

Derivation of the Green's function for Laplace and Helmholtz problems with circular boundaries by using the null-field integral equation approach

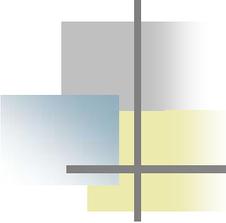
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Committee members :

Chen I. L., Lee W. M., Leu S. Y. & Chen K, H.

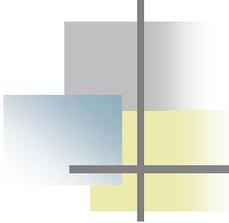




Outlines

- **Motivation and literature review**
- **Derivation of the Green's function**
 - Expansions of fundamental solution and boundary density
 - Adaptive observer system
 - Vector decomposition technique
 - Linear algebraic equation
 - Take free body
 - Image technique for solving half-plane problems
- **Numerical examples**
 - Green's function for Laplace problems
 - Green's function for Helmholtz problems
- **Conclusions**





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Motivation

Numerical methods for engineering problems

FDM / FEM / BEM / BIEM / Meshless method

BEM / BIEM

Treatment of singularity and hypersingularity

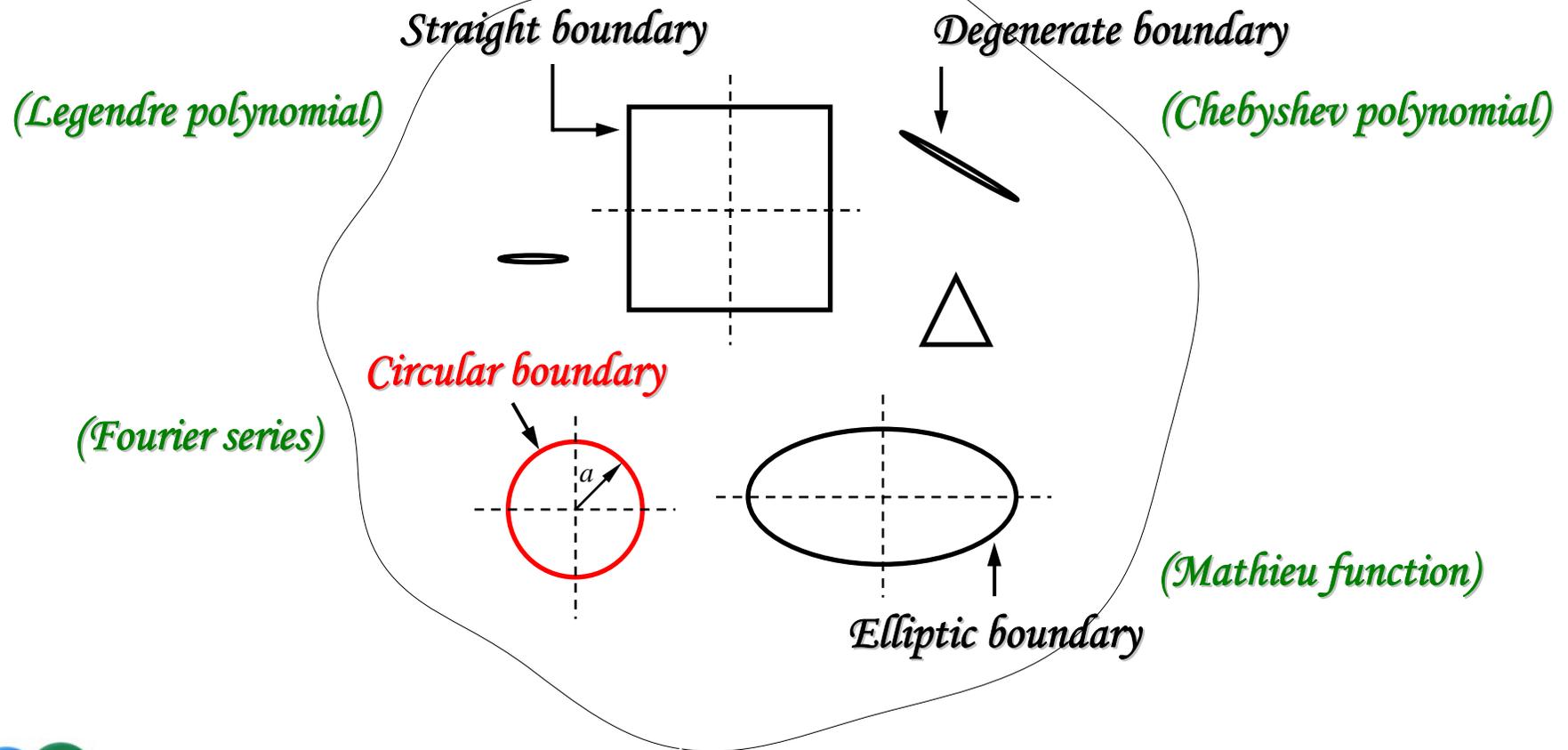
Boundary-layer effect

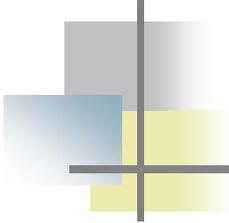
Convergence rate

Ill-posed model



Engineering problem with arbitrary geometries





Literature review

Derivation of the Green's function

Successive iteration method

Boley, 1956, "A method for the construction of Green's functions," Quarterly of Applied Mathematics

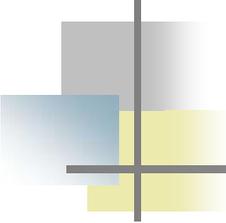
Modified potential method

Melnikov, 2001, "Modified potential as a tool for computing Green's functions in continuum mechanics", Computer Modeling in Engineering Science

Trefftz bases

Wang and Sudak, 2007, "Antiplane time-harmonic Green's functions for a circular inhomogeneity with an imperfect interface", Mechanics Research Communications





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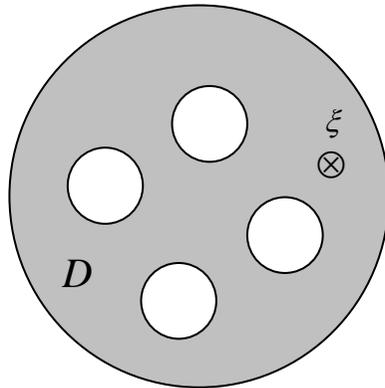
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Null-field integral approach to construct the Green's function

Original Problem



Governing equation: $\nabla^2 G(x, \xi) = \delta(x - \xi), x \in D$

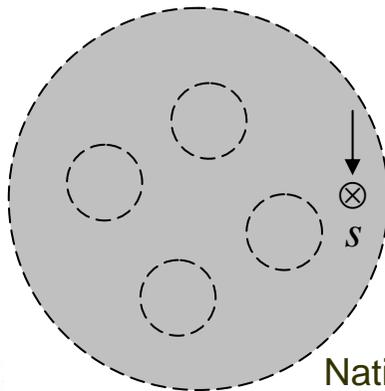
Boundary condition: Subjected to given B. C.

Green's third identity

BIE for Green's function

$$\begin{aligned} & \iint_D [u(x)\nabla^2 v(x) - v(x)\nabla^2 u(x)]dD(x) & 2\pi G(x, \xi) &= \int_B \frac{\partial U(s, x)}{\partial n_s} G(s, \xi)dB(s) \\ & = \int_B [(u(x)\frac{\partial v(x)}{\partial n} - v(x)\frac{\partial u(x)}{\partial n})]dB(x) & & - \int_B U(s, x)\frac{\partial G(s, \xi)}{\partial n_s}dB(s) + U(\xi, x) \end{aligned}$$

Auxiliary system



Governing equation: $\nabla^2 U(x, s) = 2\pi\delta(x - s)$

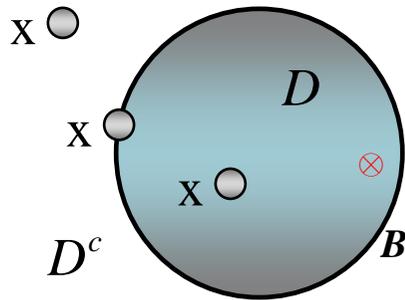
$v(x) = U(s, x)$ Fundamental solution

$u(x) = G(x, \xi)$



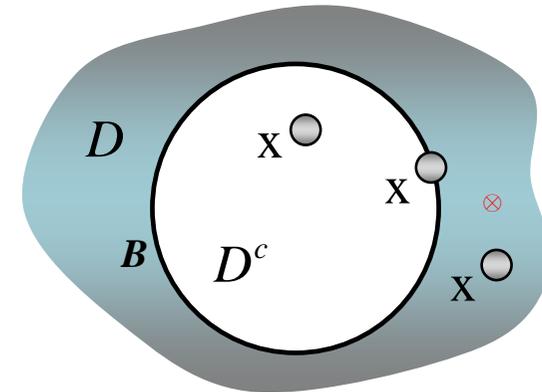
Boundary integral equation and null-field integral equation

Interior case



$$T(s, \mathbf{x}) = \frac{\partial U(s, \mathbf{x})}{\partial n_s}$$

Exterior case



$$2\pi G(\mathbf{x}, \xi) = \int_B T(s, \mathbf{x}) G(s, \xi) dB(s) - \int_B U(s, \mathbf{x}) \frac{\partial G(s, \xi)}{\partial n_s} dB(s) + U(\xi, \mathbf{x}), \quad \mathbf{x} \in D \cup B$$

$$\pi G(\mathbf{x}, \xi) = C.P.V. \int_B T(s, \mathbf{x}) G(s, \xi) dB(s) - P.P.V. \int_B U(s, \mathbf{x}) \frac{\partial G(s, \xi)}{\partial n_s} dB(s) + U(\xi, \mathbf{x}), \quad \mathbf{x} \in B$$

Generate (separate) form.

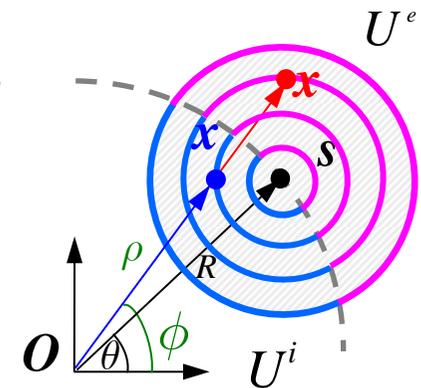
$$0 \equiv \int_B T(s, \mathbf{x}) G(s, \xi) dB(s) - \int_B U(s, \mathbf{x}) \frac{\partial G(s, \xi)}{\partial n_s} dB(s) + U(\xi, \mathbf{x}), \quad \mathbf{x} \in D^c \cup B$$



Expansions of fundamental solution (2D)

Laplace problem-- $U(s, x) = \ln|x - s| = \ln r$

$$U(s, x) = \begin{cases} U^i(R, \theta; \rho, \phi) = \ln R - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{\rho}{R}\right)^m \cos m(\theta - \phi), & R \geq \rho \\ U^e(R, \theta; \rho, \phi) = \ln \rho - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R}{\rho}\right)^m \cos m(\theta - \phi), & \rho > R \end{cases}$$

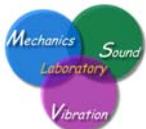


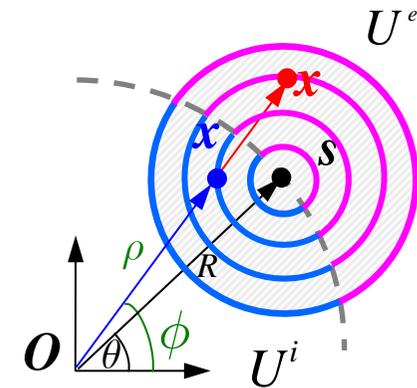
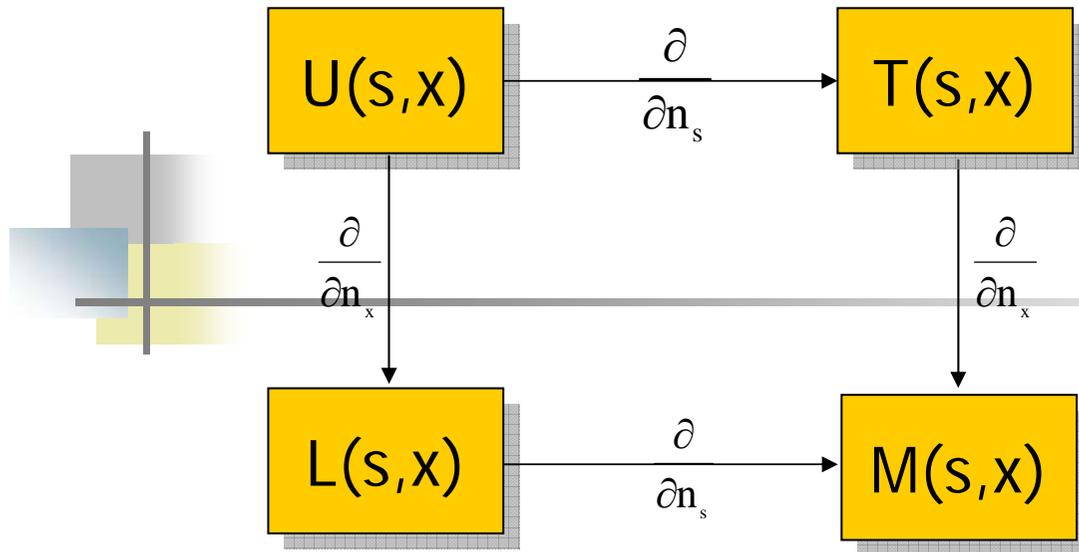
Helmholtz problem-- $U(s, x) = -i\pi H_0^{(1)}(kr)/2$

$$U(s, x) = \begin{cases} U^i(R, \theta; \rho, \phi) = \frac{-\pi i}{2} \sum_{m=0}^{\infty} \varepsilon_m J_m(k\rho) H_m^{(1)}(kR) \cos(m(\theta - \phi)), & R \geq \rho \\ U^e(R, \theta; \rho, \phi) = \frac{-\pi i}{2} \sum_{m=0}^{\infty} \varepsilon_m H_m^{(1)}(k\rho) J_m(kR) \cos(m(\theta - \phi)), & \rho > R \end{cases}$$

Neumann factor

$$\varepsilon_m = \begin{cases} 1, & m = 0 \\ 2, & m = 1, 2, \dots \end{cases}$$





Laplace problem--

$$T(s, x) = \begin{cases} T^i(R, \theta; \rho, \phi) = \frac{1}{R} + \sum_{m=1}^{\infty} \left(\frac{\rho^m}{R^{m+1}}\right) \cos m(\theta - \phi), & R > \rho \\ T^e(R, \theta; \rho, \phi) = -\sum_{m=1}^{\infty} \left(\frac{R^{m-1}}{\rho^m}\right) \cos m(\theta - \phi), & \rho > R \end{cases}$$

Helmholtz problem--

$$T(s, x) = \begin{cases} T^i(R, \theta; \rho, \phi) = \frac{-\pi k i}{2} \sum_{m=0}^{\infty} \varepsilon_m J_m(k\rho) H_m^{(1)}(kR) \cos(m(\theta - \phi)), & R > \rho \\ T^e(R, \theta; \rho, \phi) = \frac{-\pi k i}{2} \sum_{m=0}^{\infty} \varepsilon_m J'_m(kR) H_m^{(1)}(k\rho) \cos(m(\theta - \phi)), & \rho > R \end{cases}$$

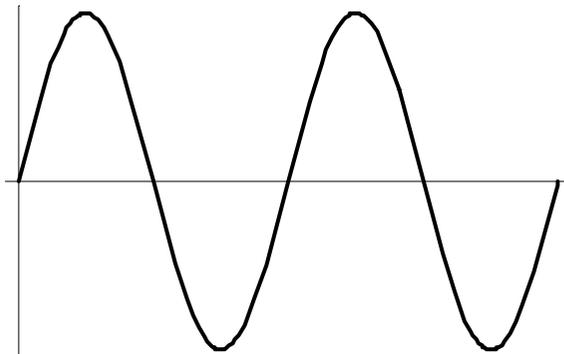


Boundary density discretization

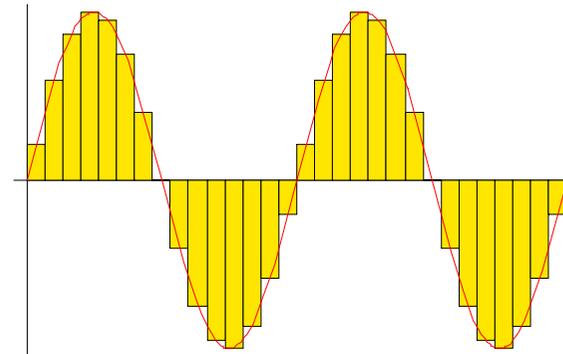
Fourier series expansions - boundary density

$$u(s) = a_0 + \sum_{n=1}^{\infty} (a_n \cos n\theta + b_n \sin n\theta), \quad s \in B$$

$$t(s) = p_0 + \sum_{n=1}^{\infty} (p_n \cos n\theta + q_n \sin n\theta), \quad s \in B$$



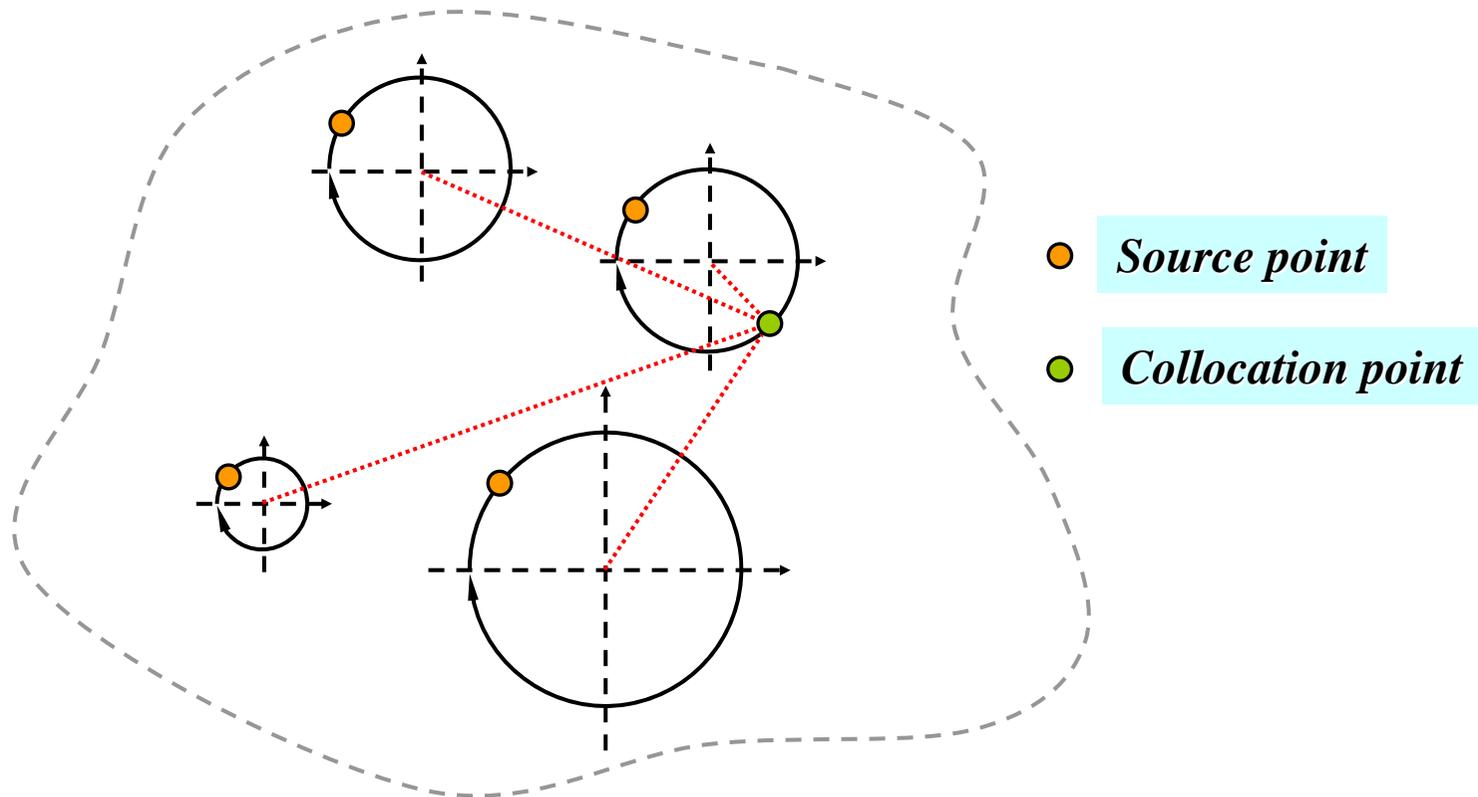
Fourier series



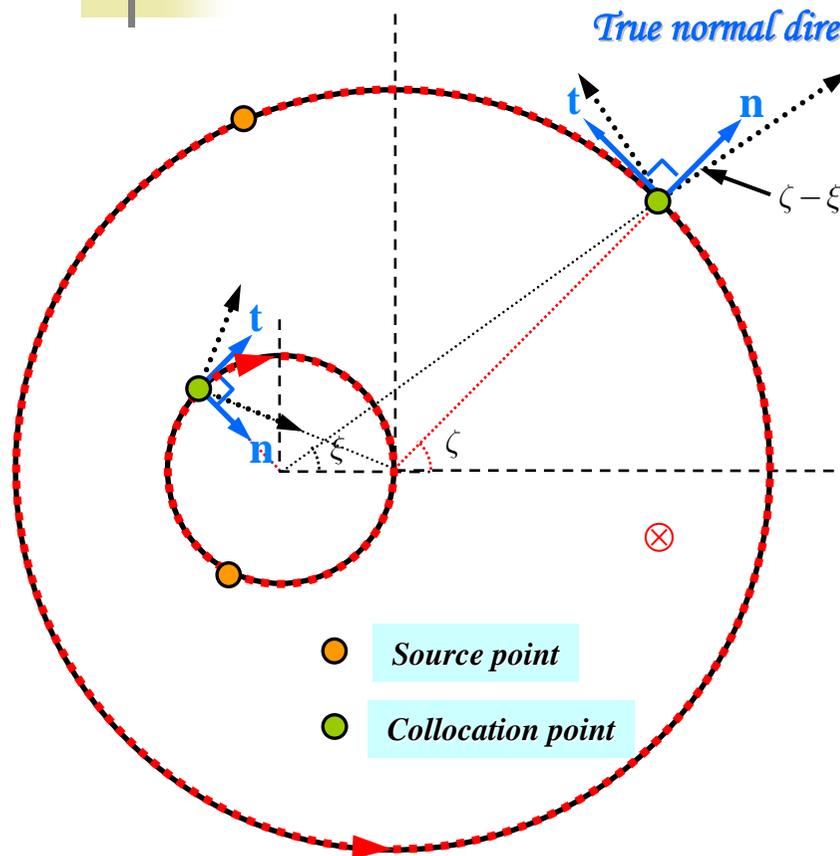
Ex. constant element



Adaptive observer system



Vector decomposition technique for potential gradient



$$2\pi \frac{\partial G(x, \xi)}{\partial \mathbf{n}} = \int_B M_\rho(s, x) G(s) dB(s) - \int_B L_\rho(s, x) \frac{\partial G(s)}{\partial \mathbf{n}} dB(s) + L_\rho(\xi, x)$$

$$2\pi \frac{\partial G(x, \xi)}{\partial \mathbf{t}} = \int_B M_\phi(s, x) G(s) dB(s) - \int_B L_\phi(s, x) \frac{\partial G(s)}{\partial \mathbf{n}} dB(s) + L_\phi(\xi, x)$$

Non-concentric case:

$$L_\rho(s, x) = \frac{\partial U(s, x)}{\partial \rho} \cos(\zeta - \xi) + \frac{1}{\rho} \frac{\partial U(s, x)}{\partial \phi} \cos\left(\frac{\pi}{2} - \zeta + \xi\right)$$

$$M_\rho(s, x) = \frac{\partial T(s, x)}{\partial \rho} \cos(\zeta - \xi) + \frac{1}{\rho} \frac{\partial T(s, x)}{\partial \phi} \cos\left(\frac{\pi}{2} - \zeta + \xi\right)$$

Concentric case (special case): $\zeta = \xi$

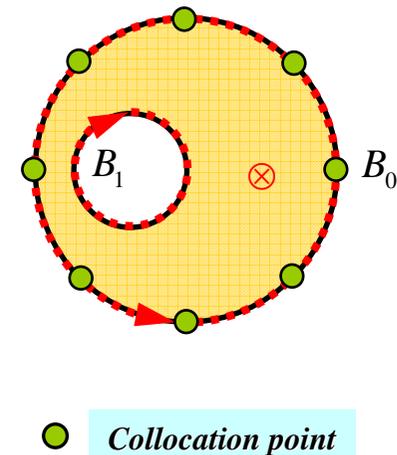
$$L_\rho(s, x) = \frac{\partial U(s, x)}{\partial \rho} \quad M_\rho(s, x) = \frac{\partial T(s, x)}{\partial \rho}$$

Linear algebraic equation

$$0 = \int_B T(s, \mathbf{x}) G(s, \xi) dB(s) - \int_B U(s, \mathbf{x}) \frac{\partial G(s, \xi)}{\partial n_s} dB(s) + U(\xi, \mathbf{x})$$

$$\rightarrow [\mathbf{U}]\{\mathbf{t}\} = [\mathbf{T}]\{\mathbf{u}\} + \{\mathbf{b}\}$$

$$[\mathbf{U}] = \begin{bmatrix} \mathbf{U}_{00} & \mathbf{U}_{01} & \cdots & \mathbf{U}_{0N} \\ \mathbf{U}_{10} & \mathbf{U}_{11} & \cdots & \mathbf{U}_{1N} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{U}_{N0} & \mathbf{U}_{N1} & \cdots & \mathbf{U}_{NN} \end{bmatrix} \quad \{\mathbf{t}\} = \begin{bmatrix} \mathbf{t}_0 \\ \mathbf{t}_1 \\ \mathbf{t}_2 \\ \vdots \\ \mathbf{t}_N \end{bmatrix} \quad \{\mathbf{b}\} = \begin{bmatrix} \mathbf{b}_0 \\ \mathbf{b}_1 \\ \mathbf{b}_2 \\ \vdots \\ \mathbf{b}_N \end{bmatrix}$$



Take free body

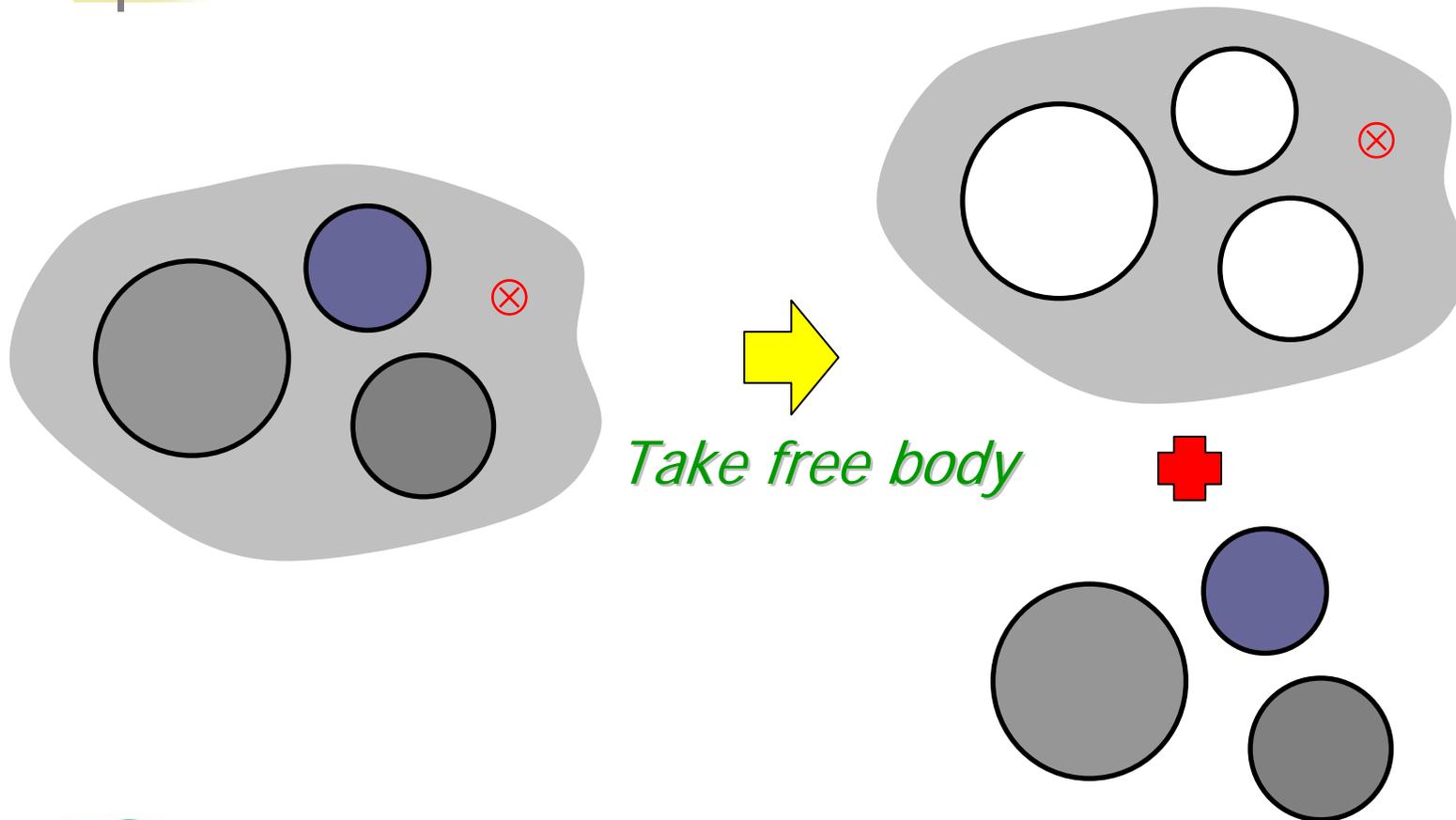
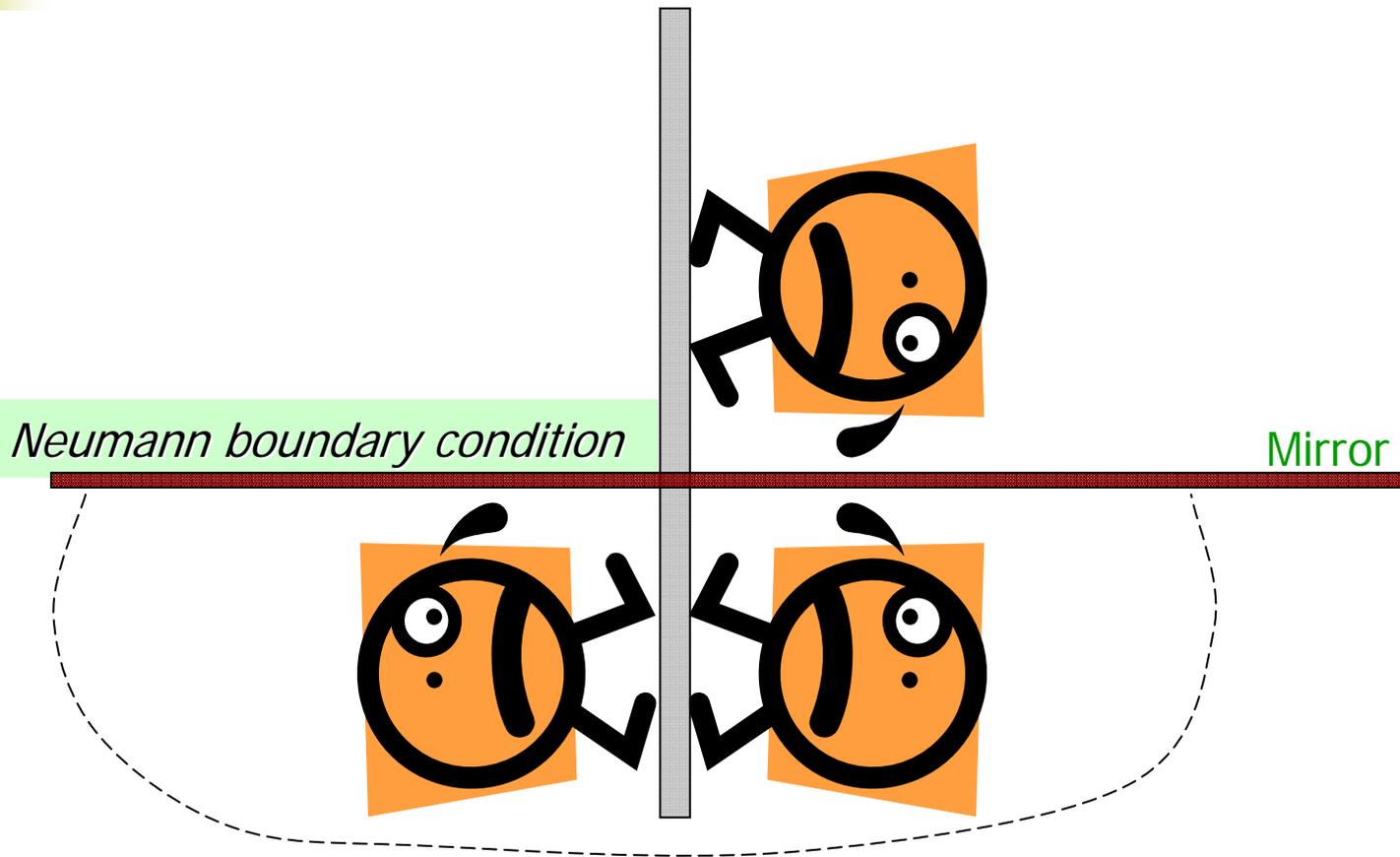
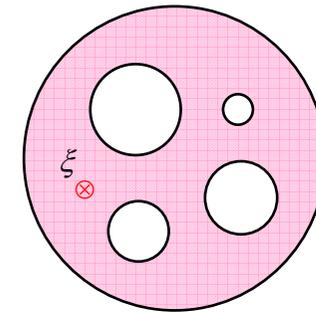
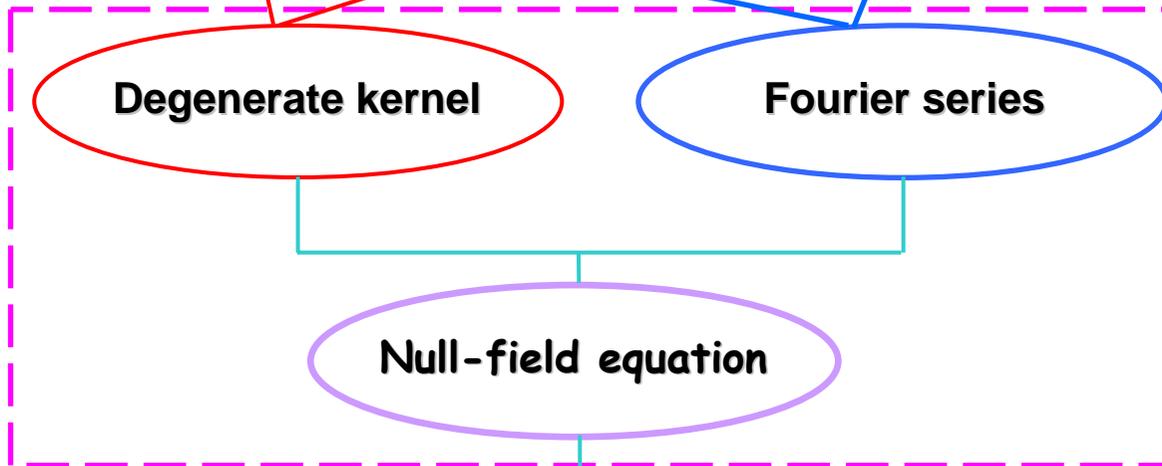


Image technique for solving half-plane problems



Flowchart of present method

$$0 = \int_B [T(s, x)G(s, \xi) - U(s, x) \frac{\partial G(s, \xi)}{\partial n_s}] dB(s) + U(\xi, x)$$



Analytical

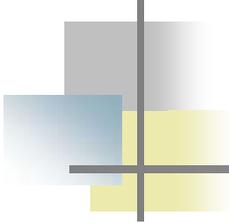
Numerical



National Taiwan Ocean University

Department of Harbor and River Engineering

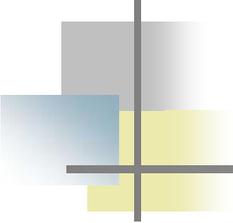




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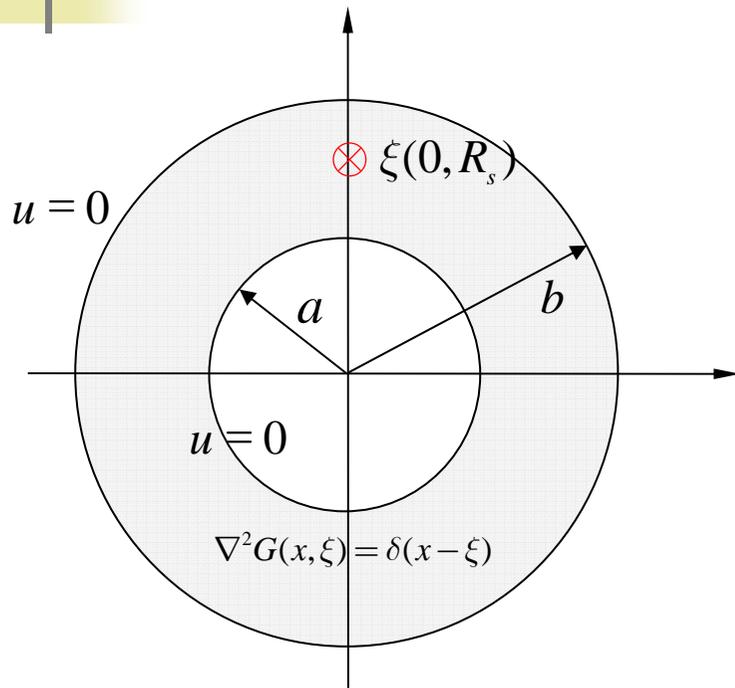


Numerical examples

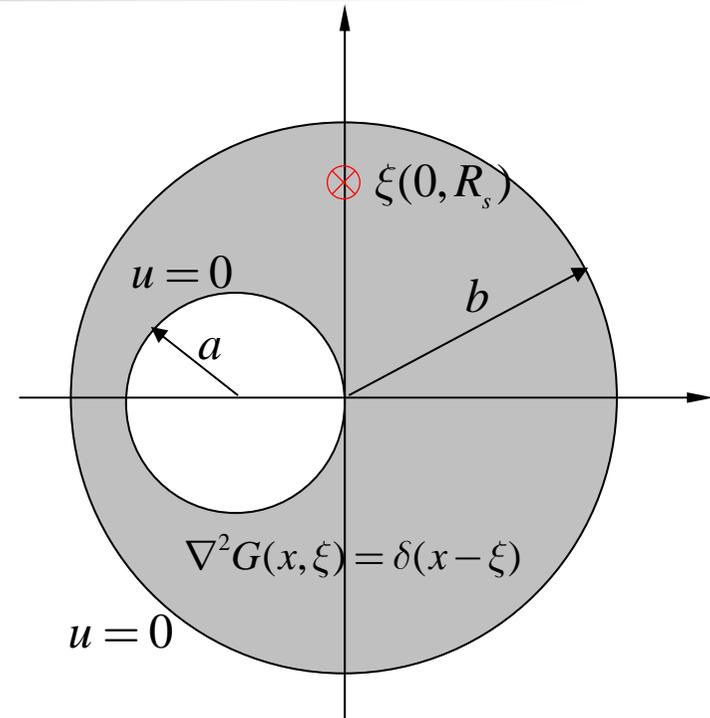
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 - Eccentric ring
 - A half-plane with an aperture
 - (1) Dirichlet boundary condition
 - (2) Robin boundary condition
 - A half-plane problem with a circular hole and a half-circular inclusion
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 - Special cases and parameter study
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Present study for Laplace equation

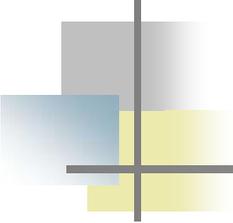


Analytical Green's function



Semi-Analytical Green's function



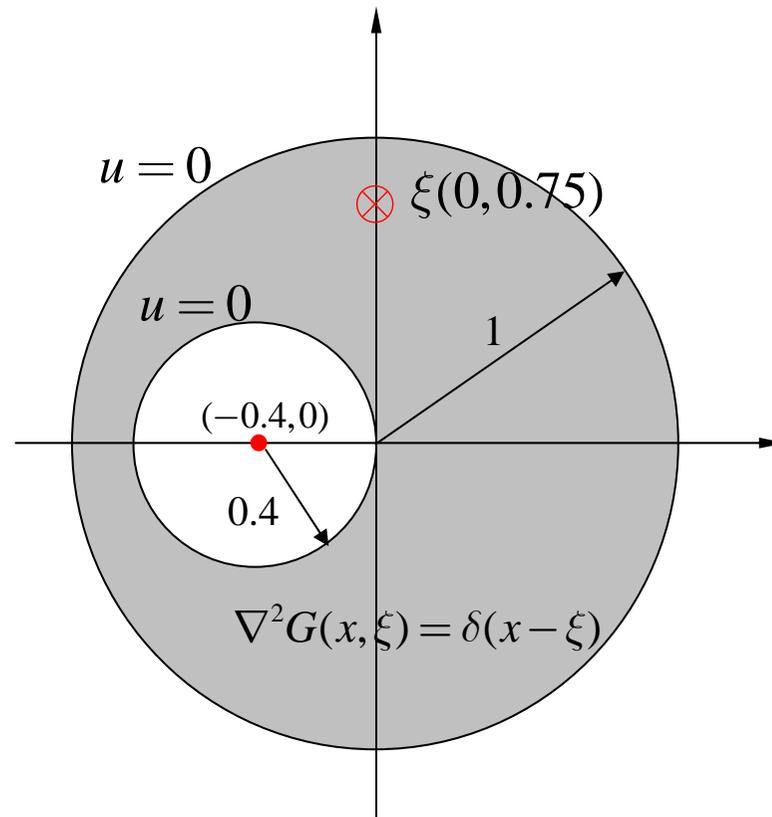


Numerical examples

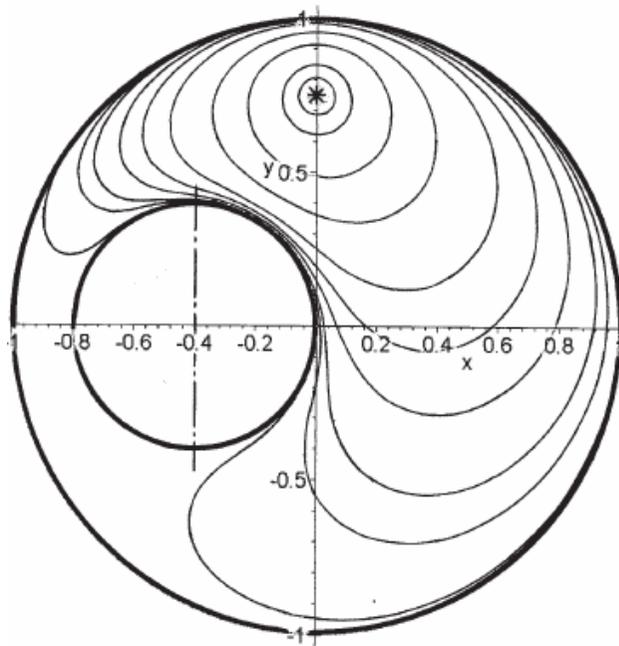
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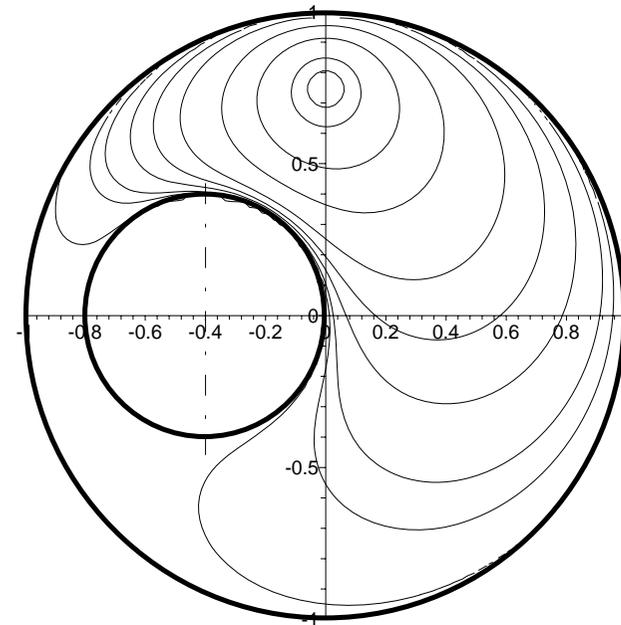
Eccentric ring



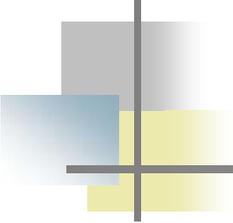
Eccentric ring



Potential contour using the Melnikov's method

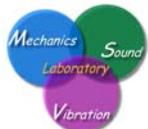


Potential contour using the present method (M=50)

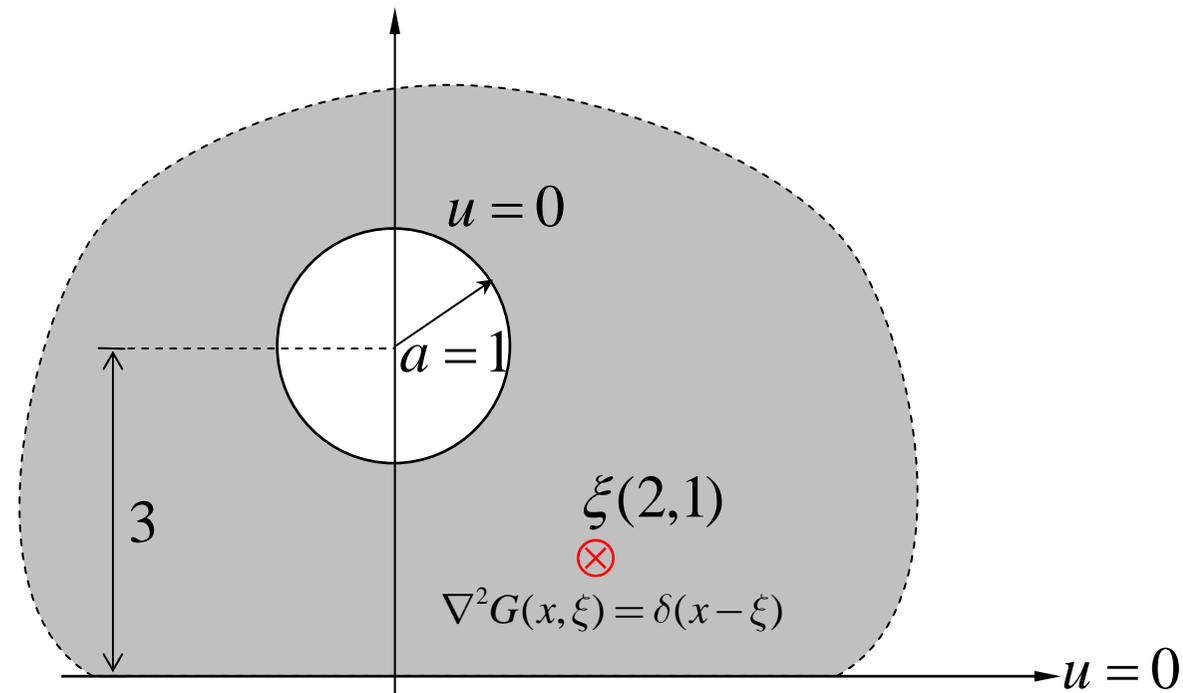


Numerical examples

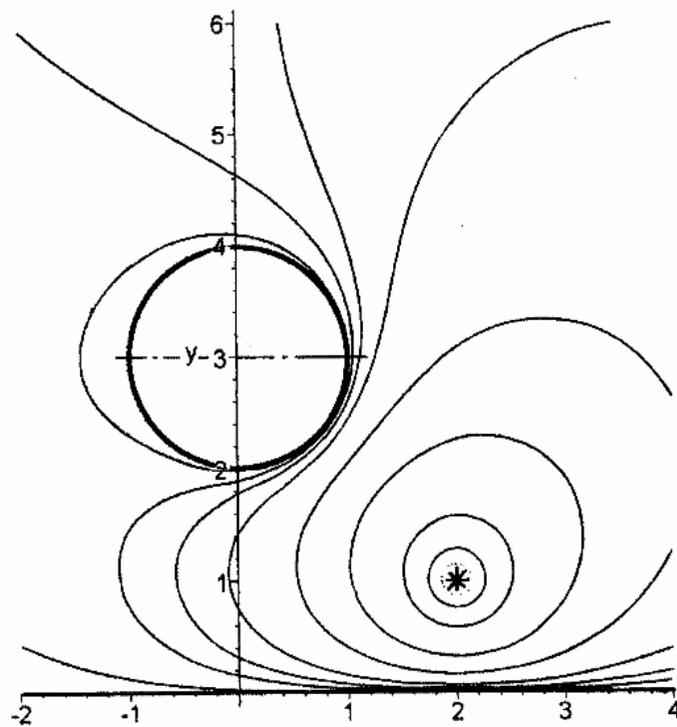
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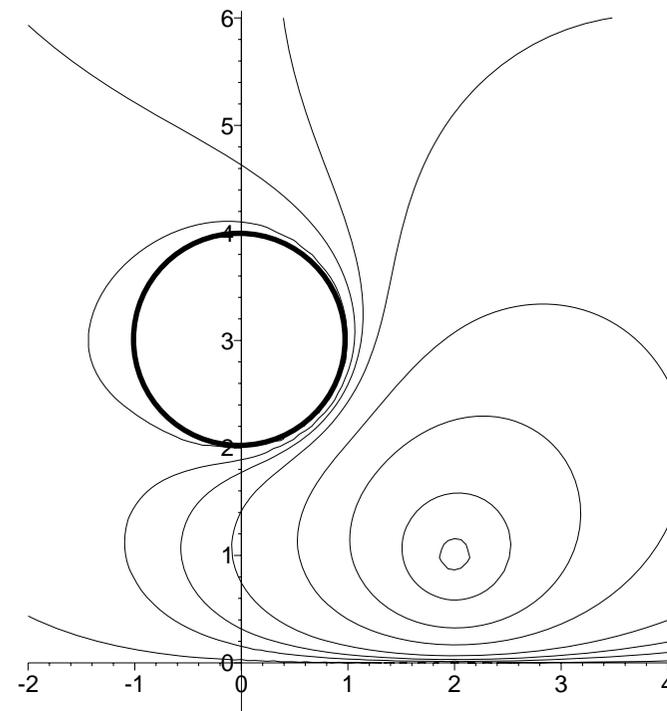
A half plane with an aperture subjected to Dirichlet boundary condition



Result of a half-plane problem with an aperture subjected to **Dirichlet boundary condition**

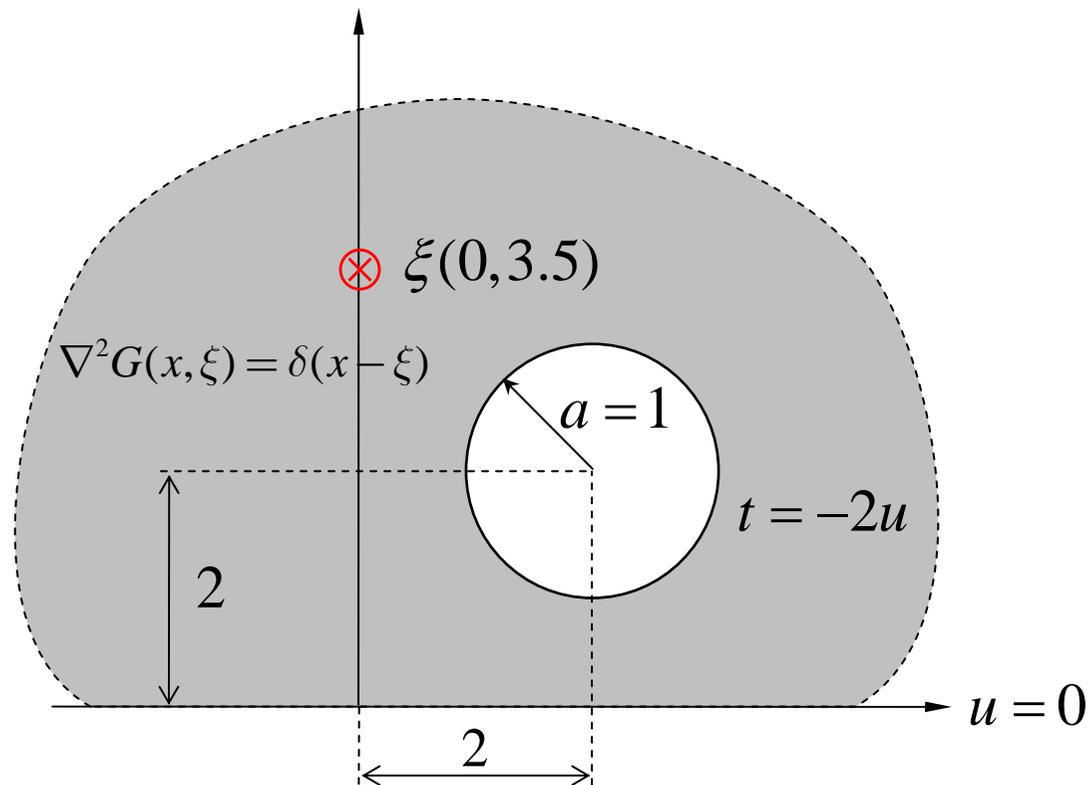


Potential contour using the Melnikov's method

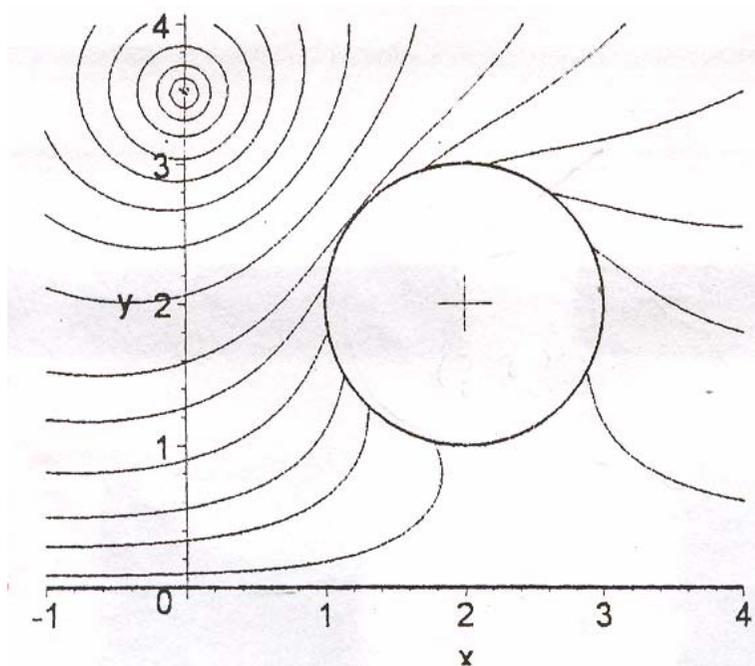


Potential contour using the present method (M=50)

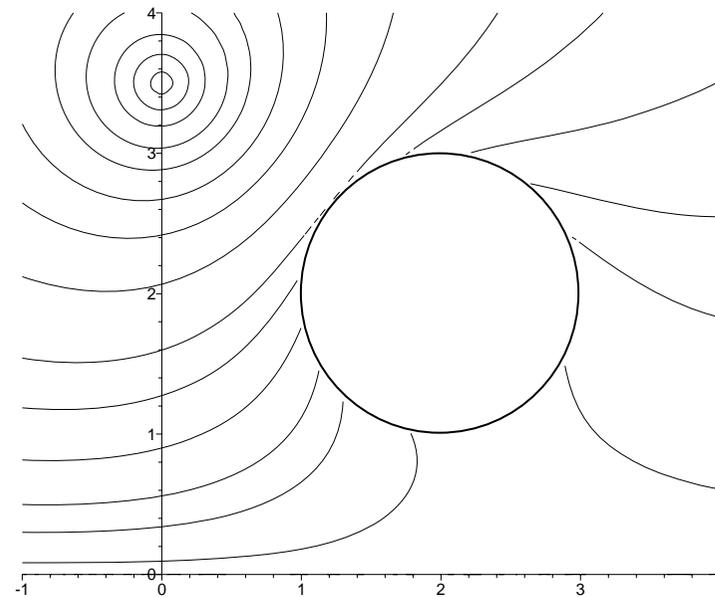
A half plane with an aperture subjected to Robin boundary condition



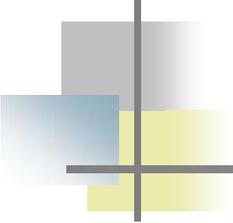
Result of a half-plane problem with an aperture subjected to Robin boundary condition



Potential contour using the Melnikov's method



Potential contour using the present method (M=50)

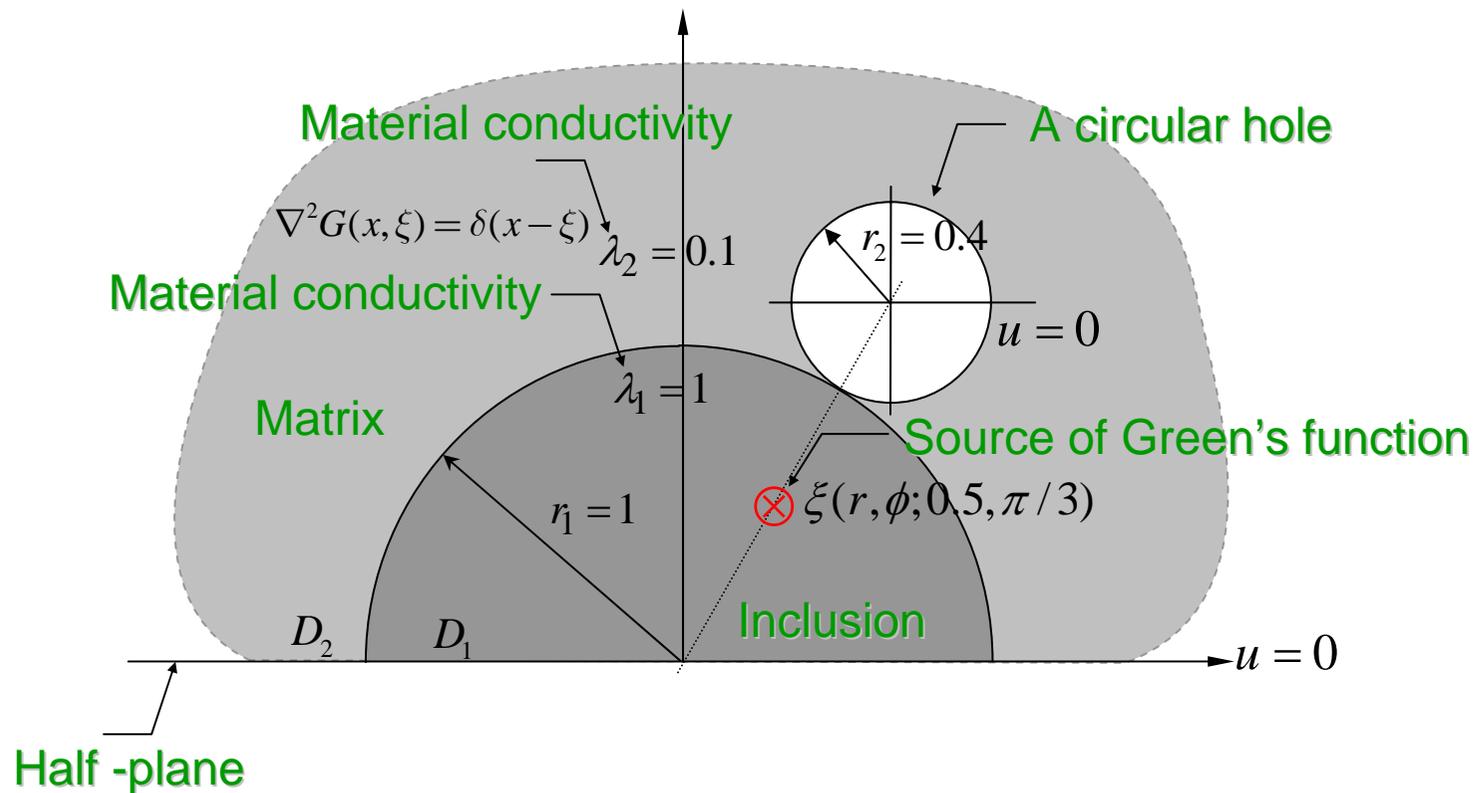


Numerical examples

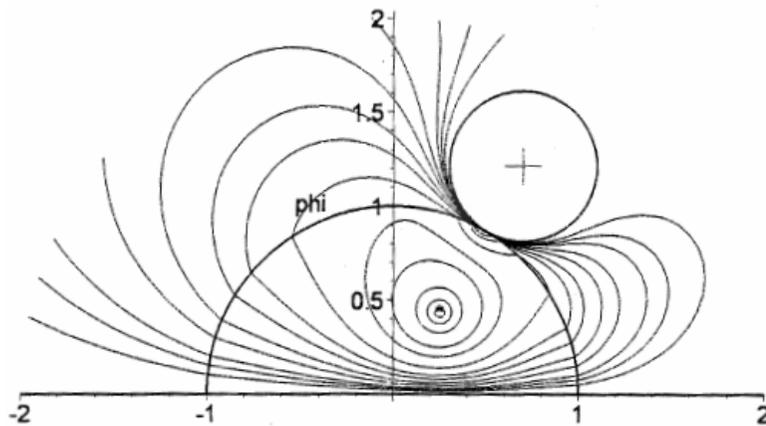
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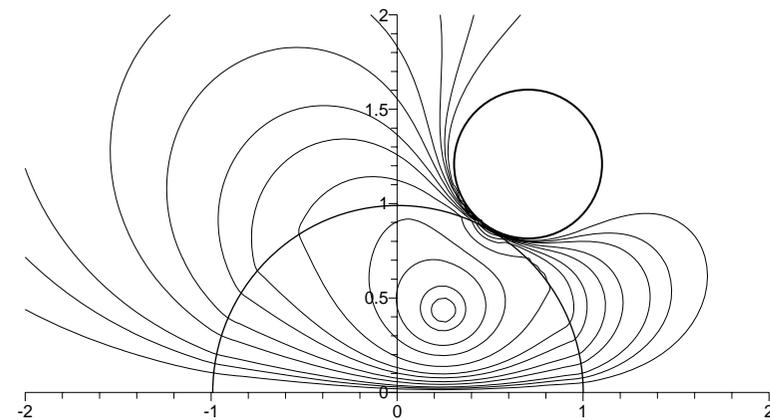
A half-plane problem with a circular hole and a half-circular inclusion



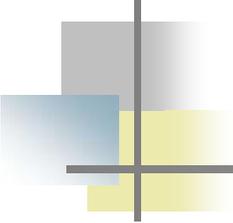
Result of a half-plane problem with a circular hole and a half-circular inclusion



Contour plot by using the Melikov's approach (2006)



Contour plot by using the null-field integral equation approach



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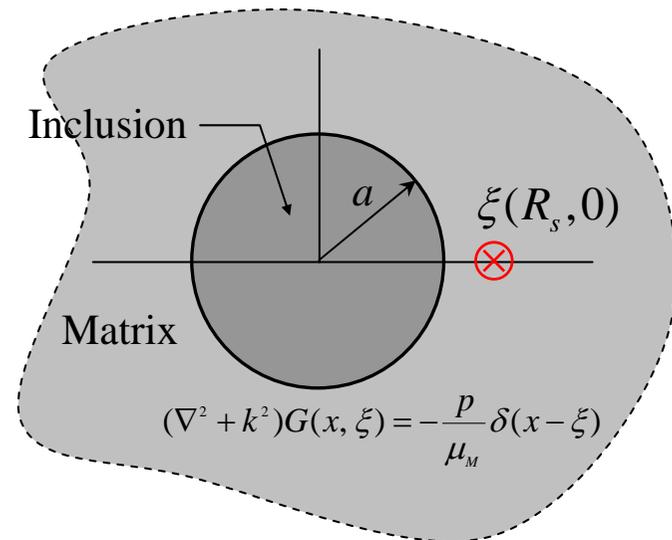
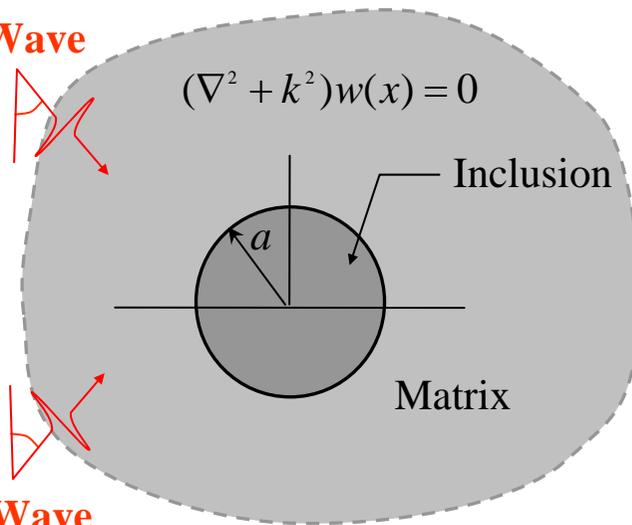
Present study for Helmholtz equation

Perfect interface boundary



Imperfect interface boundary

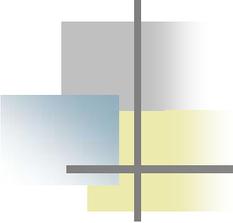
SH-Wave



SH-wave problem (Chen P. Y.)

Green's function problem (Ke J. N.)

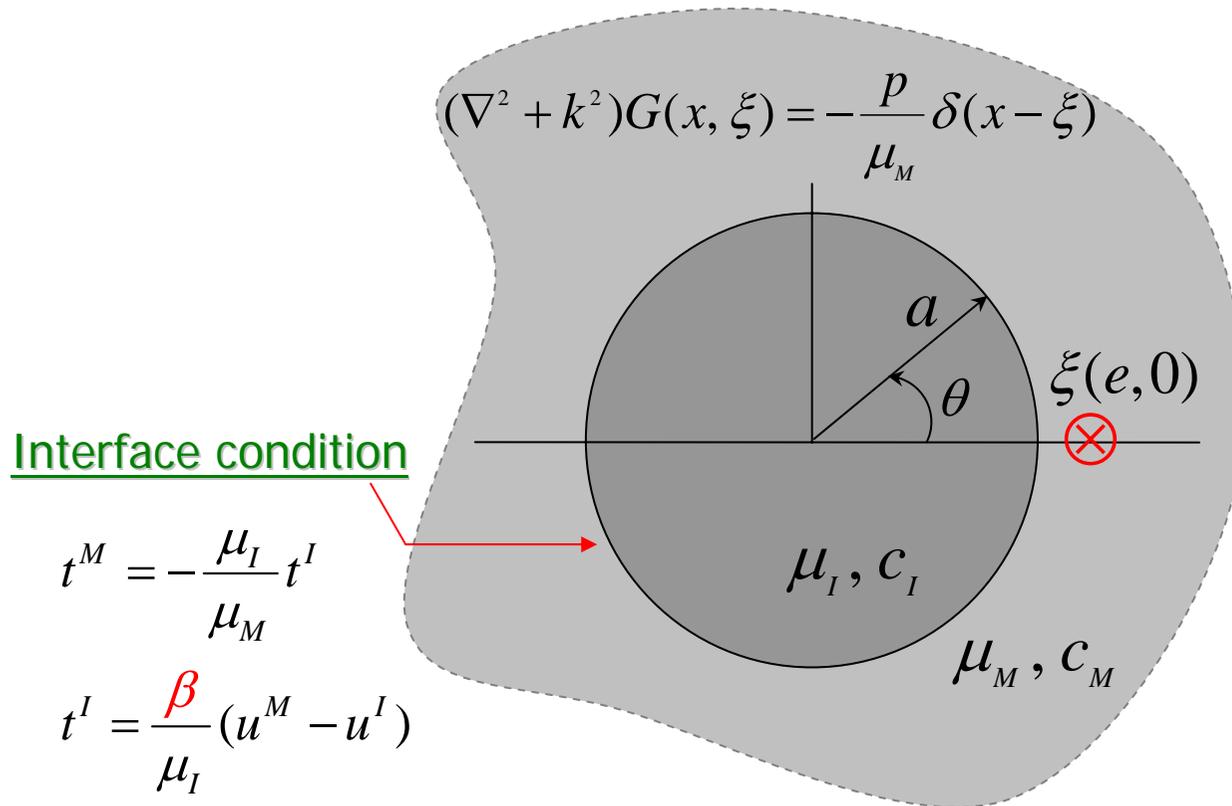




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An infinite matrix containing a circular inclusion with
a concentrated force at ξ in the matrix



$$e = 1.1a$$

$$\mu_I = 4\mu_M \quad c_I = 2c_M$$

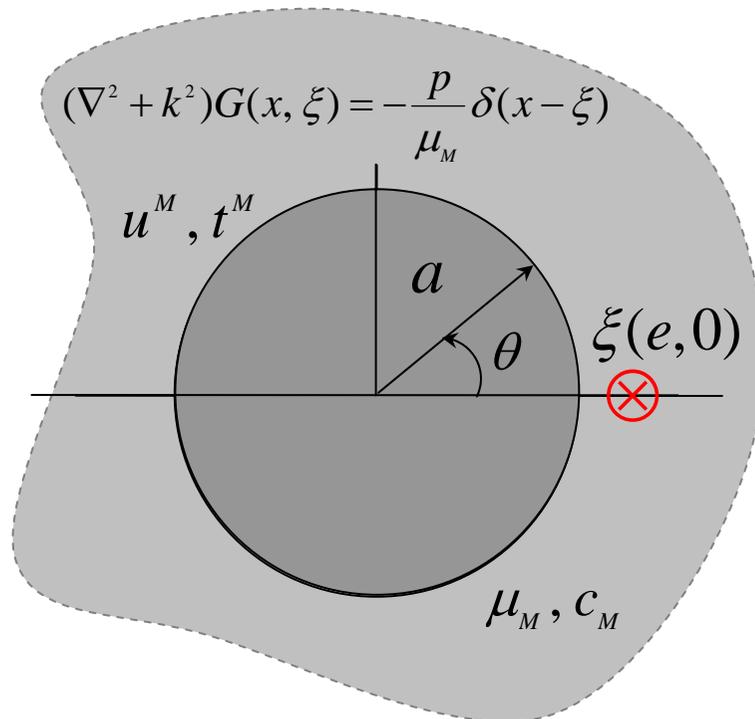
μ is the shear modulus

c is the wave speed

β is the imperfect interface parameter



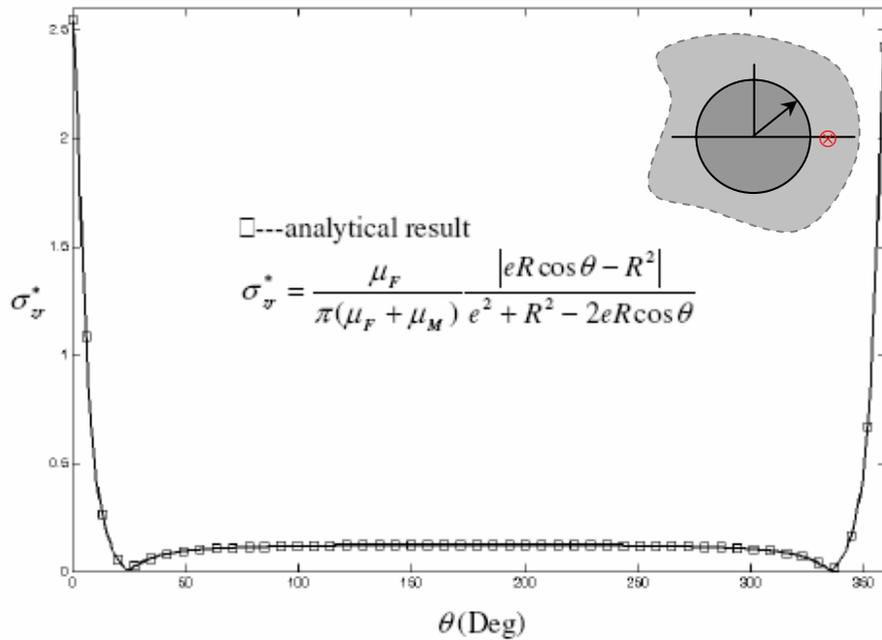
Take free body



u^I, t^I
 a
 θ
 μ_I, c_I
 $t^M = -\frac{\mu_I}{\mu_M} t^I$
 $t^I = \frac{\beta}{\mu_I} (u^M - u^I)$

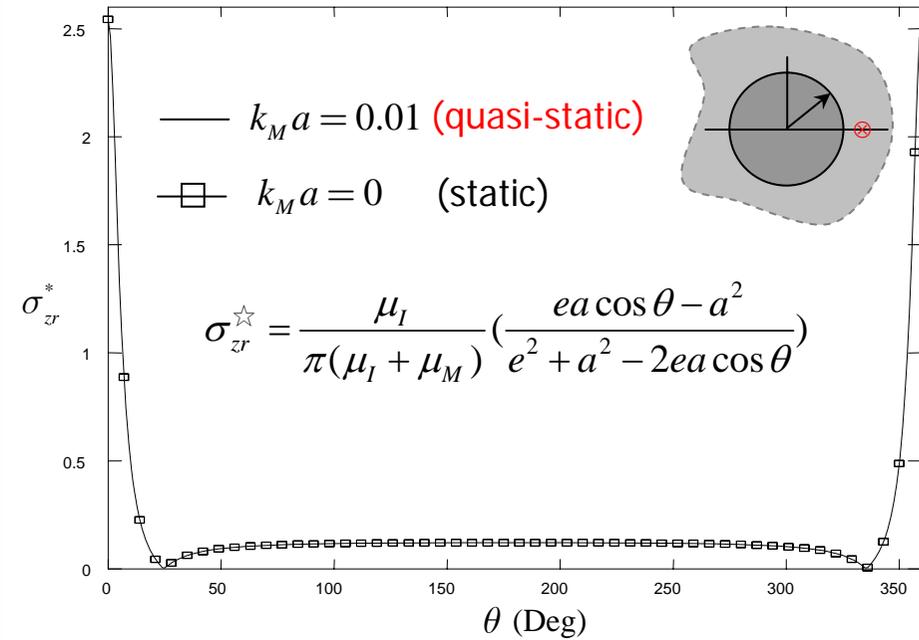
Distribution of σ_{zr}^* for the **quasi-static** ($k_M a = 0.01$) solution along the circular boundary

$$\sigma_{zr}^* = a \left| \sigma_{zr}^I \right| / p = a \left| \sigma_{zr}^M \right| / p$$



Wang and Sudak's solution

$$\sigma_{zr}^{\star} = a \sigma_{zr}^I / p = a \sigma_{zr}^M / p$$

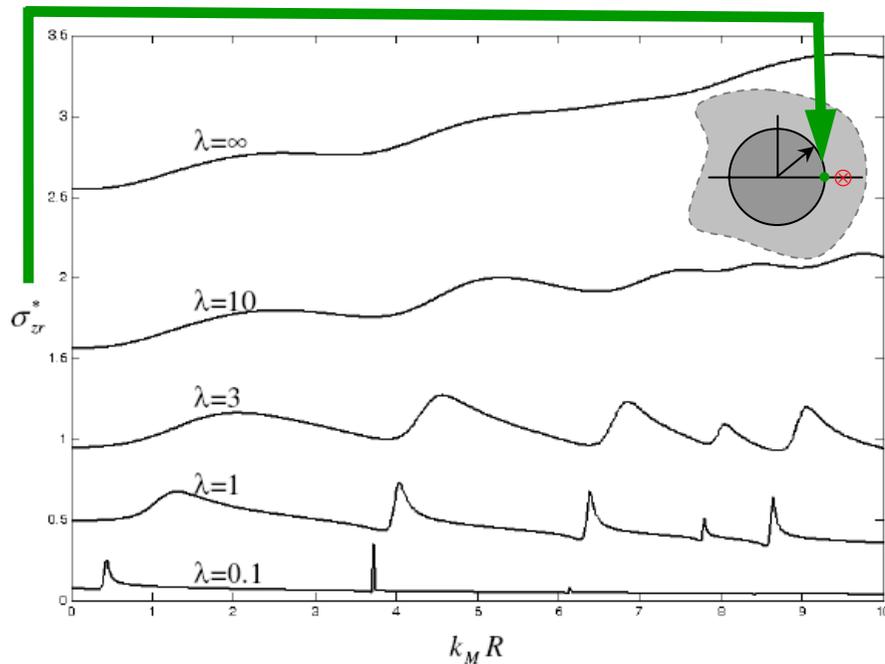


The present solution

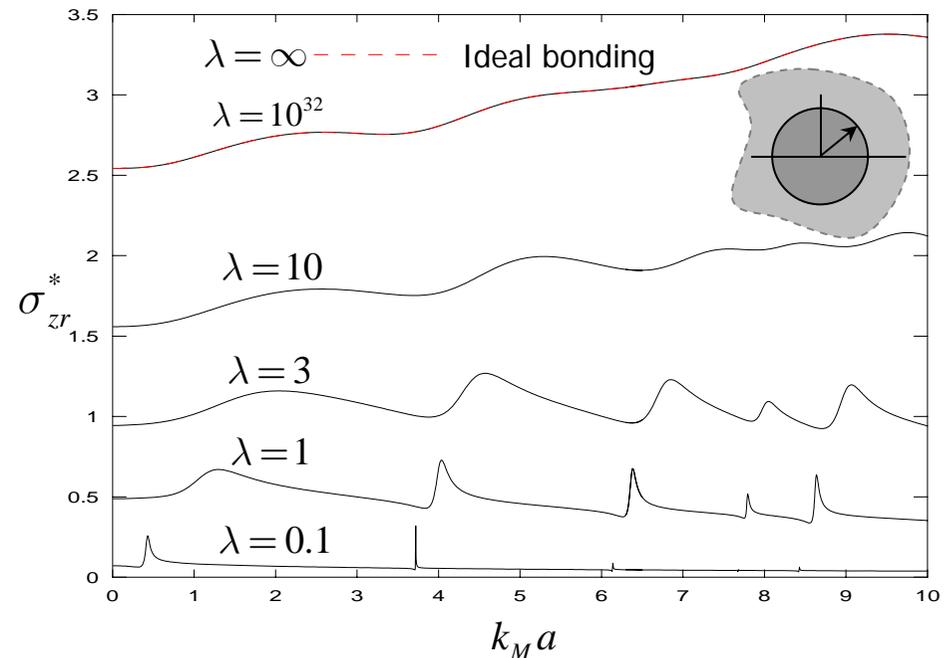
Parameter study of $\lambda = a\beta / \mu_M$ for the stress response

$$\sigma_{zr}^* = a |\sigma_{zr}^I| / p = a |\sigma_{zr}^M| / p$$

Bonding behavior



Wang and Sudak's solution



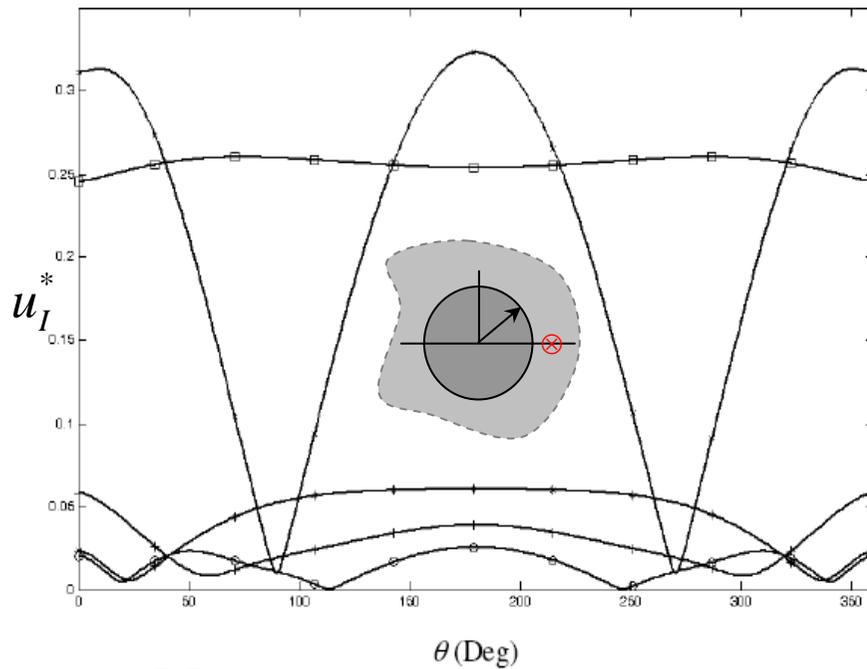
The present solution



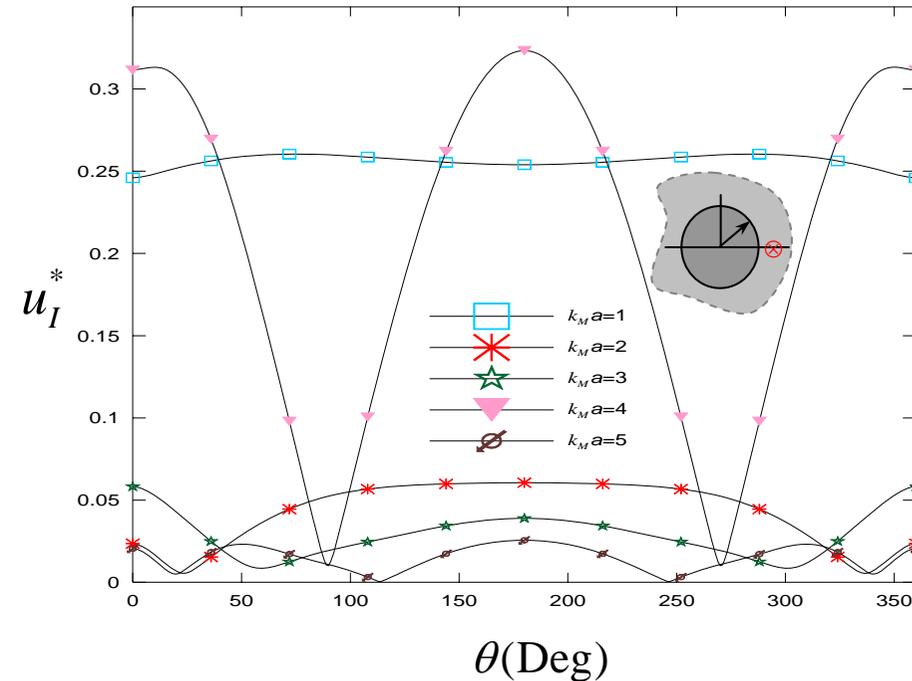
The distribution of displacement u_I^* along the circular boundary for the case ($k_M a = 1, 2, 3, 4, 5$)

$$u_I^* = \mu_M |u_I| / p$$

Dynamic effect



Wang and Sudak's solution

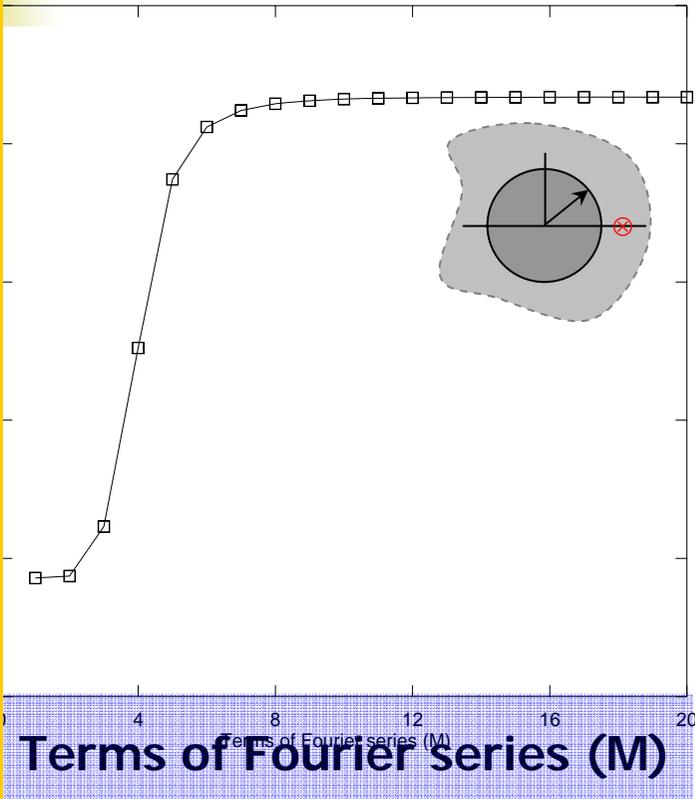


The present solution



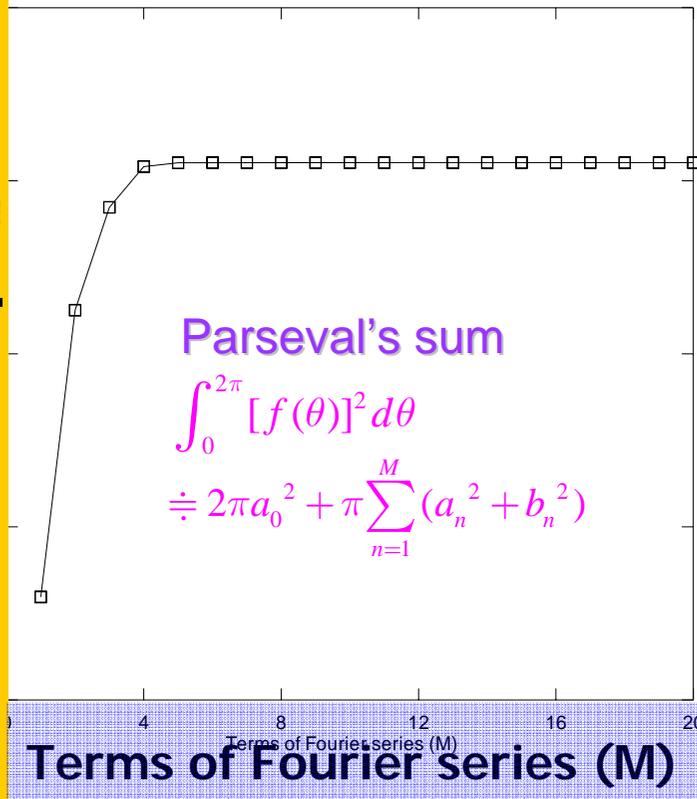
Test of convergence for the Fourier series with a concentrated force in the inclusion

Parseval's sum of real solution
for u_I^* ($k_M a = 4$)



real part

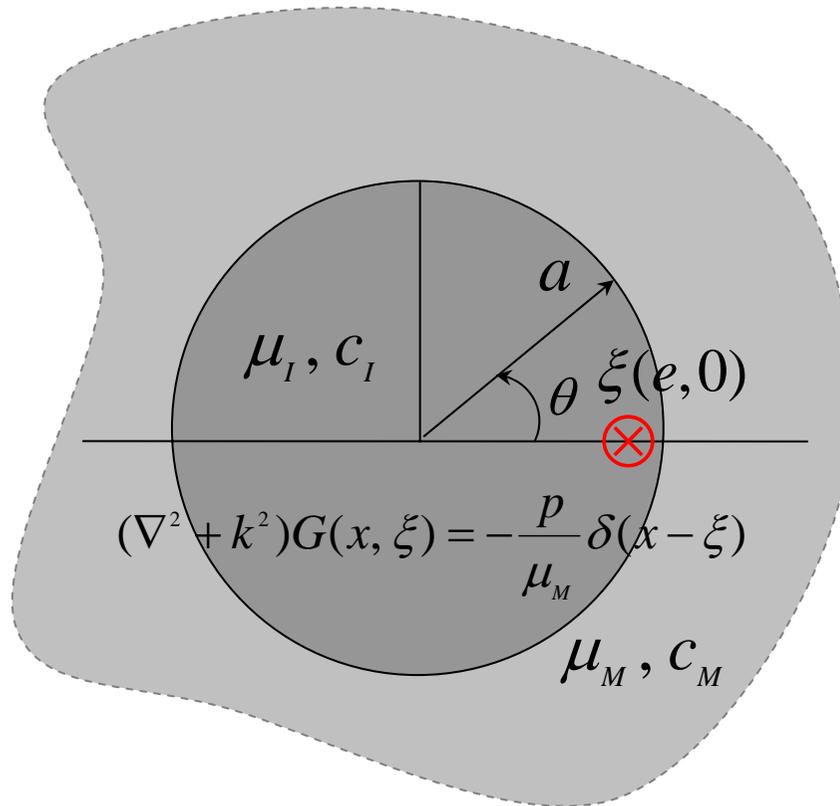
Parseval's sum of imaginary part
for u_I^* ($k_M a = 4$)



imaginary part



An infinite matrix containing a circular inclusion with a concentrated force at ξ in the inclusion



$$e = 0.9a$$

$$\mu_I = 4\mu_M, \quad c_I = 2c_M$$

μ is the shear modulus

c is the wave speed

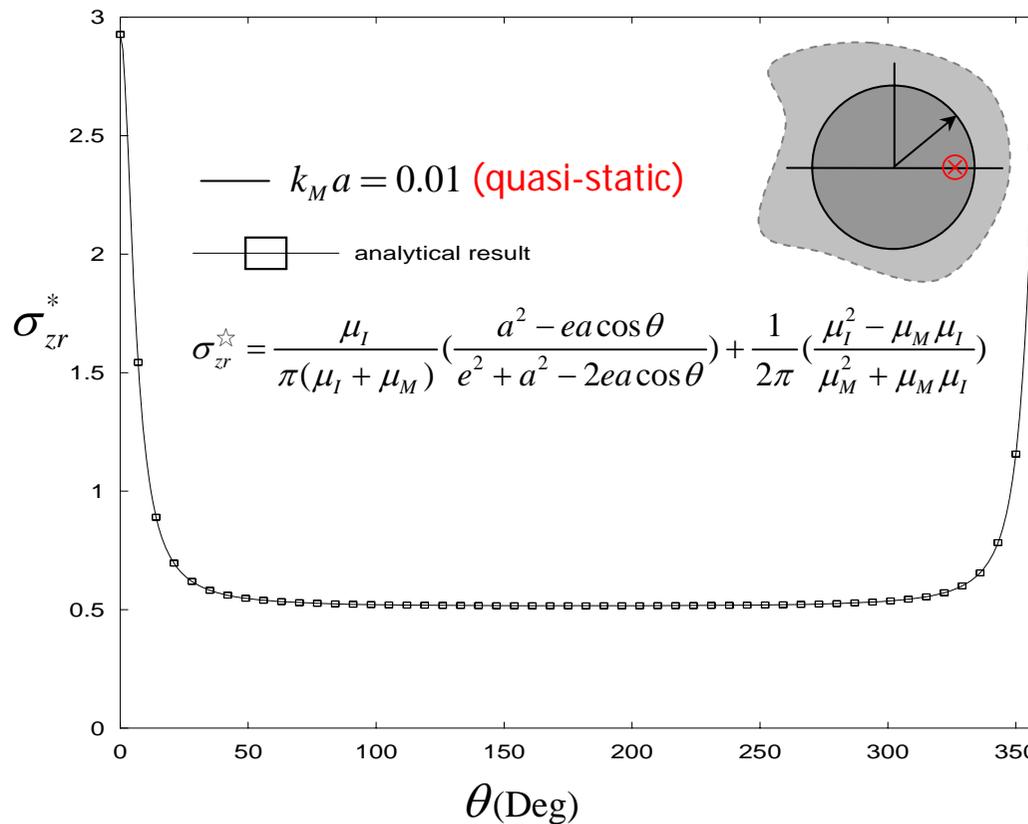
β is the imperfect interface parameter

$$t^M = -\frac{\mu_I}{\mu_M} t^I$$

$$t^I = \frac{\beta}{\mu_I} (u^M - u^I)$$



Distribution of σ_{zr}^* for the **quasi-static** ($k_M a = 0.01$) solution along the circular boundary ($e = 0.9a$)



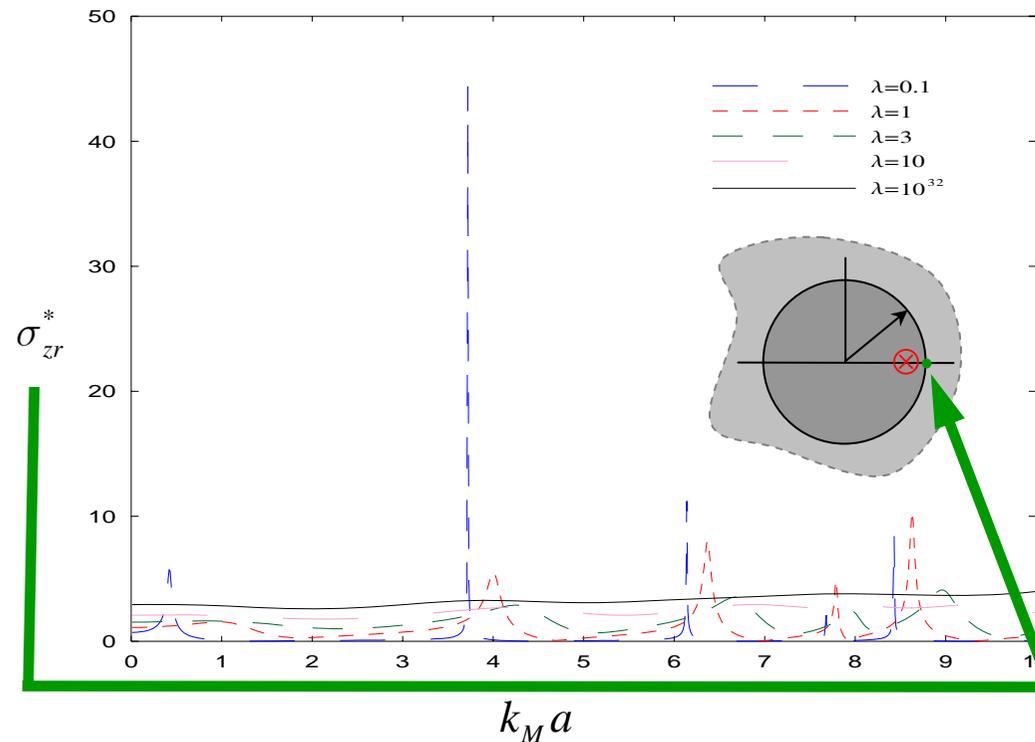
$$\sigma_{zr}^* = a |\sigma_{zr}^I| / p = a |\sigma_{zr}^M| / p$$

$$\sigma_{zr}^{\star} = a \sigma_{zr}^I / p = a \sigma_{zr}^M / p$$



Parameter study of $\lambda = a\beta / \mu_M$ for the stress response ($e = 0.9a$)

$$\sigma_{zr}^* = a |\sigma_{zr}^I| / p = a |\sigma_{zr}^M| / p$$

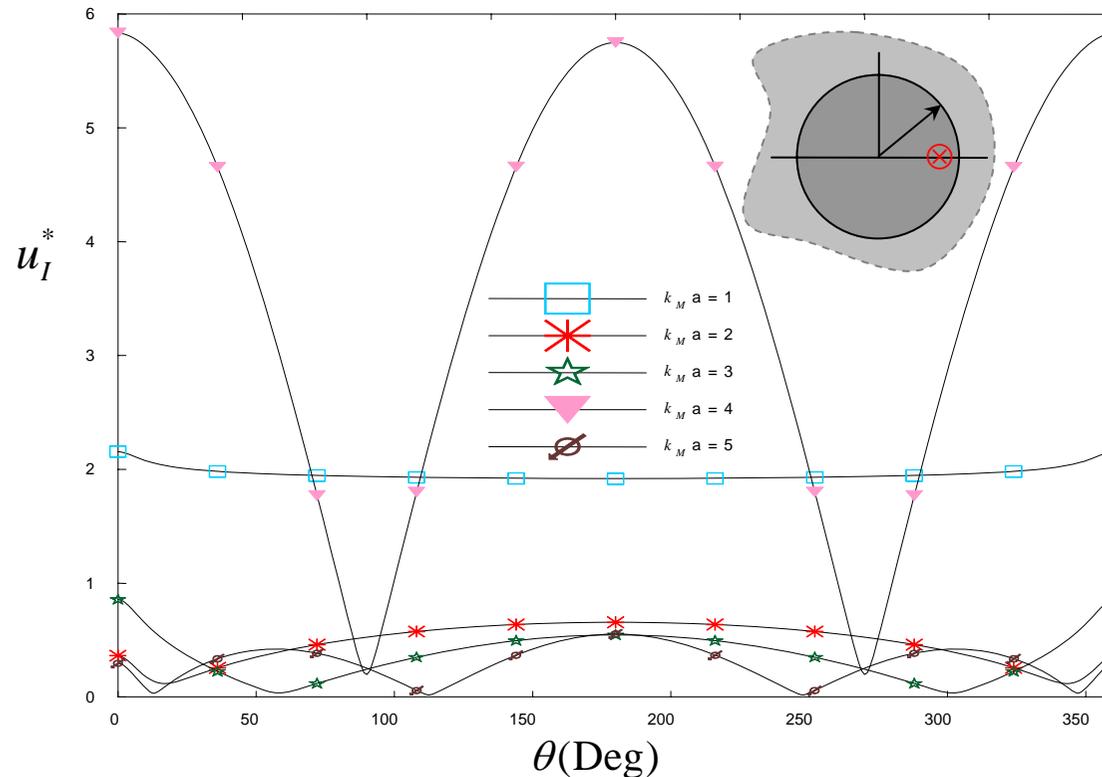


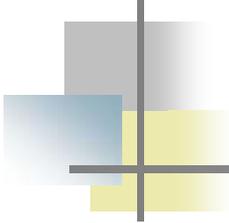
Bonding behavior



The distribution of displacement u_I^* along the circular boundary for the case of $\lambda=1$ ($e=0.9a$)

$$u_I^* = \mu_M |u_I| / p$$



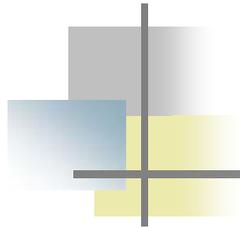


Numerical examples

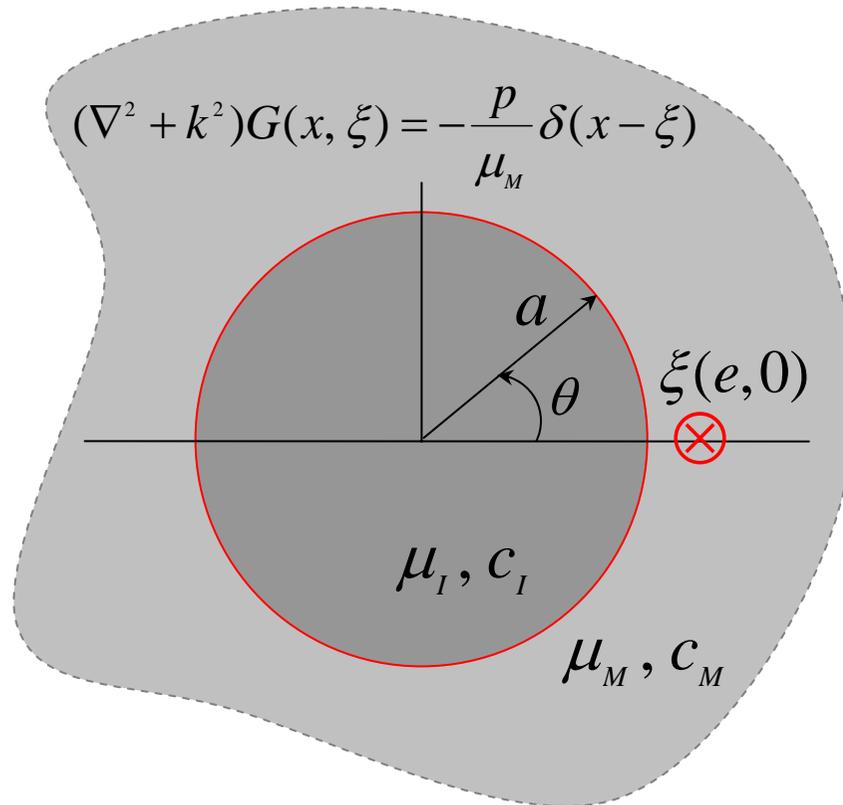
- Laplace problems
 - Eccentric ring
 - A half-plane with an aperture
 - (1) Dirichlet boundary condition
 - (2) Robin boundary condition
 - A half-plane problem with a circular hole and a half-circular inclusion
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 - An infinite matrix containing two circular inclusions with a concentrated force in the matrix



Special case of an ideally bonded case ($\beta = \infty$)



$$(\nabla^2 + k^2)G(x, \xi) = -\frac{p}{\mu_M} \delta(x - \xi)$$



$$t^M = -\frac{\mu_I}{\mu_M} t^I$$

$$t^I = \frac{\beta}{\mu_I} (u^M - u^I)$$

Imperfect bonding
 $(\beta \rightarrow \infty)$

 Ideal bonding

$$t^M = -\frac{\mu_I}{\mu_M} t^I$$

$$u^M = u^I$$

$$\mu_I = 4\mu_M$$

$$c_I = 2c_M$$

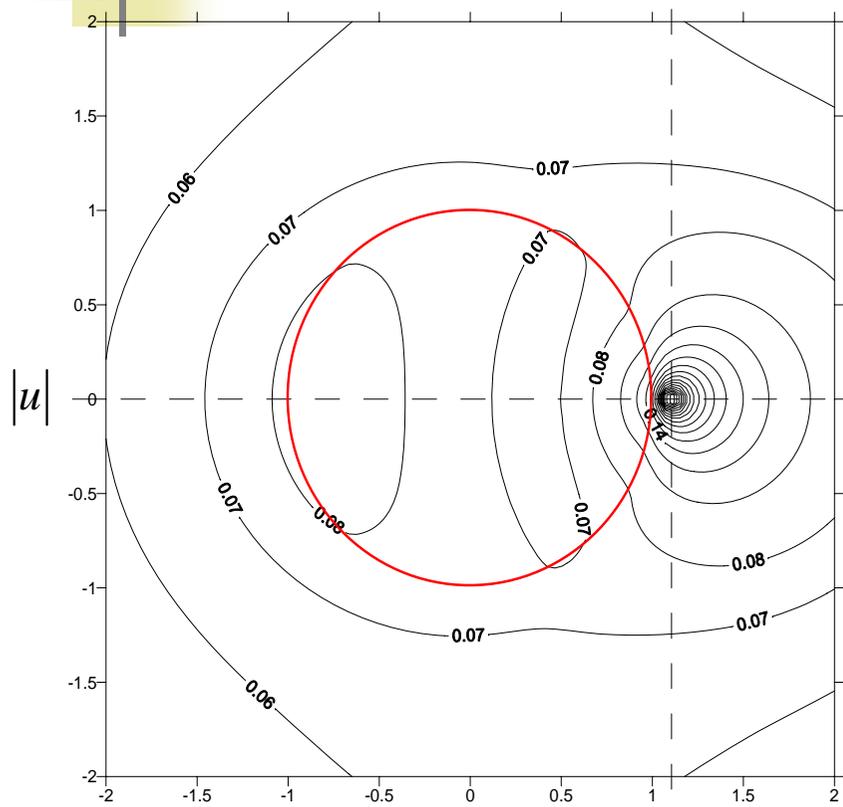
μ is the shear modulus

c is the wave speed

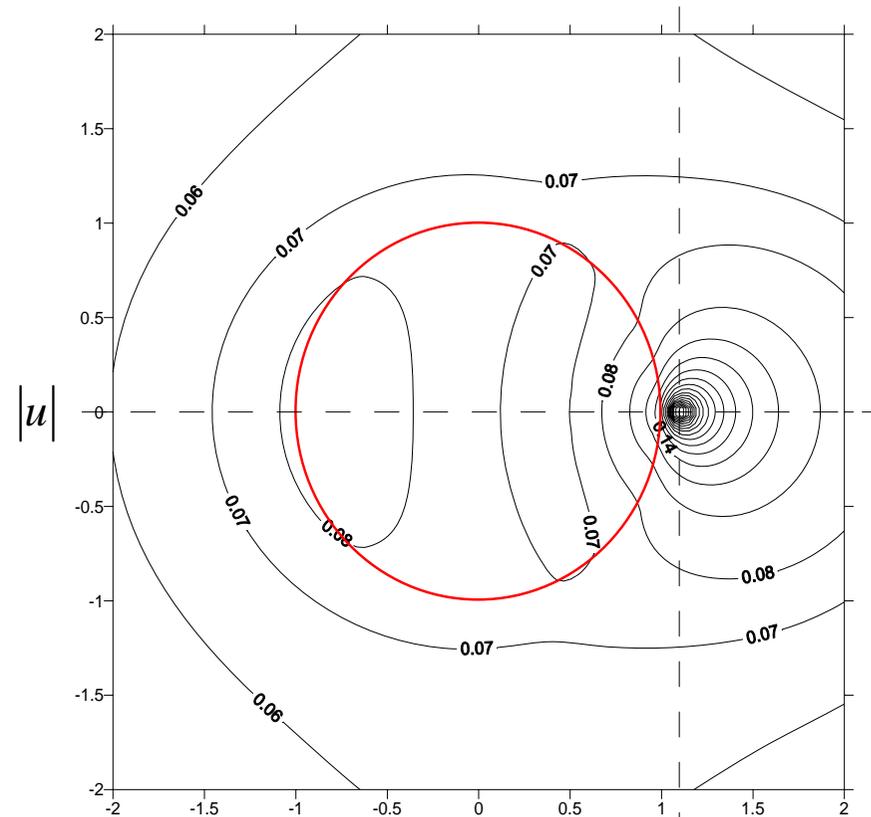
β is the imperfect interface parameter



The absolute amplitude of displacement by the present method



$\beta = \infty$ (ideal bonding interface)



$\beta = 10^{32}$



Special case of cavity ($\beta = 0$)

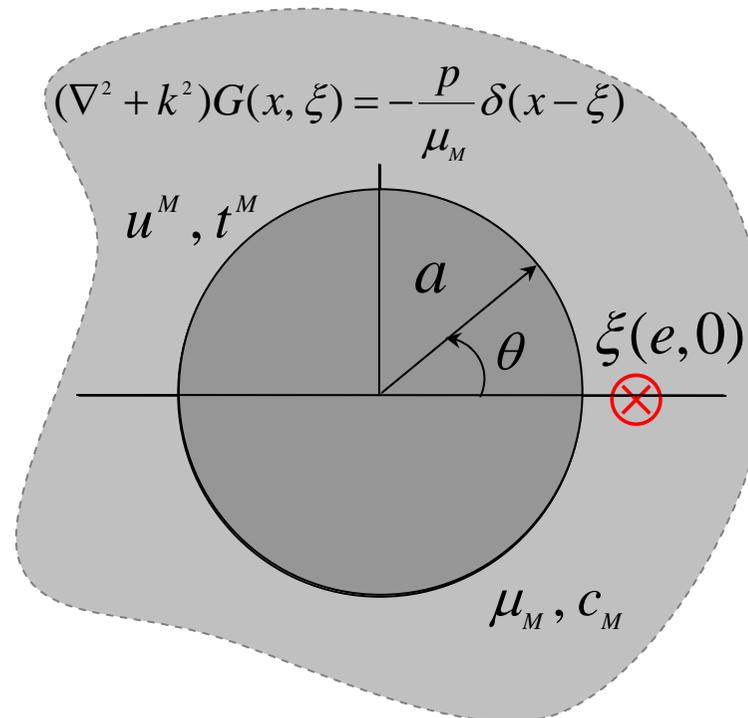
$$\mu_I = 4\mu_M$$

$$c_I = 2c_M$$

μ is shear modulus

c is wave speed

β is the imperfect interface parameter



$$t^M = -\frac{\mu_I}{\mu_M} t^I$$

$$t^I = \frac{\beta}{\mu_I} (u^M - u^I)$$

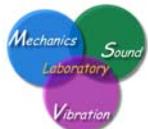


Imperfect bonding

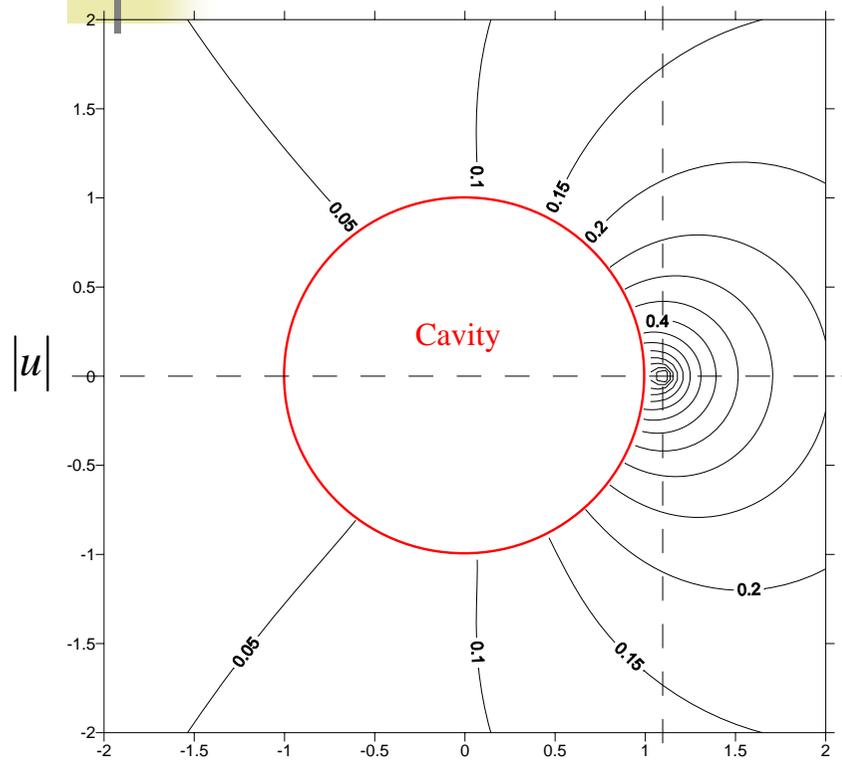
Cavity

$$t^M = 0$$

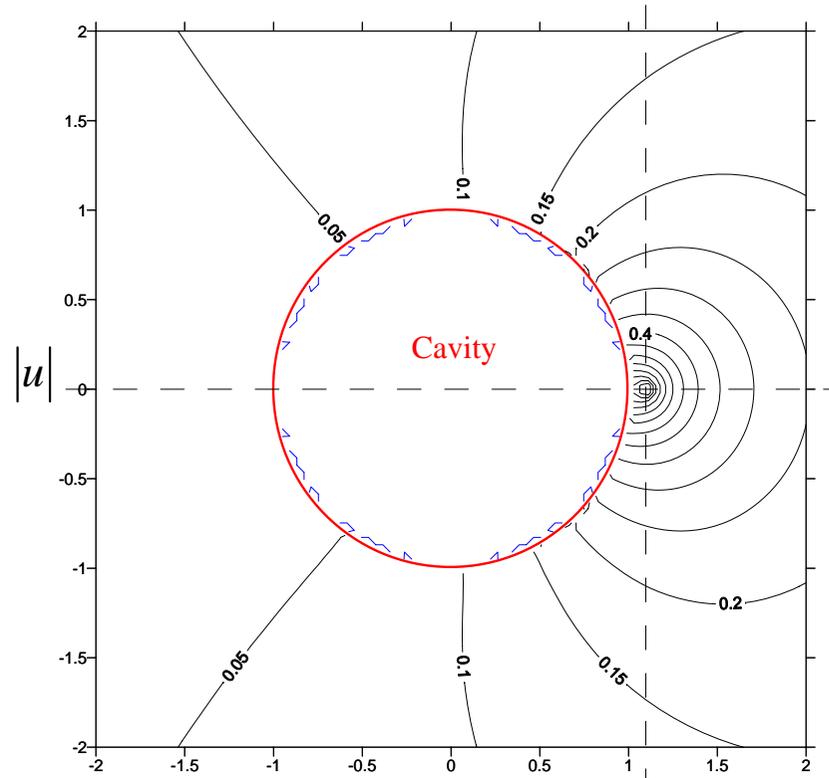
$$u^M = ?$$



The absolute amplitude of displacement by the present method



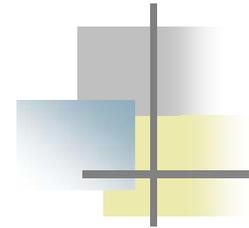
$\beta = 0$ (cavity)



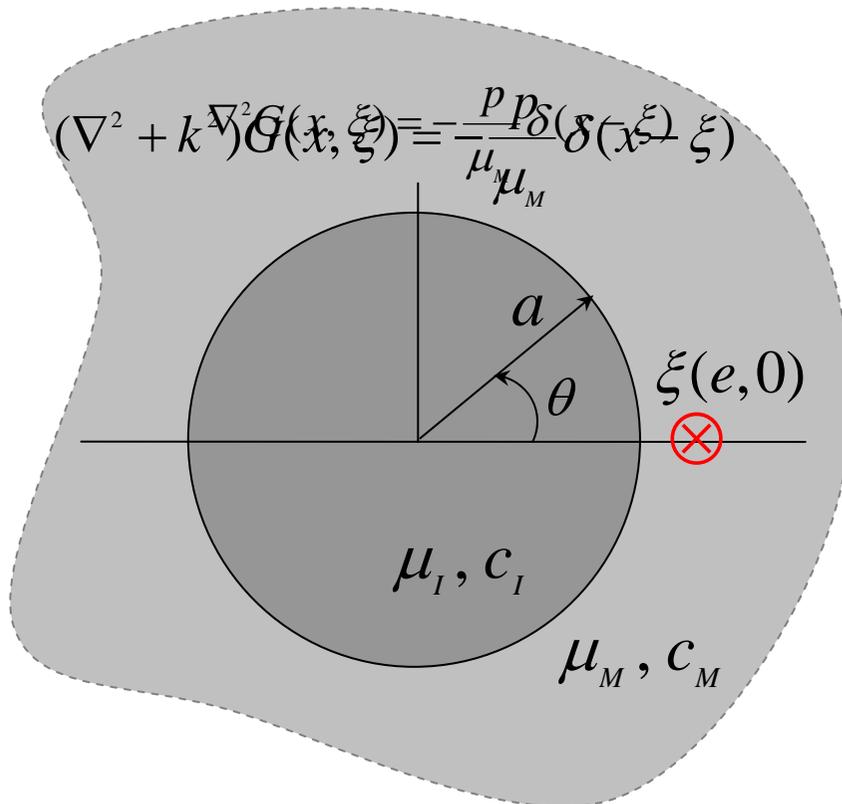
$\beta = 10^{-32}$



Parameter study ($k = 0$) for ideal bonding



$$(\nabla^2 + k^2)G(x, \xi) = -\frac{p}{\mu_I \mu_M} \delta(x - \xi)$$

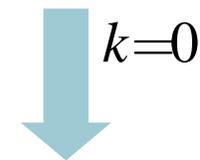


$$t^M = -\frac{\mu_I}{\mu_M} t^I$$

$$u^M = u^I$$

Fundamental solution

$$U(s, x) = -i\pi H_0^{(1)}(kr)/2$$



$$U(s, x) = \ln|x - s| = \ln r$$

$$\mu_I = 4\mu_M$$

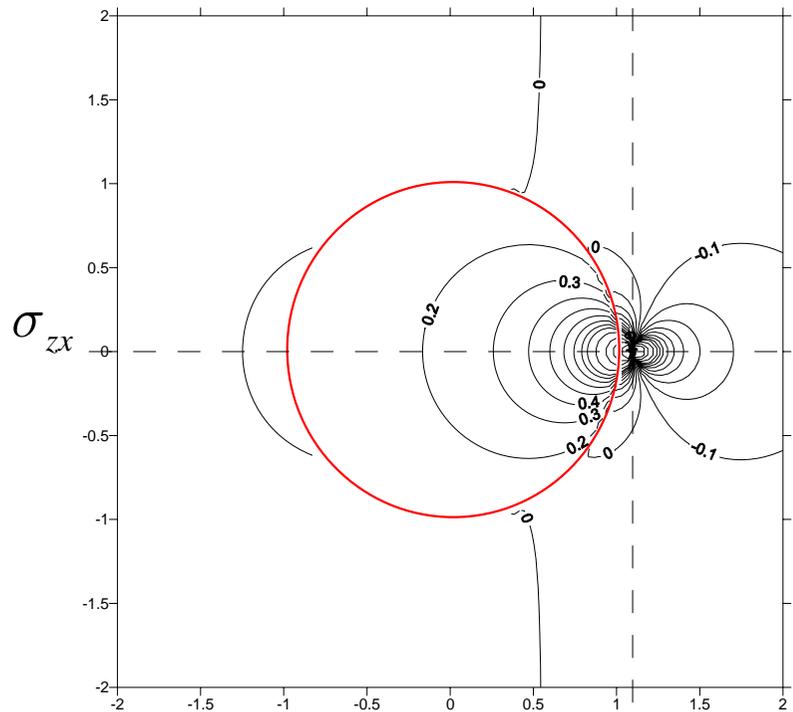
μ is the shear modulus

β is the imperfect interface parameter



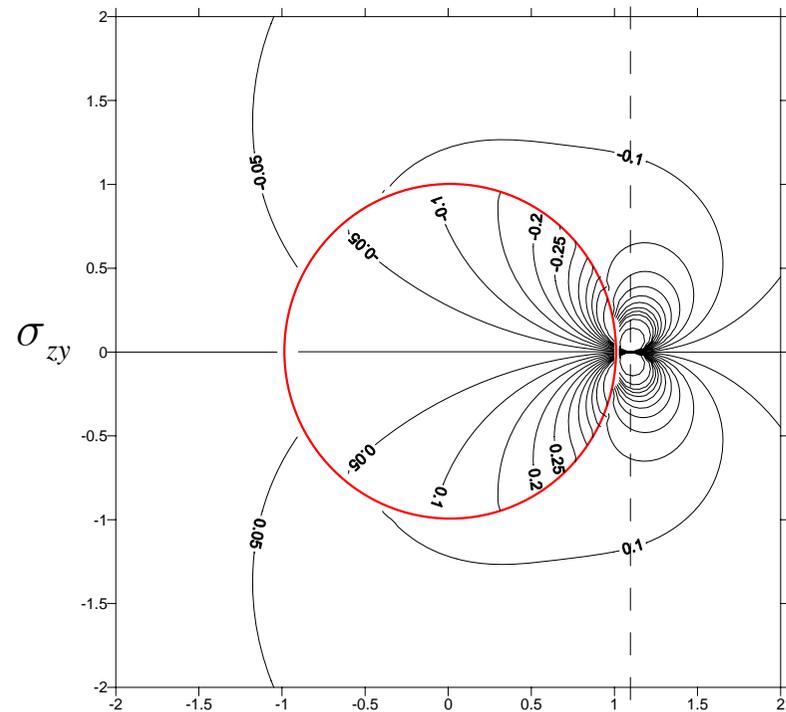
Stress contours of σ_{zx} and σ_{zy} for the static solutions (a concentrated force in the matrix)

$$\sigma_{zx} = \sigma_{zr} \cos \phi - \sigma_{z\theta} \sin \phi$$



$k = 0$, ideal bonding

$$\sigma_{zy} = \sigma_{zr} \sin \phi + \sigma_{z\theta} \cos \phi$$

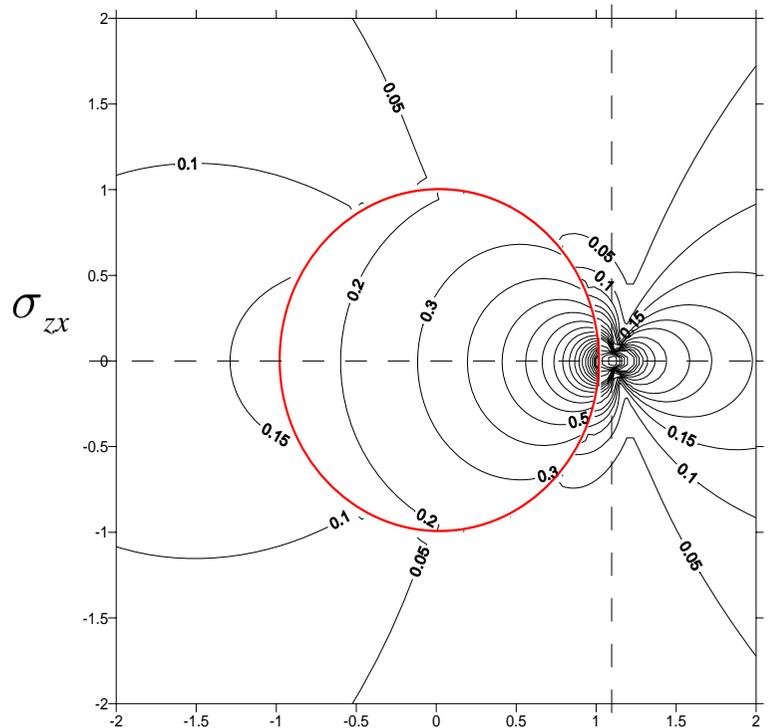


$k = 0$, ideal bonding



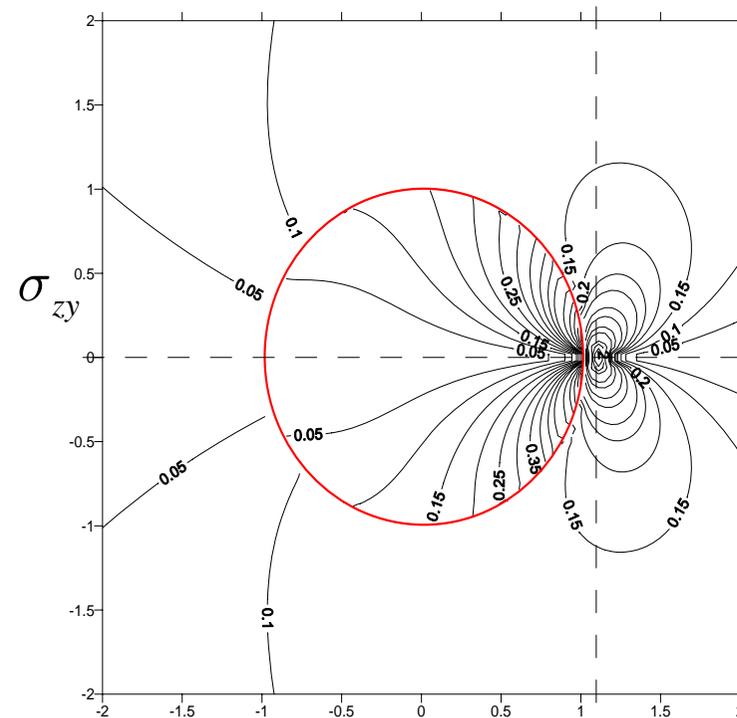
Stress contours of σ_{zx} and σ_{zy} for the dynamic solutions (a concentrated force in the matrix)

$$\sigma_{zx} = \sigma_{zr} \cos \phi - \sigma_{z\theta} \sin \phi$$



$$k_I = 1, k_M = 2, \beta = 10^{32} \text{ (ideal bonding)}$$

$$\sigma_{zy} = \sigma_{zr} \sin \phi + \sigma_{z\theta} \cos \phi$$



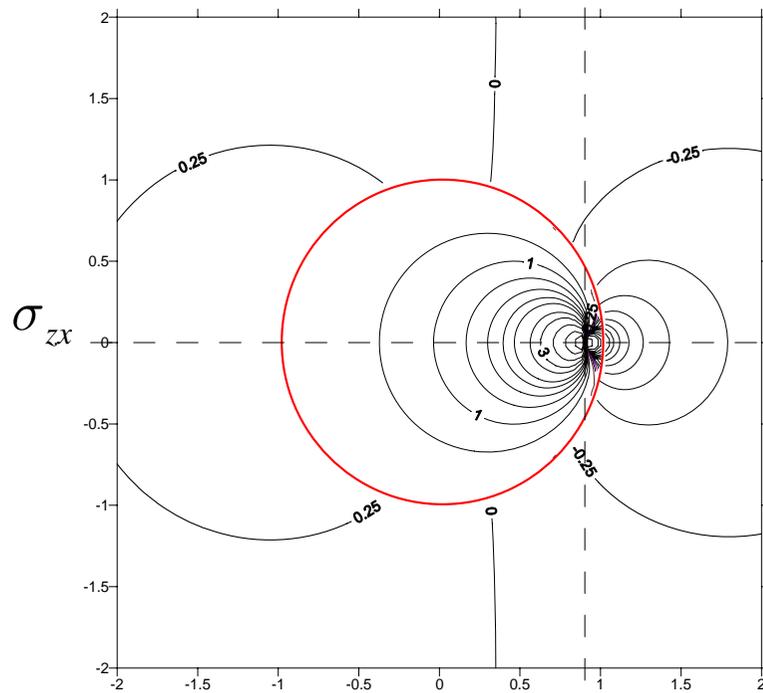
$$k_I = 1, k_M = 2, \beta = 10^{32} \text{ (ideal bonding)}$$



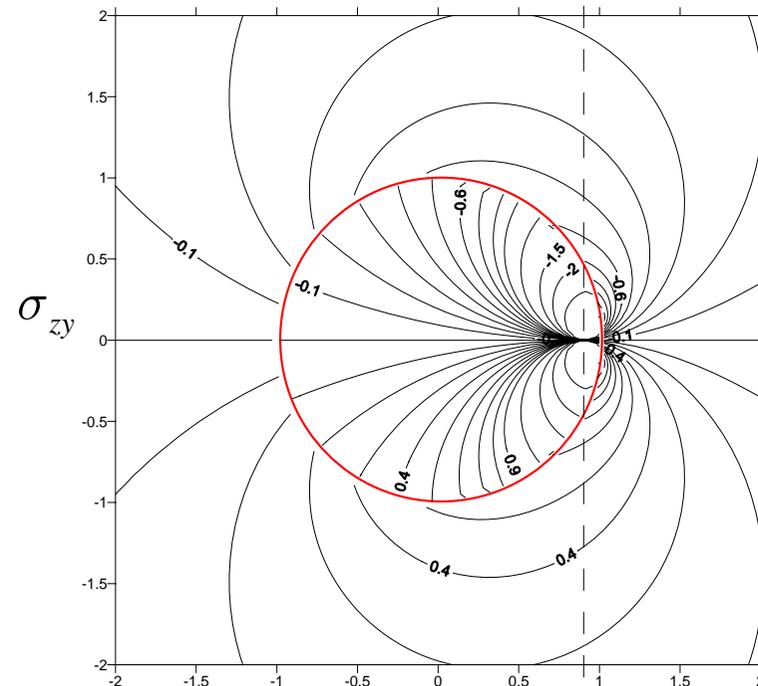
Stress contours of σ_{zx} and σ_{zy} for the static solutions (a concentrated force in the inclusion)

$$\sigma_{zx} = \sigma_{zr} \cos \phi - \sigma_{z\theta} \sin \phi$$

$$\sigma_{zy} = \sigma_{zr} \sin \phi + \sigma_{z\theta} \cos \phi$$



$k = 0, \text{ ideal bonding}$

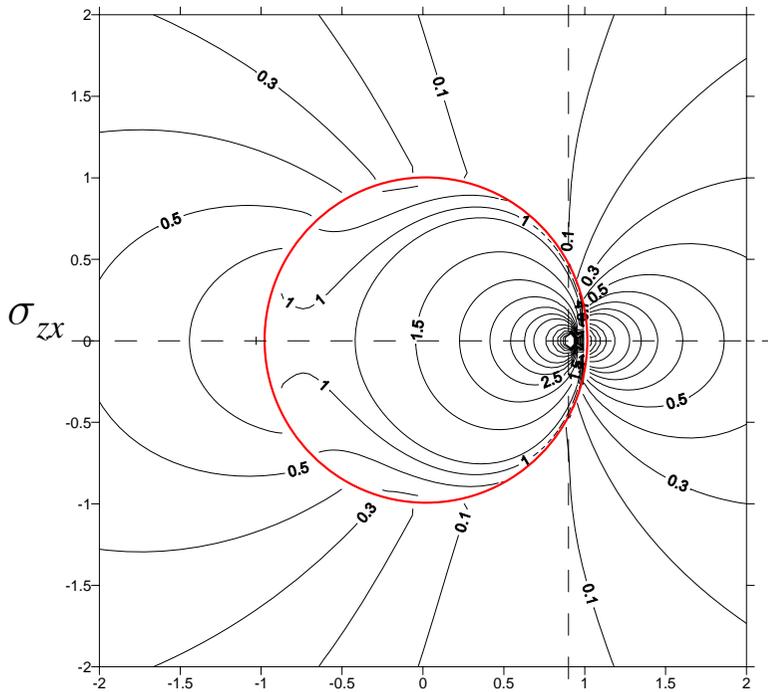


$k = 0, \text{ ideal bonding}$



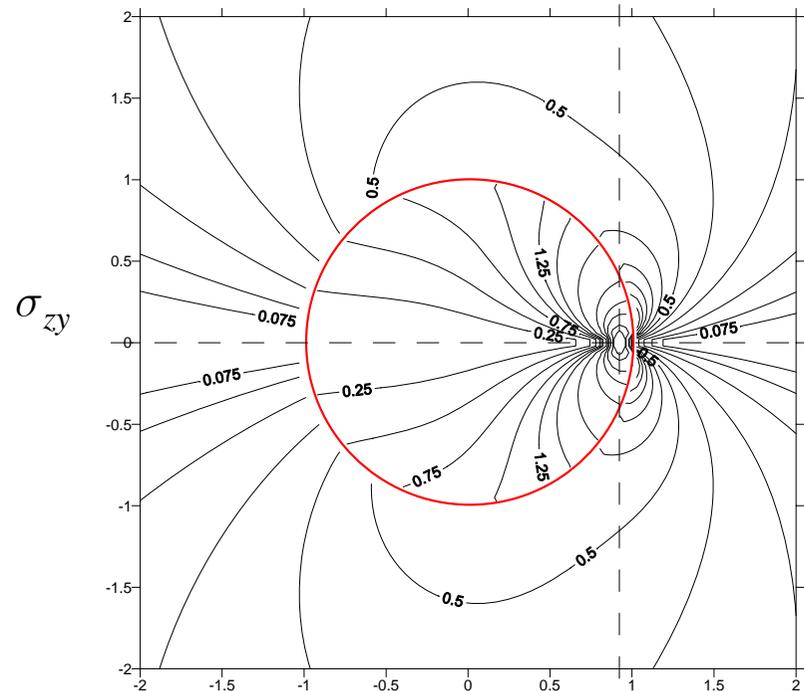
Stress contours of σ_{zx} and σ_{zy} for the **dynamic solutions** (a concentrated force in the inclusion)

$$\sigma_{zx} = \sigma_{zr} \cos \phi - \sigma_{z\theta} \sin \phi$$



$k_I = 1, k_M = 2, \beta = 10^{32}$ (ideal bonding)

$$\sigma_{zy} = \sigma_{zr} \sin \phi + \sigma_{z\theta} \cos \phi$$



$k_I = 1, k_M = 2, \beta = 10^{32}$ (ideal bonding)



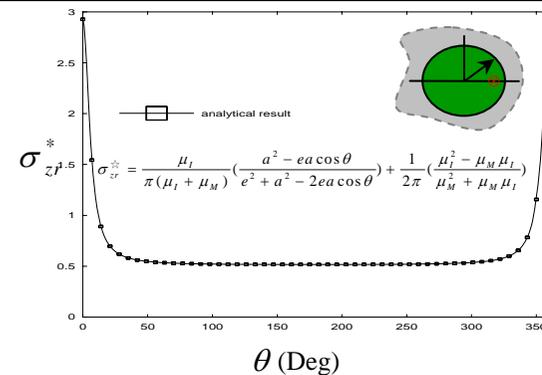
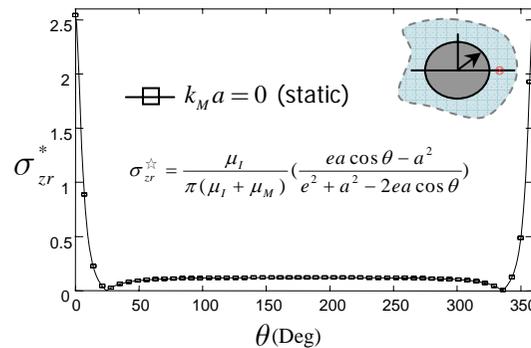
Series-form & closed-form solutions for the static case (ideally bonded interface)

$$\sigma_{zr}^{\star} = a\sigma_{zr}^I / p = a\sigma_{zr}^M / p$$

Concentrated force in the matrix

Concentrated force in the inclusion

Stress distribution along the interface



Closed-form solution

$$\sigma_{zr}^{\star} = \frac{\mu_I}{\pi(\mu_I + \mu_M)} \left(\frac{ea \cos \theta - a^2}{e^2 + a^2 - 2ea \cos \theta} \right)$$

$$\sigma_{zr}^{\star} = \frac{\mu_I}{\pi(\mu_I + \mu_M)} \left(\frac{a^2 - ea \cos \theta}{e^2 + a^2 - 2ea \cos \theta} \right)$$

Fourier series
(Poisson integral formula)

(easy)
↓
(not easy)

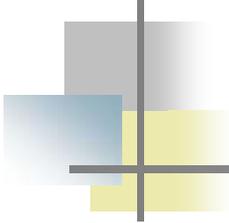
$$+ \frac{1}{2\pi} \left(\frac{\mu_I^2 - \mu_M \mu_I}{\mu_M^2 + \mu_M \mu_I} \right)$$

Series-form solution

$$\sigma_{zr}^{\star} = \frac{\mu_I}{\pi(\mu_I + \mu_M)} \sum_{m=1}^{\infty} \left(\frac{a}{e} \right)^m \cos m\theta$$

$$\sigma_{zr}^{\star} = \frac{\mu_I}{2\pi\mu_M} + \frac{\mu_I}{\pi(\mu_I + \mu_M)} \sum_{m=1}^{\infty} \left(\frac{e}{a} \right)^m \cos m\theta$$





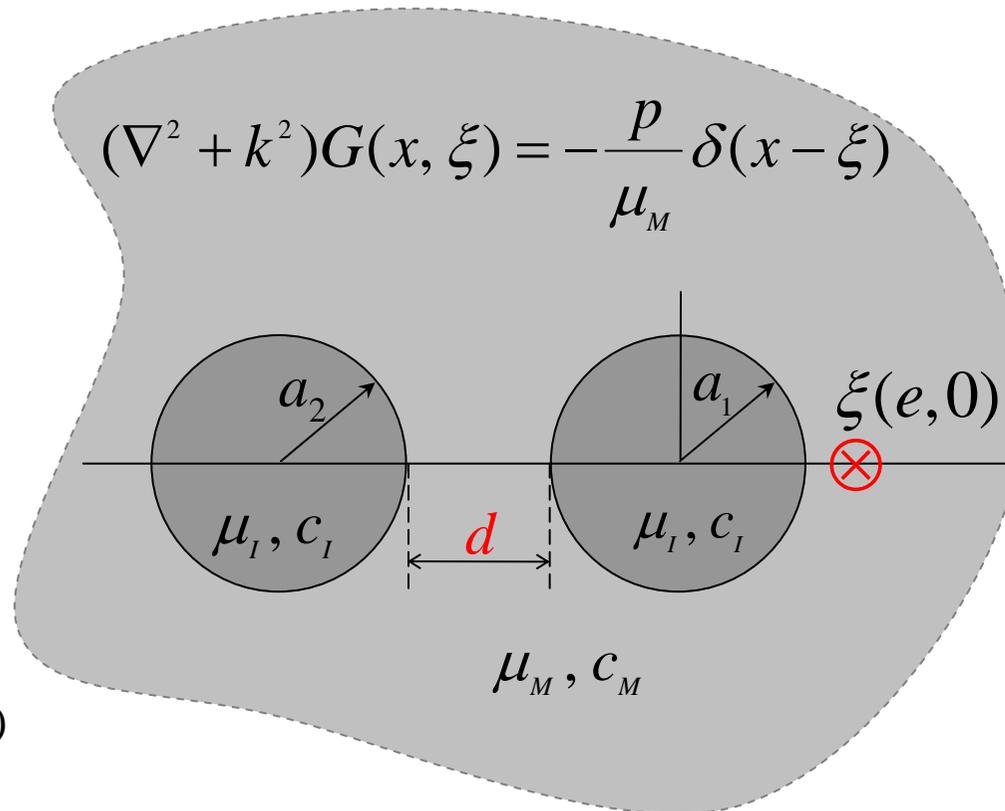
Numerical examples

- Laplace problems
 - Eccentric ring
 - A half-plane with an aperture
 - (1) Dirichlet boundary condition
 - (2) Robin boundary condition
 - A half-plane problem with a circular hole and a half-circular inclusion
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An infinite matrix containing **two circular inclusions** with a concentrated force at ξ in the matrix

$$(\nabla^2 + k^2)G(x, \xi) = -\frac{p}{\mu_M} \delta(x - \xi)$$



$$t^M = -\frac{\mu_I}{\mu_M} t^I$$

$$t^I = \frac{\beta}{\mu_I} (u^M - u^I)$$

$$\mu_I = 4\mu_M \quad c_I = 2c_M$$

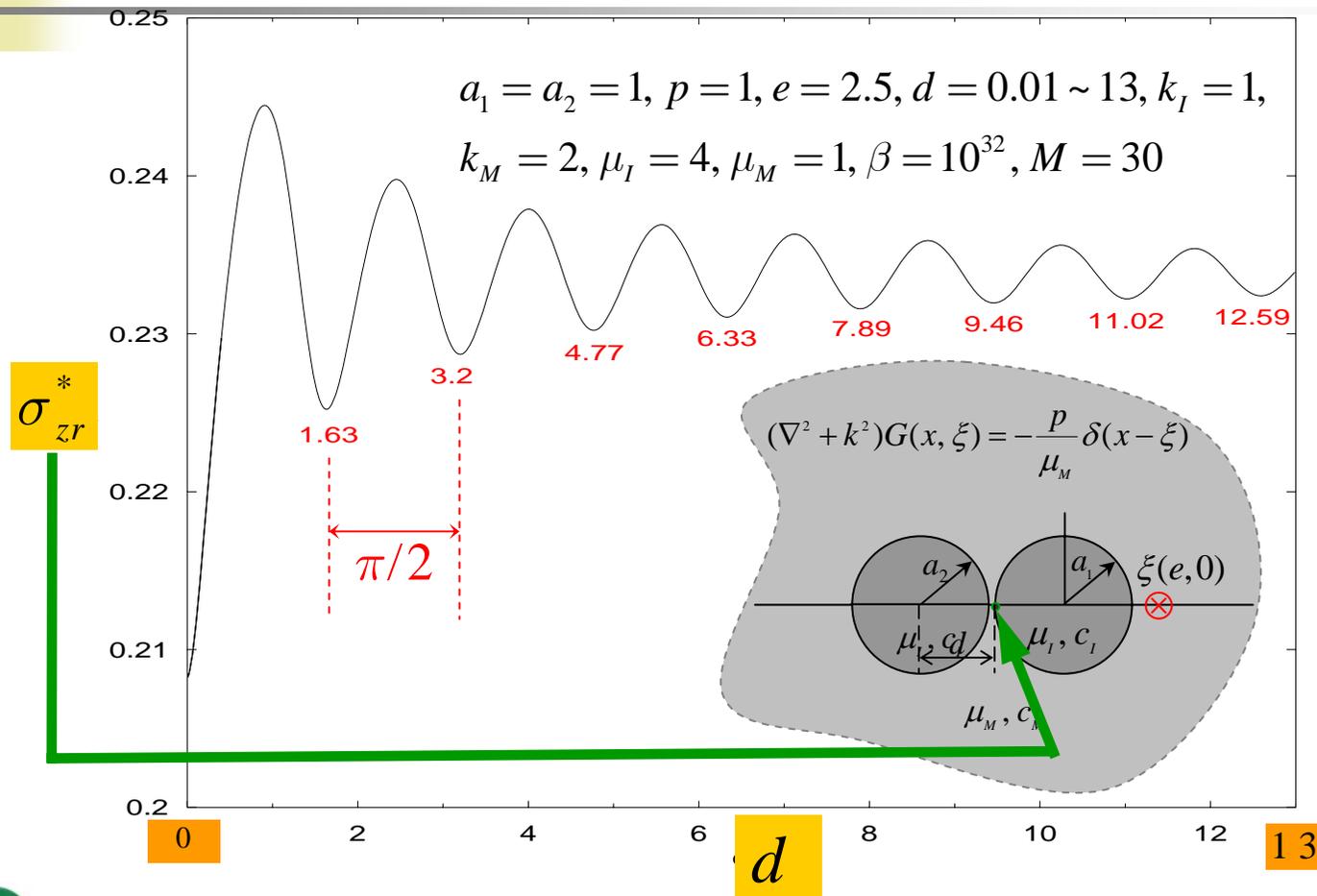
μ is the shear modulus

c is the wave speed

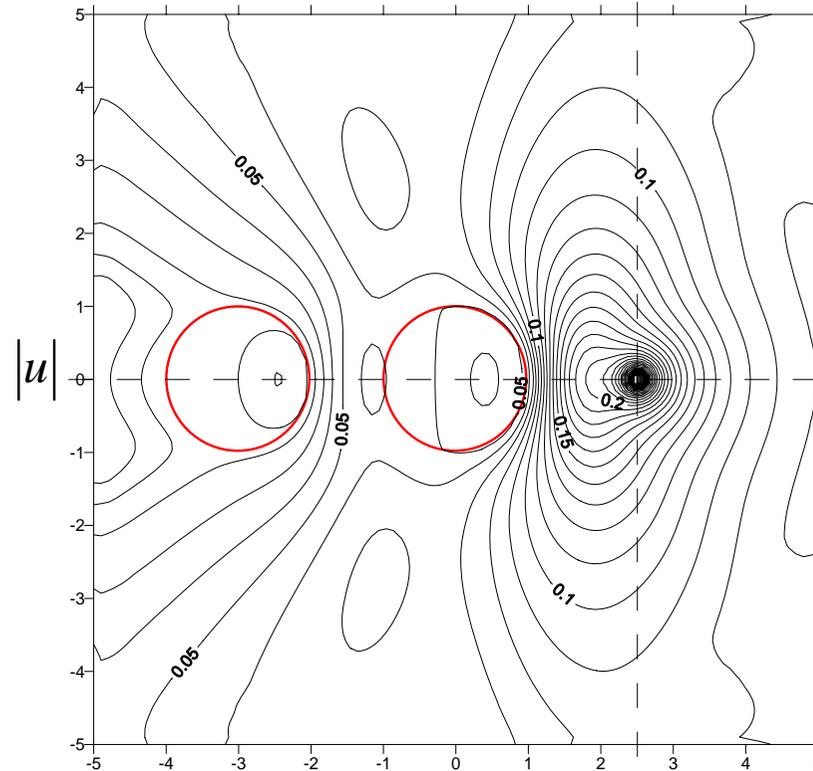
β is the imperfect interface parameter



Distribution of σ_{zr}^* of the matrix at the position of d various (a_1, π)



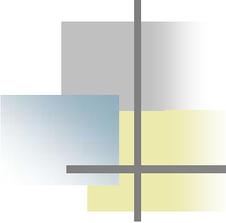
The contour of the displacement for an infinite matrix containing **two inclusions** with a concentrated force at ξ in the matrix for ideal bonding



Potential contour using the present method (M=30)

National Taiwan Ocean University
Department of Harbor and River Engineering





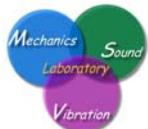
Outlines

- **Motivation and literature review**
- **Derivation of the Green's function**
 - Expansions of fundamental solution and boundary density
 - Adaptive observer system
 - Vector decomposition technique
 - Linear algebraic equation
 - Take free body
 - Image technique for solving half-plane problems
- **Numerical examples**
 - Green's function for Laplace problems
 - Green's function for Helmholtz problems
- **Conclusions**



Conclusions

- After introducing **the degenerate kernel**, the BIE is nothing more than **the linear algebra**.
- We derived the **analytic Green's function** for one inclusion problem by using the null-field integral equation. Also, the present approach can be utilized to construct **semi-analytic Green's functions** for several circular inclusions.



Conclusions

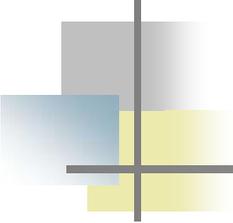
- Several examples, Laplace and Helmholtz problems were demonstrated to check the validity of the **present formulation** and **the results match well** with available solutions in the literature.
- A general-purpose program for deriving the Green's function of Laplace or Helmholtz problems **with arbitrary number of circular apertures and/or inclusions of arbitrary radii and various positions involving Dirichlet or Neumann or mixed boundary condition** was developed.



Further studies

- The imperfect circular interface is homogeneous  nonhomogeneous.
 $\beta \rightarrow \beta(\theta)$
- According to our successful experiences for half-plane problems, it is straightforward to quarter-plane problems.





The end

Thanks for your attentions.

You can get more information on our website.

<http://msvlab.hre.ntou.edu.tw>

