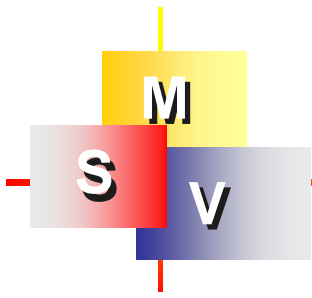


Free vibration analysis of multiply-connected plates using the method of fundamental solutions

Ying-Te Lee, I-Lin Chen and Jeng-Tzong Chen

ICCM 2004 Conference, Singapore

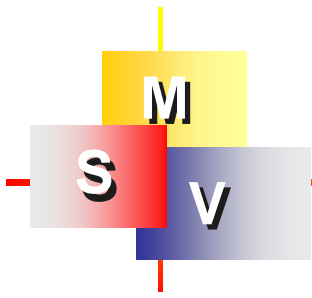
December, 15-17, 2004



Outlines

1. Introduction
2. Methods of solution
3. Mathematical analysis
4. Treatment methods
5. Numerical example
6. Conclusions

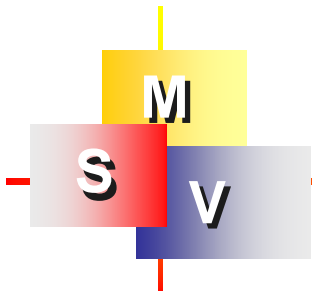




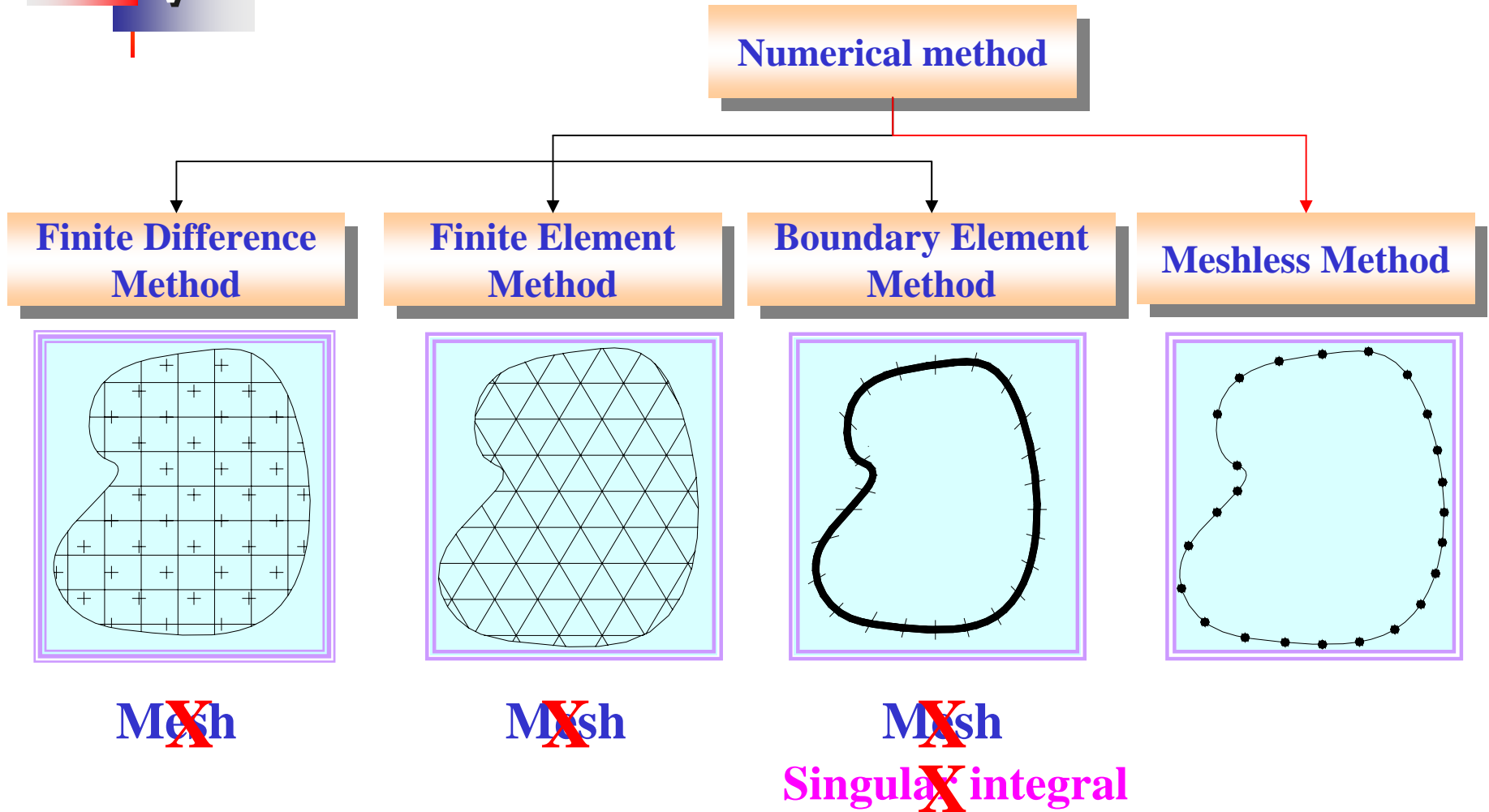
Outlines

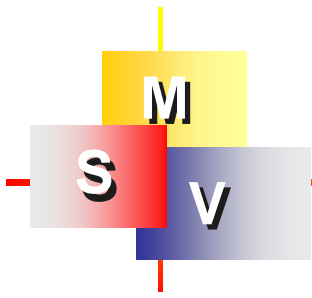
- 1. Introduction**
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Numerical method

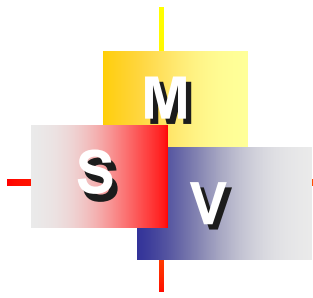




Outlines

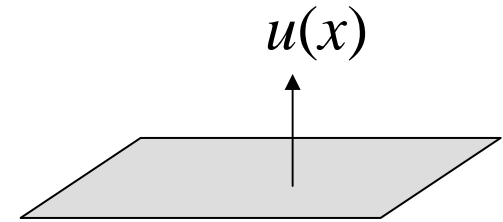
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Vibration of plates

Governing Equation:



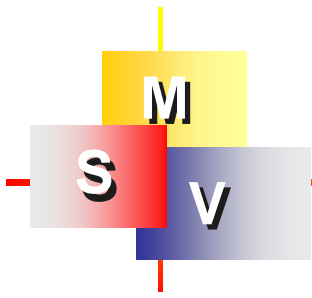
$$\nabla^4 u(x) = \lambda^4 u(x), x \in \Omega$$

$$\lambda^4 = \frac{\omega^2 \rho h}{D}$$

$$D = \frac{E h^3}{12 (1 - \nu)}$$

ω is the angle frequency
 ρ is the surface density
 h is the plates thickness
 D is the flexural rigidity
 E is the Young's modulus
 ν is the Poisson's ratio





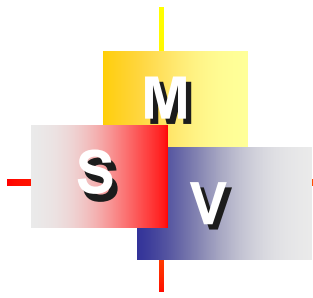
Fundamental solution

The fundamental solution satisfies

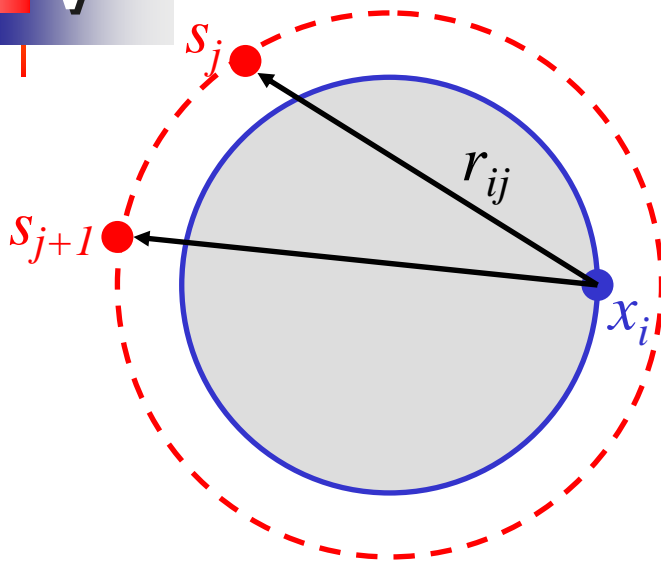
$$\nabla^4 U(s, x) - \lambda^4 U(s, x) = -\delta(x - s)$$

$$U(s, x) = \frac{1}{8\lambda^2} [Y_0(\lambda r) - iJ_0(\lambda r) + \frac{2}{\pi} (K_0(\lambda r) - iI_0(\lambda r))]$$

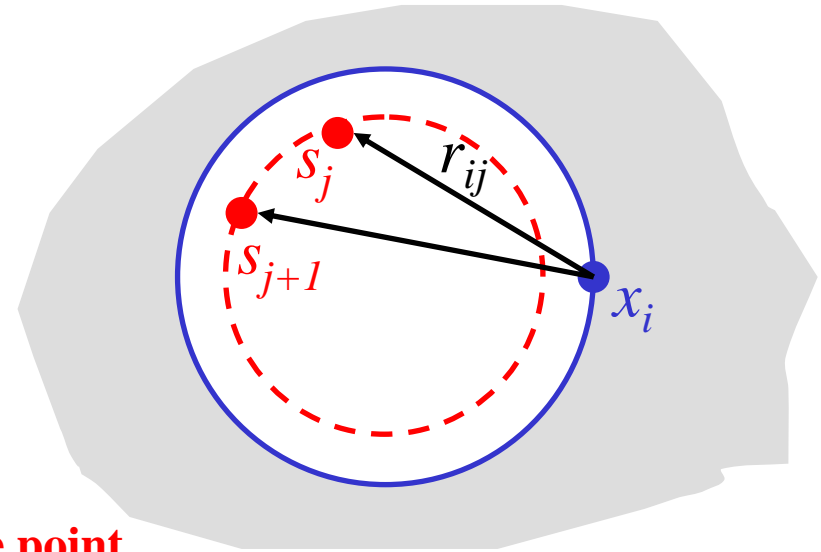




Field representation using MFS



Interior problem



Exterior problem

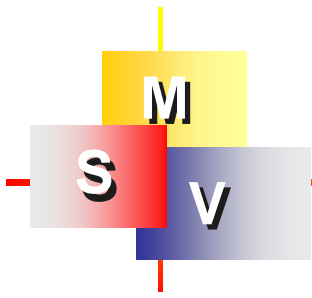
● Source point

Field representation

$$u(x_i) = \sum_j c_j \psi(s_j, x_i)$$

$$\psi(s_j, x_i) = \psi(r_{ij}), \quad r_{ij} \equiv |s_j - x_i|$$





The other three kernels

Displacement to slope operator

$$\Theta(s, x) = \mathfrak{S}_{\theta}(U(s, x))$$

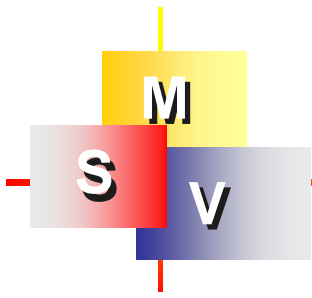
Displacement to normal moment operator

$$M(s, x) = \mathfrak{S}_m(U(s, x))$$

Displacement to effective shear operator

$$V(s, x) = \mathfrak{S}_v(U(s, x))$$





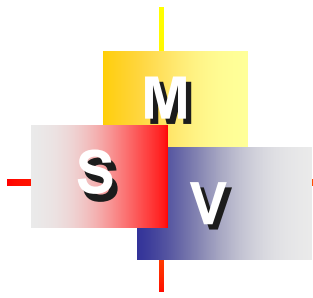
Explicit forms for operators

$$\mathfrak{N}_\theta(\cdot) = \frac{\partial(\cdot)}{\partial n}$$

$$\mathfrak{N}_m(\cdot) = \nu \nabla^2(\cdot) + (1 - \nu) \frac{\partial^2(\cdot)}{\partial n^2}$$

$$\mathfrak{N}_v(\cdot) = \frac{\partial \nabla^2(\cdot)}{\partial n} + (1 - \nu) \frac{\partial}{\partial t} \left(\frac{\partial^2(\cdot)}{\partial n \partial t} \right)$$





Displacement, Slope, Moment and Shear

Displacement

$$u(x) = \sum_{j=1}^{2N} P(s_j, x) p(s_j) + \sum_{j=1}^{2N} Q(s_j, x) q(s_j)$$

Slope

$$\theta(x) = \sum_{j=1}^{2N} P_{\theta}(s_j, x) p(s_j) + \sum_{j=1}^{2N} Q_{\theta}(s_j, x) q(s_j)$$

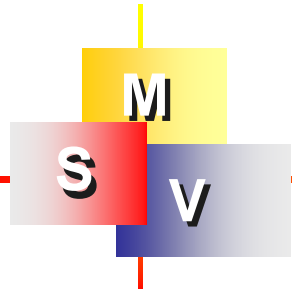
Normal moment

$$m(x) = \sum_{j=1}^{2N} P_m(s_j, x) p(s_j) + \sum_{j=1}^{2N} Q_m(s_j, x) q(s_j)$$

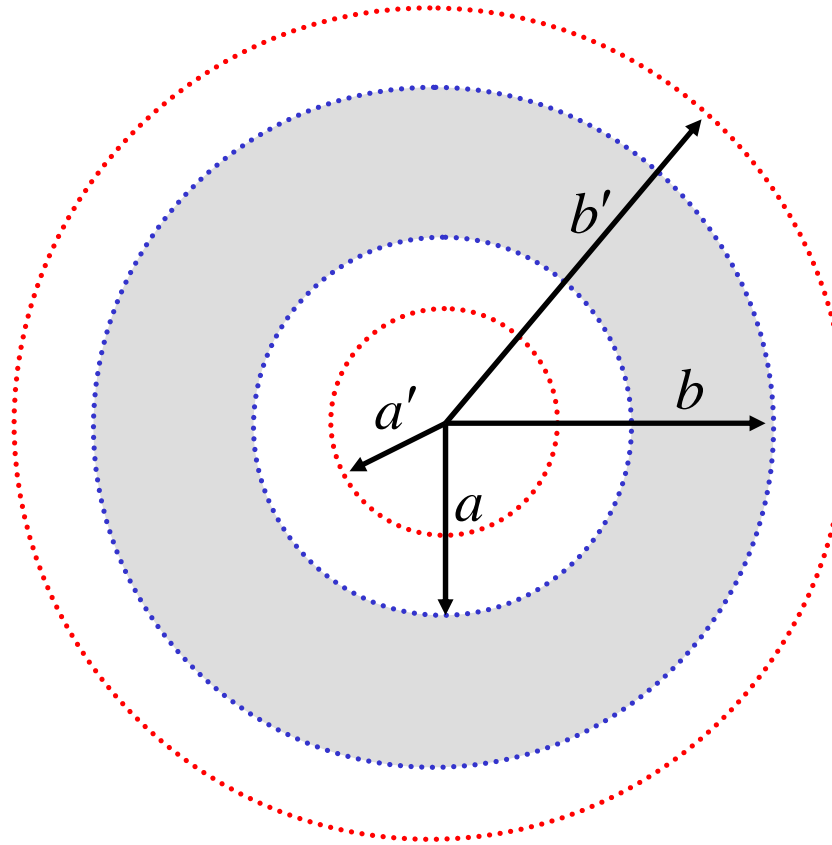
Effective shear

$$v(x) = \sum_{j=1}^{2N} P_v(s_j, x) p(s_j) + \sum_{j=1}^{2N} Q_v(s_j, x) q(s_j)$$





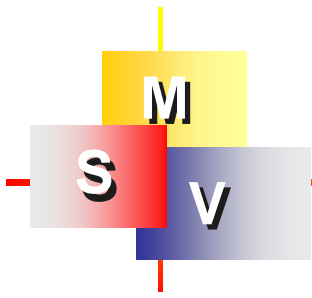
Problem statement



..... Collocation point distribution (real boundary)

..... Source point distribution (fictitious boundary)





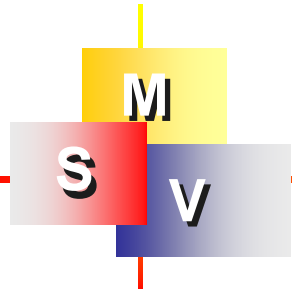
Matching boundary condition

The **clamped-clamped case** is considered

$$\begin{Bmatrix} 0 \\ 0 \end{Bmatrix} = \begin{bmatrix} U_{11} & U_{12} \\ U_{21} & U_{22} \end{bmatrix} \begin{Bmatrix} \phi_1 \\ \phi_2 \end{Bmatrix} + \begin{bmatrix} \Theta_{11} & \Theta_{12} \\ \Theta_{21} & \Theta_{22} \end{bmatrix} \begin{Bmatrix} \varphi_1 \\ \varphi_2 \end{Bmatrix}$$

$$\begin{Bmatrix} 0 \\ 0 \end{Bmatrix} = \begin{bmatrix} U_{11}_\theta & U_{12}_\theta \\ U_{21}_\theta & U_{22}_\theta \end{bmatrix} \begin{Bmatrix} \phi_1 \\ \phi_2 \end{Bmatrix} + \begin{bmatrix} \Theta_{11}_\theta & \Theta_{12}_\theta \\ \Theta_{21}_\theta & \Theta_{22}_\theta \end{bmatrix} \begin{Bmatrix} \varphi_1 \\ \varphi_2 \end{Bmatrix}$$





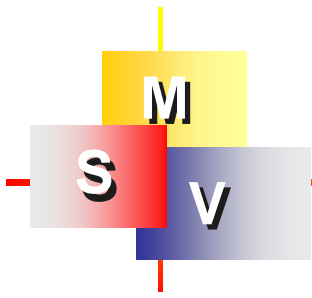
Matrix assembling

$$\begin{bmatrix} U11 & U12 & \Theta11 & \Theta12 \\ U21 & U22 & \Theta21 & \Theta22 \\ U11_{\theta} & U12_{\theta} & \Theta11_{\theta} & \Theta12_{\theta} \\ U21_{\theta} & U22_{\theta} & \Theta21_{\theta} & \Theta22_{\theta} \end{bmatrix} \begin{Bmatrix} \phi1 \\ \phi2 \\ \varphi1 \\ \varphi2 \end{Bmatrix} = \{0\}$$

$\det[SM^{cc}] = 0$

Nontrivial

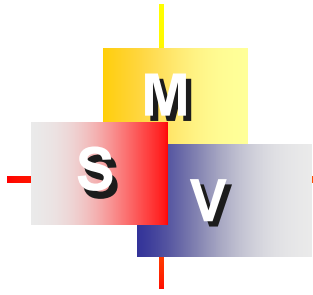




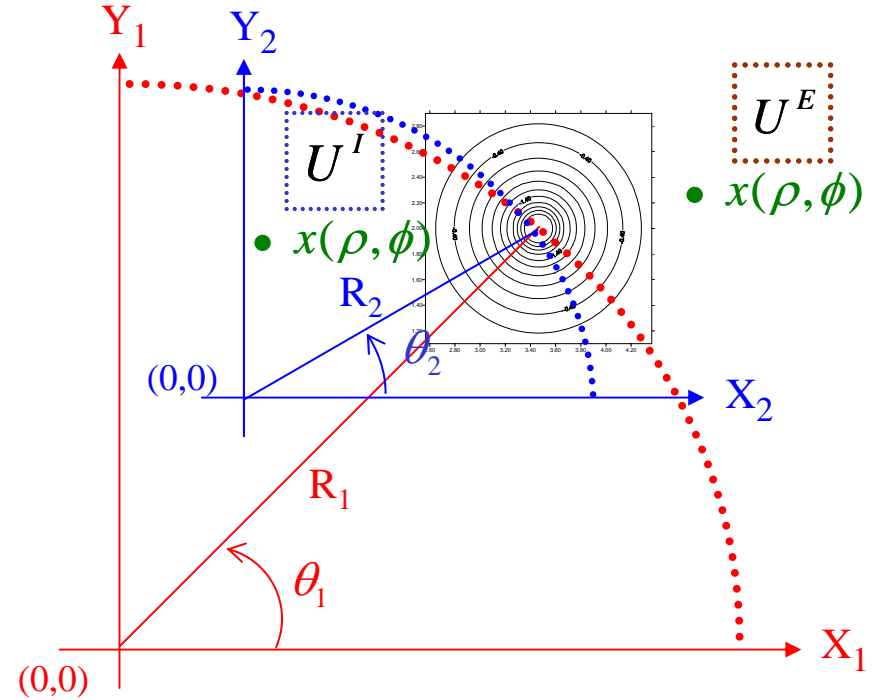
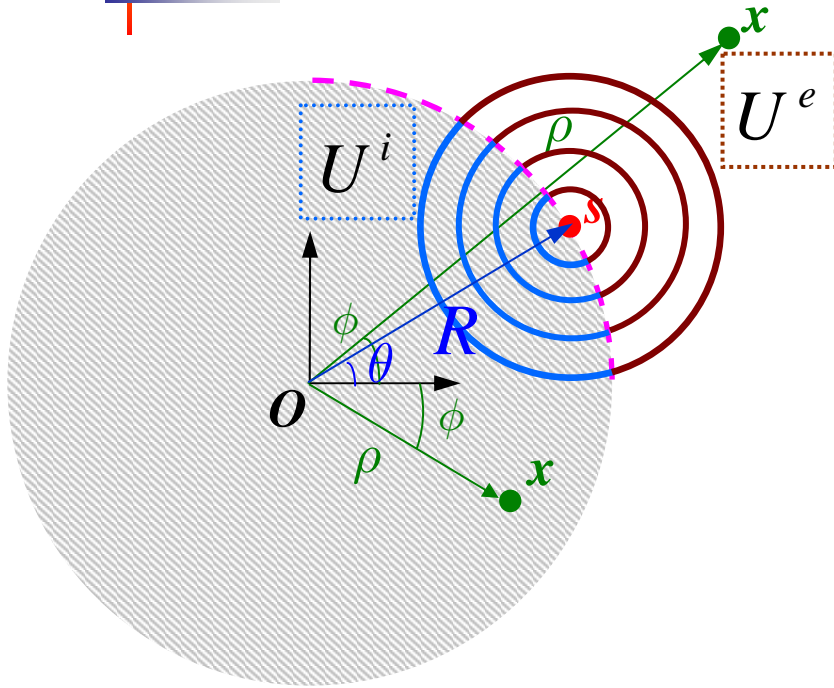
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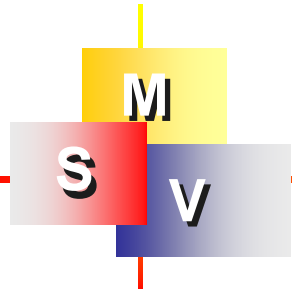
Degenerate kernels for circular case



$$U^I(R, \theta; \rho, \phi) = \sum_{m=-\infty}^{\infty} \frac{1}{8\lambda^2} \{ J_m(\lambda\rho)[Y_m(\lambda R) - iJ_m(\lambda R)] + \frac{2}{\pi} (-1)^m I_m(\lambda\rho)[(-1)^m K_m(\lambda R) - iI_m(\lambda R)] \} \cos(m(\theta - \phi)), \quad R > \rho,$$

$$U^E(R, \theta; \rho, \phi) = \sum_{m=-\infty}^{\infty} \frac{1}{8\lambda^2} \{ J_m(\lambda R)[Y_m(\lambda\rho) - iJ_m(\lambda\rho)] + \frac{2}{\pi} (-1)^m I_m(\lambda R)[(-1)^m K_m(\lambda\rho) - iI_m(\lambda\rho)] \} \cos(m(\theta - \phi)), \quad R < \rho,$$





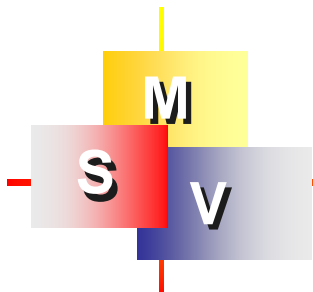
Circulants

Discretization into $2N$ nodes on the circular boundary

$$[U11] = \begin{bmatrix} a_0 & a_1 & a_2 & \cdots & a_{2N-2} & a_{2N-1} \\ a_{2N-1} & a_0 & a_1 & \cdots & a_{2N-3} & a_{2N-2} \\ a_{2N-2} & a_{2N-1} & a_0 & \cdots & a_{2N-4} & a_{2N-3} \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ a_2 & a_3 & a_4 & \cdots & a_0 & a_1 \\ a_1 & a_2 & a_3 & \cdots & a_{2N-1} & a_0 \end{bmatrix}$$

$$[U11] = a_0 I + a_1 C_{2N} + a_2 (C_{2N})^2 + \cdots + a_{2N-1} (C_{2N})^{2N-1}$$





Circulants

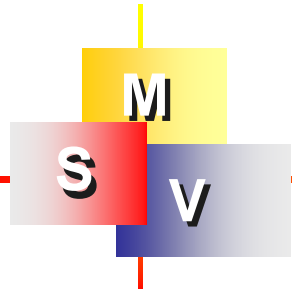
$$C_{2N} = \begin{bmatrix} 0 & 1 & 0 & \cdots & 0 & 0 \\ 0 & 0 & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 0 & 1 \\ 1 & 0 & 0 & \cdots & 0 & 0 \end{bmatrix}_{2N \times 2N}$$

$$\alpha_\ell = e^{i\frac{2\pi\ell}{2N}} = \cos\left(\frac{2\pi\ell}{2N}\right) + i \sin\left(\frac{2\pi\ell}{2N}\right) \quad : \text{eigenvalue of } C_{2N}$$

$$\lambda_\ell^{[U11]} = a_0 + a_1\alpha_\ell + a_2\alpha_\ell^2 + \cdots + a_{2N-1}\alpha_\ell^{2N-1} \quad : \text{eigenvalue of } [U11]$$

$$\ell = 0, \pm 1, \pm 2, \cdots, \pm (N-1), N$$





Eigenvalues

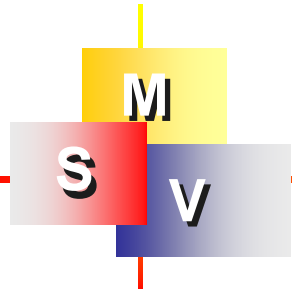
$$\lambda_m^{[U11]} = \frac{N}{4\lambda^2} \{ J_m(\lambda a') [Y_m(\lambda a) - iJ_m(\lambda a)] + \frac{2}{\pi} I_m(\lambda a') [K_m(\lambda a) - (-1)^m iI_m(\lambda a)] \}$$

$$\lambda_m^{[U12]} = \frac{N}{4\lambda^2} \{ J_m(\lambda a) [Y_m(\lambda b') - iJ_m(\lambda b')] + \frac{2}{\pi} I_m(\lambda a) [K_m(\lambda b') - (-1)^m iI_m(\lambda b')] \}$$

$$\lambda_m^{[U21]} = \frac{N}{4\lambda^2} \{ J_m(\lambda a') [Y_m(\lambda b) - iJ_m(\lambda b)] + \frac{2}{\pi} I_m(\lambda a') [K_m(\lambda b) - (-1)^m iI_m(\lambda b)] \}$$

$$\lambda_m^{[U22]} = \frac{N}{4\lambda^2} \{ J_m(\lambda b) [Y_m(\lambda b') - iJ_m(\lambda b')] + \frac{2}{\pi} I_m(\lambda b) [K_m(\lambda b') - (-1)^m iI_m(\lambda b')] \}$$





Similar transformation

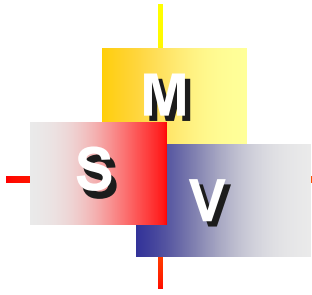
By using the similar transformation

$$[U11] = \Phi \Sigma_{[U11]} \Phi^H$$

$$\Sigma_{[U11]} = \text{diag}(\lambda_0^{[U11]} \lambda_1^{[U11]} \lambda_{-1}^{[U11]} \dots \lambda_{N-1}^{[U11]} \lambda_N^{[U11]})$$

$$\Phi = \frac{1}{\sqrt{2N}} \begin{bmatrix} 1 & (e^{2\pi i/2N})^0 & (e^{-2\pi i/2N})^0 & \dots & (e^{-2(N-1)\pi i/2N})^0 & (e^{2N\pi i/2N})^0 \\ 1 & (e^{2\pi i/2N})^1 & (e^{-2\pi i/2N})^1 & \dots & (e^{-2(N-1)\pi i/2N})^1 & (e^{2N\pi i/2N})^1 \\ 1 & (e^{2\pi i/2N})^2 & (e^{-2\pi i/2N})^2 & \dots & (e^{-2(N-1)\pi i/2N})^2 & (e^{2N\pi i/2N})^2 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 1 & (e^{2\pi i/2N})^{2N-2} & (e^{-2\pi i/2N})^{2N-2} & \dots & (e^{-2(N-1)\pi i/2N})^{2N-2} & (e^{2N\pi i/2N})^{2N-2} \\ 1 & (e^{2\pi i/2N})^{2N-1} & (e^{-2\pi i/2N})^{2N-1} & \dots & (e^{-2(N-1)\pi i/2N})^{2N-1} & (e^{2N\pi i/2N})^{2N-1} \end{bmatrix}$$



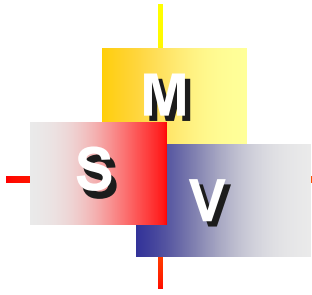


Similar transformation

$$[SM^{cc}] = \begin{bmatrix} \Phi & 0 & 0 & 0 \\ 0 & \Phi & 0 & 0 \\ 0 & 0 & \Phi & 0 \\ 0 & 0 & 0 & \Phi \end{bmatrix} \begin{bmatrix} \Sigma_{[U11]} & \Sigma_{[U12]} & \Sigma_{[\Theta11]} & \Sigma_{[\Theta12]} \\ \Sigma_{[U21]} & \Sigma_{[U22]} & \Sigma_{[\Theta21]} & \Sigma_{[\Theta22]} \\ \Sigma_{[U11_\theta]} & \Sigma_{[U12_\theta]} & \Sigma_{[\Theta11_\theta]} & \Sigma_{[\Theta12_\theta]} \\ \Sigma_{[U21_\theta]} & \Sigma_{[U22_\theta]} & \Sigma_{[\Theta21_\theta]} & \Sigma_{[\Theta22_\theta]} \end{bmatrix} \begin{bmatrix} \Phi & 0 & 0 & 0 \\ 0 & \Phi & 0 & 0 \\ 0 & 0 & \Phi & 0 \\ 0 & 0 & 0 & \Phi \end{bmatrix}^H$$

$$\det[SM^{cc}] = \det \begin{bmatrix} \Sigma_{[U11]} & \Sigma_{[U12]} & \Sigma_{[\Theta11]} & \Sigma_{[\Theta12]} \\ \Sigma_{[U21]} & \Sigma_{[U22]} & \Sigma_{[\Theta21]} & \Sigma_{[\Theta22]} \\ \Sigma_{[U11_\theta]} & \Sigma_{[U12_\theta]} & \Sigma_{[\Theta11_\theta]} & \Sigma_{[\Theta12_\theta]} \\ \Sigma_{[U21_\theta]} & \Sigma_{[U22_\theta]} & \Sigma_{[\Theta21_\theta]} & \Sigma_{[\Theta22_\theta]} \end{bmatrix}_{8N \times 8N}$$





True and spurious eigenequations

$$\det[SM^{cc}] = \prod_{m=-(N-1)}^N \det([T_m^{cc}][S_m^{U\Theta}])$$

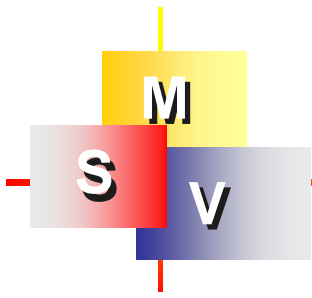
$$[T_m^{cc}] = \begin{bmatrix} J_m(\lambda a) & Y_m(\lambda a) & I_m(\lambda a) & K_m(\lambda a) \\ J_m(\lambda b) & Y_m(\lambda b) & I_m(\lambda b) & K_m(\lambda b) \\ J'_m(\lambda a) & Y'_m(\lambda a) & I'_m(\lambda a) & K'_m(\lambda a) \\ J'_m(\lambda b) & Y'_m(\lambda b) & I'_m(\lambda b) & K'_m(\lambda b) \end{bmatrix}$$

True eigenequation

$$[S_m^{U\Theta}] = \begin{bmatrix} -iJ_m(\lambda a') & Y_m(\lambda b') - iJ_m(\lambda b') & -iJ'_m(\lambda a') & Y'_m(\lambda b') - iJ'_m(\lambda b') \\ J_m(\lambda a') & 0 & J'_m(\lambda a') & 0 \\ -(-1)^m i \frac{2}{\pi} I_m(\lambda a') & \frac{2}{\pi} [k_m(\lambda b') - (-1)^m i I_m(\lambda b')] & -(-1)^m i \frac{2}{\pi} I'_m(\lambda a') & \frac{2}{\pi} [k'_m(\lambda b') - (-1)^m i I'_m(\lambda b')] \\ \frac{2}{\pi} I_m(\lambda a') & 0 & \frac{2}{\pi} I'_m(\lambda a') & 0 \end{bmatrix}$$

Spurious eigenequation





Discussion of spurious eigenequation

$$\det[S_m^{U\Theta}] = \det[S_{a'}(a')] \det[S_{b'}(b')] = 0$$

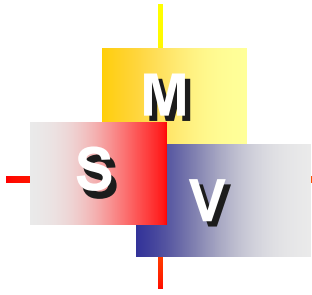
$$\det[S_{b'}(b')] = \frac{2}{\pi} \begin{vmatrix} Y_m(\lambda b') - iJ_m(\lambda b') & Y'_m(\lambda b') - iJ'_m(\lambda b') \\ K_m(\lambda b') - i(-1)^m I_m(\lambda b') & K'_m(\lambda b') - i(-1)^m I'_m(\lambda b') \end{vmatrix}$$

Never zero for any

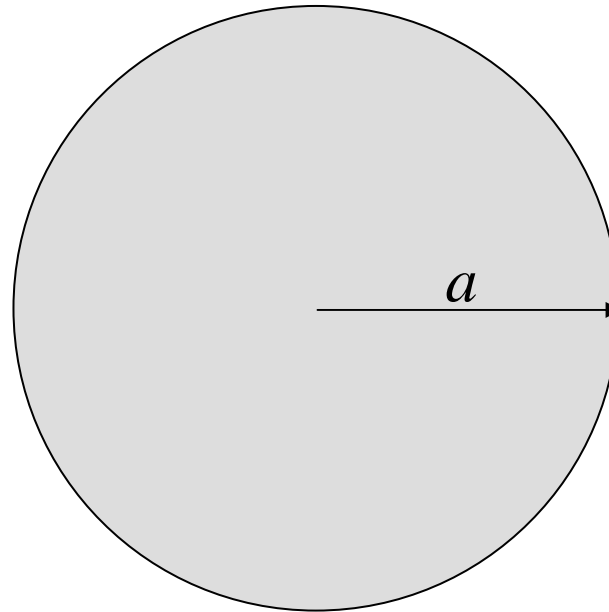
$$\det[S_{a'}(a')] = \frac{2}{\pi} \begin{vmatrix} J_m(\lambda a') & J'_m(\lambda a') \\ I_m(\lambda a') & I'_m(\lambda a') \end{vmatrix} = 0$$

$$J_\ell(\lambda a') I_{\ell+1}(\lambda a') + I_\ell(\lambda a') J_{\ell+1}(\lambda a') = 0$$



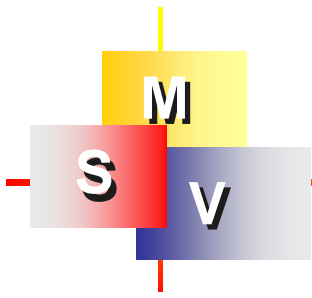


True eigenequation of clamped plate



$$J_{\ell}(\lambda a)I_{\ell+1}(\lambda a) + I_{\ell}(\lambda a)J_{\ell+1}(\lambda a) = 0$$

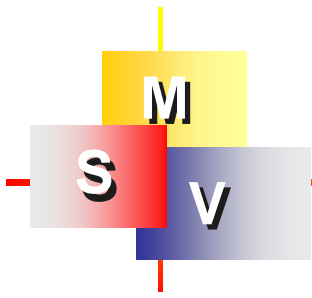




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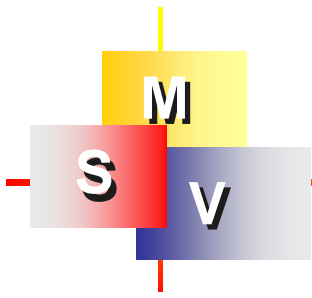


SVD updating technique

$$[SM^{cc}] \begin{Bmatrix} \phi 1 \\ \phi 2 \\ \phi 1 \\ \phi 2 \end{Bmatrix} = \begin{bmatrix} U11 & U12 & \Theta 11 & \Theta 12 \\ U21 & U22 & \Theta 21 & \Theta 22 \\ U11_{\theta} & U12_{\theta} & \Theta 11_{\theta} & \Theta 12_{\theta} \\ U21_{\theta} & U22_{\theta} & \Theta 21_{\theta} & \Theta 22_{\theta} \end{bmatrix} \begin{Bmatrix} \phi 1 \\ \phi 2 \\ \phi 1 \\ \phi 2 \end{Bmatrix} = \{0\}$$

$$[SM_1^{cc}] \begin{Bmatrix} \phi'1 \\ \phi'2 \\ \phi'1 \\ \phi'2 \end{Bmatrix} = \begin{bmatrix} M11 & M12 & V11 & V12 \\ M21 & M22 & V21 & V22 \\ M11_{\theta} & M12_{\theta} & V11_{\theta} & V12_{\theta} \\ M21_{\theta} & M22_{\theta} & V21_{\theta} & V22_{\theta} \end{bmatrix} \begin{Bmatrix} \phi'1 \\ \phi'2 \\ \phi'1 \\ \phi'2 \end{Bmatrix} = \{0\}$$





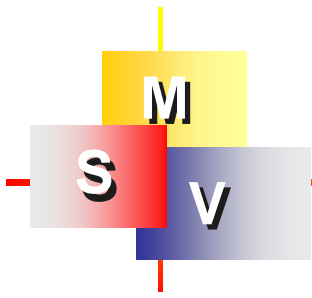
SVD updating technique

$$[C] = \begin{bmatrix} (SM^{cc})^H \\ (SM_1^{cc})^H \end{bmatrix}$$

By using SVD technique and the least-squares method, we have

$$\begin{vmatrix} J_m(\lambda a) & Y_m(\lambda a) & I_m(\lambda a) & K_m(\lambda a) \\ J_m(\lambda b) & Y_m(\lambda b) & I_m(\lambda b) & K_m(\lambda b) \\ J'_m(\lambda a) & Y'_m(\lambda a) & I'_m(\lambda a) & K'_m(\lambda a) \\ J'_m(\lambda b) & Y'_m(\lambda b) & I'_m(\lambda b) & K'_m(\lambda b) \end{vmatrix} = 0$$





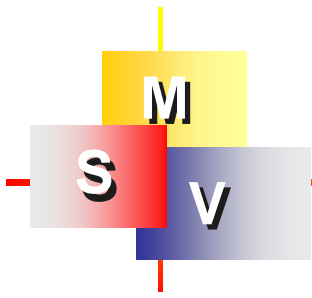
Burton & Miller method

$$\left[[SM^{cc}] + i[SM_1^{cc}] \right] \begin{Bmatrix} \psi 1 \\ \psi 2 \end{Bmatrix} = \{0\}$$

True eigenequation is obtained

$$\begin{vmatrix} J_m(\lambda a) & Y_m(\lambda a) & I_m(\lambda a) & K_m(\lambda a) \\ J_m(\lambda b) & Y_m(\lambda b) & I_m(\lambda b) & K_m(\lambda b) \\ J'_m(\lambda a) & Y'_m(\lambda a) & I'_m(\lambda a) & K'_m(\lambda a) \\ J'_m(\lambda b) & Y'_m(\lambda b) & I'_m(\lambda b) & K'_m(\lambda b) \end{vmatrix} = 0$$

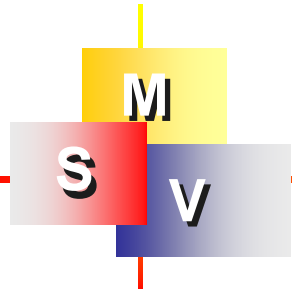




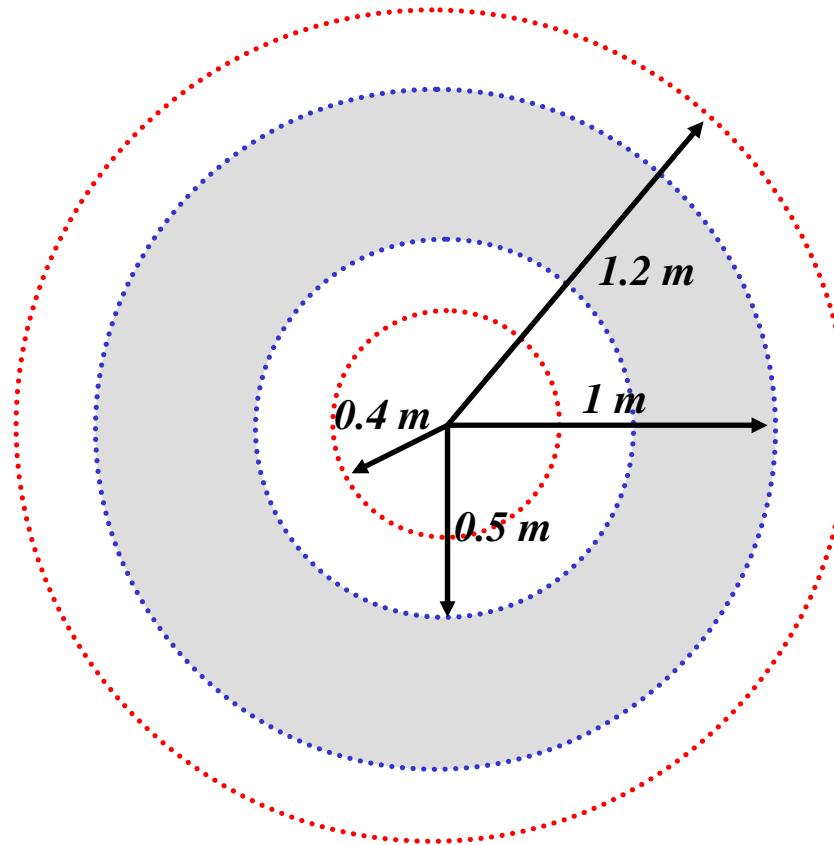
Outlines

1. Introduction
2. Methods of solution
3. Mathematical analysis
4. Treatment methods
- 5. Numerical example**
6. Conclusions





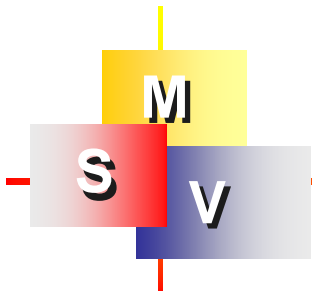
Numerical example



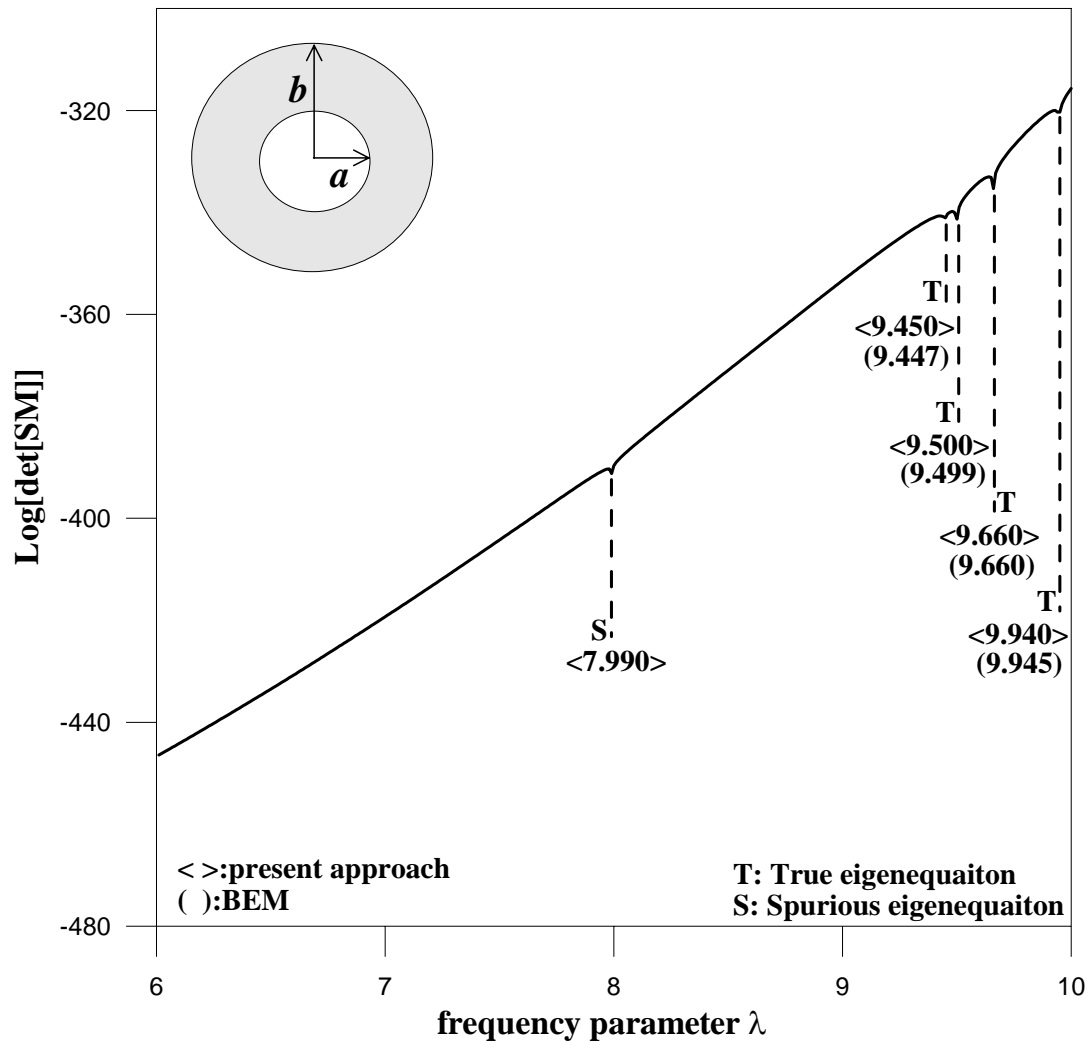
..... Collocation point distribution

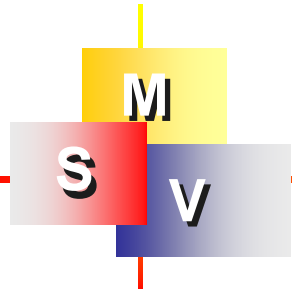
..... Source point distribution



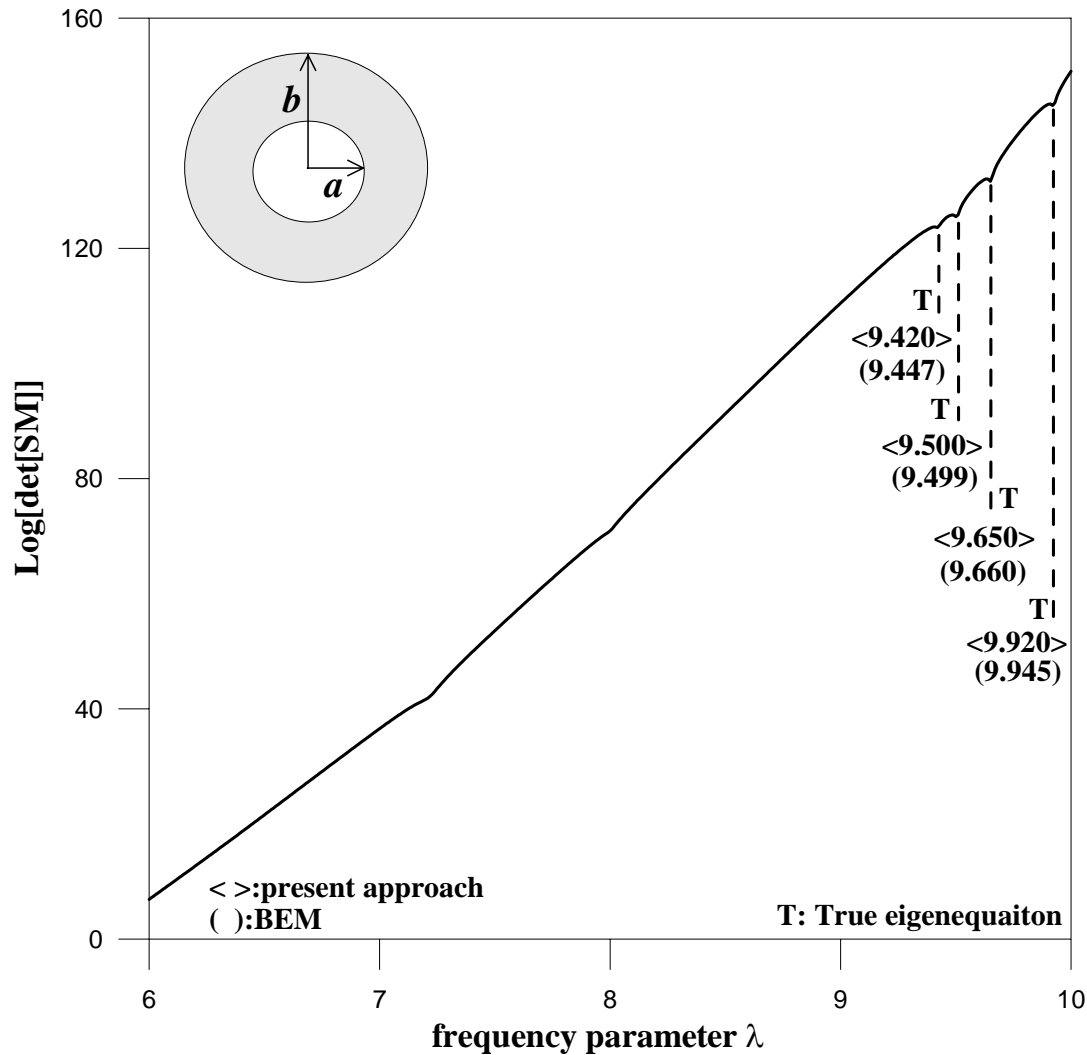


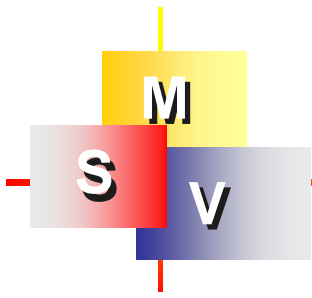
Numerical result (*U*-formulation)





Burton & Miller method

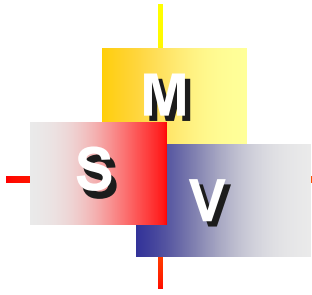




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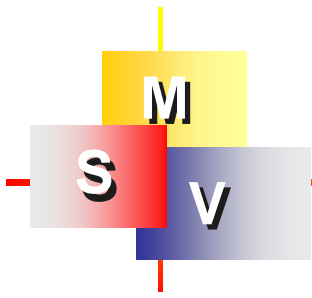




Conclusions

1. The mathematical analysis has shown that spurious eigenvalues occur by using **degenerate kernels** and **circulants**.
2. The positions of spurious eigenvalues for the annular problem depend on the **location of inner fictitious boundary** where the sources are distributed.
3. The spurious eigenvalues in the annular problem are found to be the true eigenvalues of the associated **simply-connected problem bounded by the inner sources**.
4. **SVD updating technique** and **Burton & Miller method** were used to filter out the spurious eigenvalues successfully.
5. For the membrane case, one paper of EABE is in press.

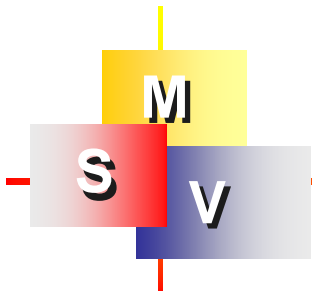




Welcome to Mechanics, Sound and Vibration Laboratory

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The End

Thanks for your kind attention

