

BEM H.W .007 M93520010 陳柏源

$$\nabla^2 U(x, s) = \delta(x - s)$$

ANS.

$$\begin{aligned} \nabla^2 U(x, s) &= \delta(x - s) \\ \text{右式} &\rightarrow \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} (U(r, \theta, \phi)) \\ &= \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial U}{\partial r} \right) + \frac{1}{r^2 \sin[\theta]} \frac{\partial}{\partial \theta} \left(\sin[\theta] \frac{\partial U}{\partial \theta} \right) + \frac{1}{r^2 \sin^2[\theta]} \left(\frac{\partial^2 U}{\partial \phi^2} \right) \\ \theta, \phi &\text{不影響} \\ &= \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial U}{\partial r} \right) \\ &= \frac{1}{r^2} \left(2r \frac{\partial U}{\partial r} + r^2 \frac{\partial^2 U}{\partial r^2} \right) \end{aligned}$$

令等於零 (求補解)

$$\frac{2}{r} \frac{\partial U[r]}{\partial r} + \frac{\partial^2 U[r]}{\partial r^2} = 0. \dots \dots (1)$$

$$\text{令 } r = e^t, \quad t = \text{Log}[r], \quad dt = \frac{1}{r} dr$$

$$U[r] = U[e^t] = u[t]$$

$$u' = \frac{du}{dt} \frac{dt}{dr} = u' \frac{1}{r}$$

$$u'' = \frac{1}{r^2} (u'' - u')$$

(1) 式

$$\rightarrow \frac{1}{r^2} (u'' - u') + \frac{2}{r} u' \frac{1}{r} = 0$$

$$\rightarrow u'' - u' + 2u' = 0$$

$$\rightarrow u'' + u' = 0$$

 $e^{\lambda t}$ 代入

$$\lambda = 0, -1$$

$$U(e^t) = u(t) = C_1 e^{\lambda t} + C_2 e^{\lambda t}$$

$$\rightarrow U(r) = C_1 e^{\lambda \text{Log}[r]} + C_2 e^{\lambda \text{Log}[r]}$$

$$\rightarrow U(r) = C_1 e^{0 \cdot \text{Log}[r]} + C_2 e^{-1 \cdot \text{Log}[r]}$$

$$= C_1 + C_2 * \frac{1}{r} \dots \dots (C_1 : \text{剛體運動項})$$

$$= \frac{C_2}{r} \dots \dots \dots (\text{補解})$$

$$u''[r] + \frac{2}{r} u[r] = \delta(x - s) \dots \dots (\text{特解})$$

$$\iiint \nabla^2 U(x, s) dV = \iiint \delta(x - s) dV$$

$$\text{右式} \rightarrow \iiint \nabla^2 U(x, s) dV = \iiint \nabla \cdot (\nabla \cdot n) dV_a = \iint \frac{\partial U}{\partial n} dA_a$$

$$\int_0^{2\pi} \int_0^\pi \frac{\partial U}{\partial r} d\theta d\phi = \int_0^{2\pi} \int_0^\pi \frac{-C_2}{r^2} (r \sin[\theta]) r d\theta d\phi$$

$$= -C_2 \int_0^{2\pi} \int_0^\pi \sin[\theta] d\theta d\phi$$

$$= -C_2 \int_0^{2\pi} -\cos[\theta] \Big|_0^\pi d\phi$$

$$= -C_2 \left(2\phi \mid \begin{matrix} 2\pi \\ 0 \end{matrix} \right)$$

$$= -4\pi * C_2$$

$$\text{左式} \rightarrow \iiint \delta(\mathbf{x} - \mathbf{s}) \, d\mathbf{V} = 1$$

$$-4\pi * C_2 = 1$$

$$C_2 = -\frac{1}{4\pi}$$

$$\mathbf{U} = -\frac{1}{4\pi} \frac{1}{r} \quad \ominus$$