U & \Sigma_{U_\theta} \\ \Sigma_\Theta & \Sigma_{\Theta_\theta} \\ \Sigma_M & \Sigma_{M_\theta} \\ \Sigma_V & \Sigma_{V_\theta} \end{bmatrix}_{8N \times 4N} \begin{bmatrix} \Phi^{-1} & 0 \\ 0 & \Phi^{-1} \end{bmatrix}
 \end{aligned}$$



SVD updating terms (clamped case)

Based on the least squares

$$[C]^T [C] = \begin{bmatrix} \Phi & 0 \\ 0 & \Phi \end{bmatrix} [D]_{4N \times 4N} \begin{bmatrix} \Phi^{-1} & 0 \\ 0 & \Phi^{-1} \end{bmatrix}$$

$$\det[[C]^T [C]] = \det[D]$$

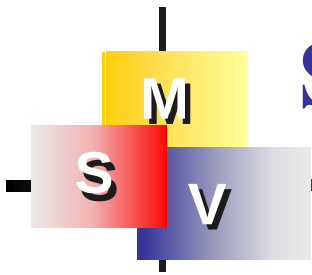
$$\begin{aligned} &= \prod_{\ell=-(N-1)}^N [(\lambda_{\ell}^{[U]} \mu_{\ell}^{[\Theta]} - \mu_{\ell}^{[U]} \lambda_{\ell}^{[\Theta]})^2 + (\lambda_{\ell}^{[U]} \mu_{\ell}^{[M]} - \mu_{\ell}^{[U]} \lambda_{\ell}^{[M]})^2 \\ &\quad + (\lambda_{\ell}^{[U]} \mu_{\ell}^{[V]} - \mu_{\ell}^{[U]} \lambda_{\ell}^{[V]})^2 + (\lambda_{\ell}^{[\Theta]} \mu_{\ell}^{[M]} - \mu_{\ell}^{[\Theta]} \lambda_{\ell}^{[M]})^2 \\ &\quad + (\lambda_{\ell}^{[\Theta]} \mu_{\ell}^{[V]} - \mu_{\ell}^{[\Theta]} \lambda_{\ell}^{[V]})^2 + (\lambda_{\ell}^{[M]} \mu_{\ell}^{[V]} - \mu_{\ell}^{[M]} \lambda_{\ell}^{[V]})^2] \end{aligned}$$

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SVD updating terms (clamped case)

The only possibility for zero determinant of $[D]$ 

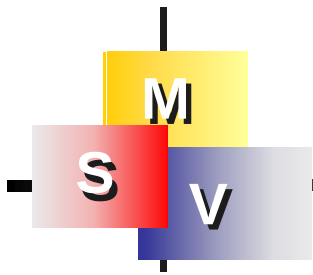
$$\begin{aligned}(\lambda_\ell^{[U]} \mu_\ell^{[\Theta]} - \mu_\ell^{[U]} \lambda_\ell^{[\Theta]}) &= 0, & (\lambda_\ell^{[U]} \mu_\ell^{[M]} - \mu_\ell^{[U]} \lambda_\ell^{[M]}) &= 0, \\(\lambda_\ell^{[U]} \mu_\ell^{[V]} - \mu_\ell^{[U]} \lambda_\ell^{[V]}) &= 0, & (\lambda_\ell^{[\Theta]} \mu_\ell^{[M]} - \mu_\ell^{[\Theta]} \lambda_\ell^{[M]}) &= 0, \\(\lambda_\ell^{[\Theta]} \mu_\ell^{[V]} - \mu_\ell^{[\Theta]} \lambda_\ell^{[V]}) &= 0, & (\lambda_\ell^{[M]} \mu_\ell^{[V]} - \mu_\ell^{[M]} \lambda_\ell^{[V]}) &= 0.\end{aligned}$$

at the same time for the same ℓ .

The common term is

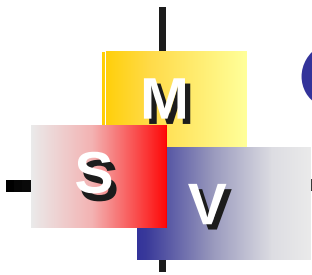
$$J_\ell(\lambda r) I_{\ell+1}(\lambda r) + J_{\ell+1}(\lambda r) I_\ell(\lambda r) = 0$$

True eigenequation



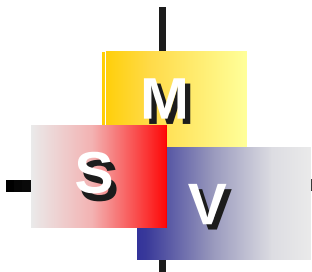
Outlines

1. Introduction
2. Plate vibration
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4. SVD updating terms
- 5. Conclusions**

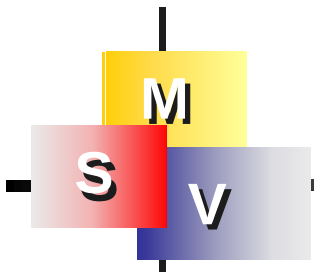


Conclusions

1. Since any two combinations of the four types of potentials, **six options**(C_2^4) were considered.
2. **Spurious eigenequation** only depends on the adopted **kernel function**, while the **true eigenequation** is relevant to the specified **boundary condition**.
3. True eigenequation can be extract out by using **SVD updating term**.



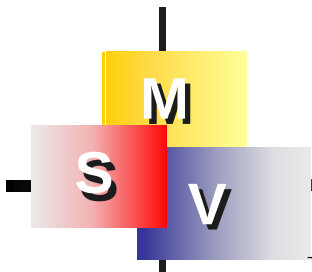
1. J. T. Chen, M. H. Chang, I. L. Chung and Y. C. Cheng, 2002, [Comments on eigenmode analysis of arbitrarily shaped two-dimensional cavities by the method of point matching](#), J. Acoust. Soc. Amer., Vol.111, No.1, pp.33-36. (SCI and EI)
2. J. T. Chen, M. H. Chang, K. H. Chen and S. R. Lin, 2002, [Boundary collocation method with meshless concept for acoustic eigenanalysis of two-dimensional cavities using radial basis function](#), Journal of Sound and Vibration, Vol.257, No.4, pp.667-711 (SCI and EI)
3. J. T. Chen, M. H. Chang, K. H. Chen, I. L. Chen, 2002, [Boundary collocation method for acoustic eigenanalysis of three-dimensional cavities using radial basis function](#), Computational Mechanics, Vol.29, pp.392-408. (SCI and EI)
4. J. T. Chen, S. R. Kuo, K. H. Chen and Y. C. Cheng, 2000, [Comments on "vibration analysis of arbitrary shaped membranes using non-dimensional dynamic influence function"](#), Journal of Sound and Vibration, Vol.235, No.1, pp.156-171. (SCI and EI)
5. J. T. Chen, I. L. Chen, K. H. Chen and Y. T. Lee, 2003, [Comments on "Free vibration analysis of arbitrarily shaped plates with clamped edges using wave-type function."](#), Journal of Sound and Vibration, Vol.262, pp.370-378. (SCI and EI)
6. J. T. Chen, I. L. Chen, K. H. Chen, Y. T. Yeh and Y. T. Lee, 2003, [A meshless method for free vibration analysis of arbitrarily shaped plates with clamped boundaries using radial basis function](#), Engineering Analysis with Boundary Elements, Accepted. (SCI and EI)



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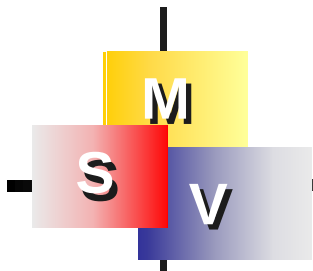
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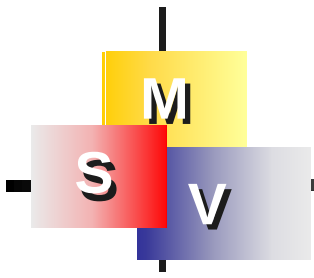
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**There is nothing more practical than
the right theory.**

**Whether the theory is right or not
depends on the experiment**

Thanks for your kind attention