



Lectures on the Trefftz method, MFS (method of fundamental solutions) and image method for Laplace problems

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(LectureYoung.ppt)



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Outline

- **Introduction**
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- **Numerical results**
- **Conclusions**
- **References**

The simplest Trefftz method

Solve $y''(x) = 0$

subject to $y(0) = a, \quad y(1) = b$

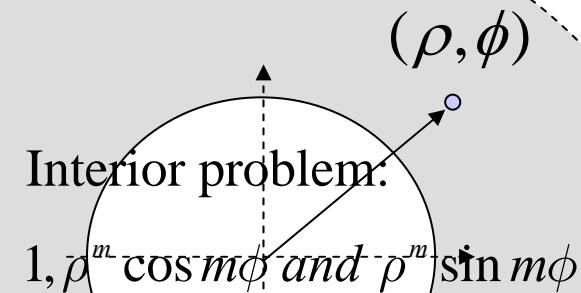
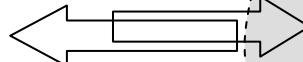
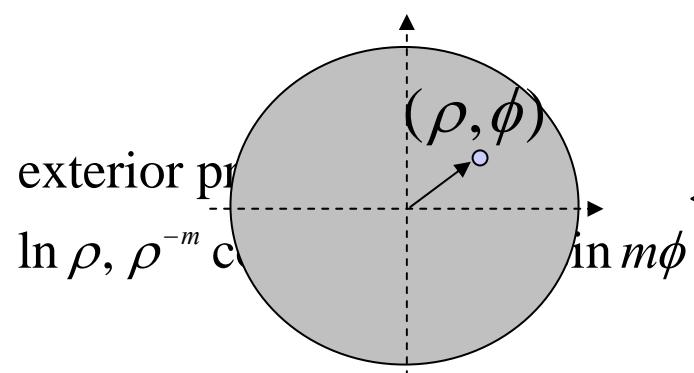
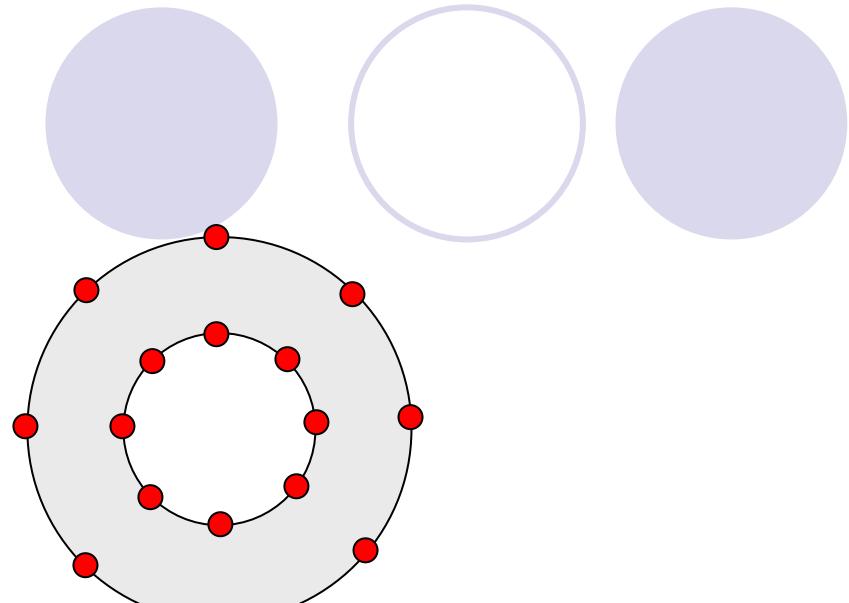
$$\Rightarrow y(x) = \sum_{i=1}^2 c_i \psi_i(x)$$

$$\left. \begin{array}{l} \psi_1(x) = 1 \\ \psi_2(x) = x \end{array} \right\} \Rightarrow \text{Trefftz base}$$

Trefftz method

$$u(x) = \sum_{j=1}^M c_j \Phi_j$$

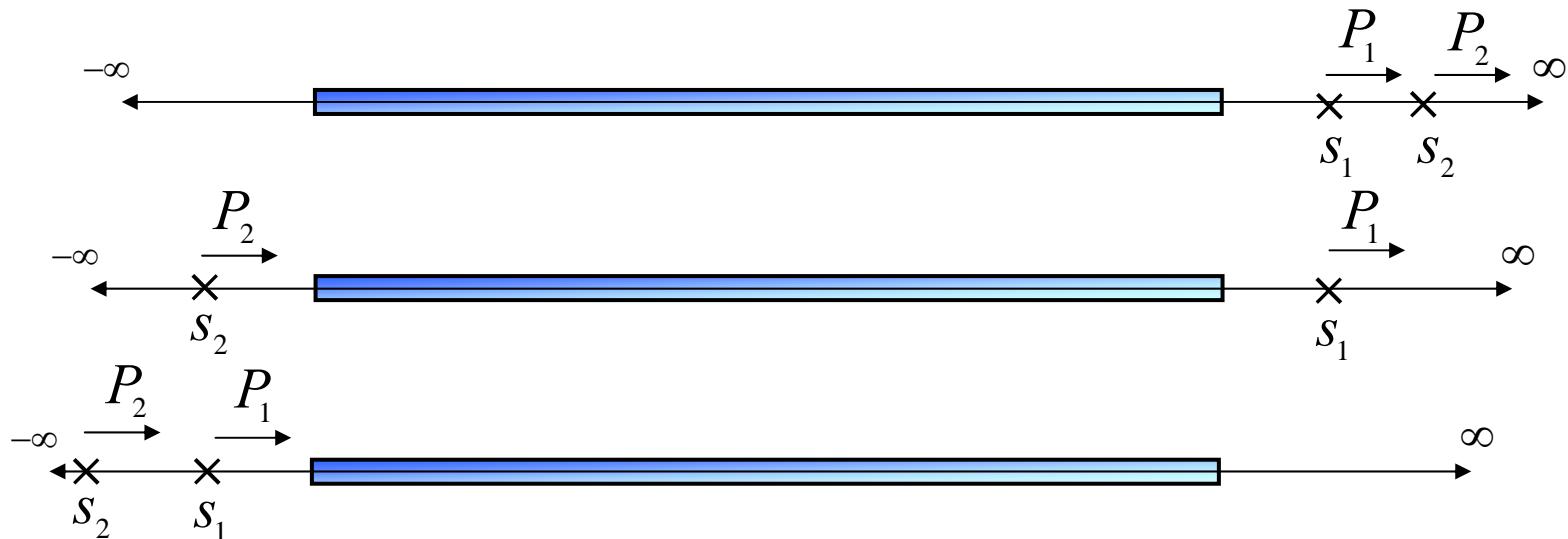
Φ_j is the j^{th} T-complete function



The simplest MFS

1-D Rod

$$u(x) = U(x, s_1)P_1 + U(x, s_2)P_2$$

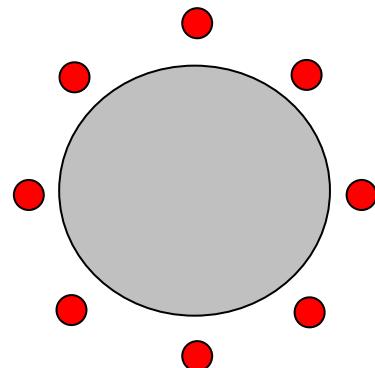



where $U(x,s)$ is the fundamental solution.

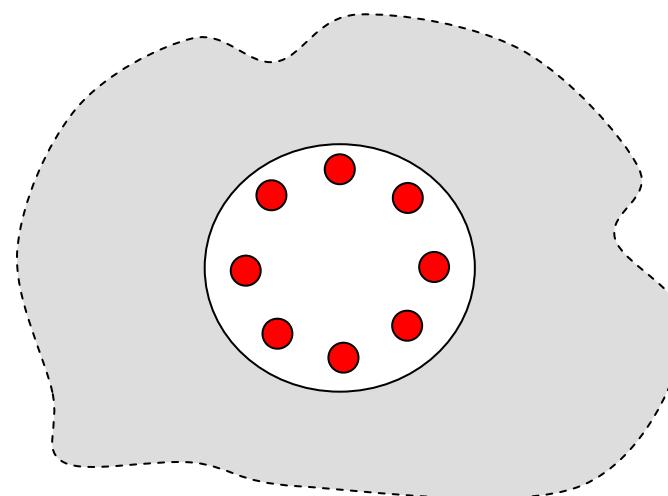
Method of Fundamental Solution (MFS)

$$u(x) = \sum_{j=1}^N w_j U(x, s_j)$$

Interior problem



exterior problem



$$U(x, s) = \ln r, r = |x - s_j|, j \in N$$

MFS: Theoretical Result

Alex Cheng's comments

- Bogomolny Error analysis
- Schaback Base equivalence
- Jeng-Tzong Chen Solution equivalence
- Zi-Cai Li, et al. Effective condition number
- D. L. Young and K. H. Chen MFS to the real boundary

Trefftz method and MFS

Method	Trefftz method	MFS
Definition	$u(x) = \sum_{j=1}^M c_j \Phi_j$	$u(x) = \sum_{j=1}^N w_j U(x, s_j)$
Figure caption	<p>A 2D coordinate system with axes. A shaded region labeled D represents the domain. A point x is marked inside D, and a value $u(x)$ is indicated at that point.</p>	<p>A 2D coordinate system with axes. A shaded region labeled D represents the domain. A point x is marked outside D. A dashed circle labeled r represents the distance from x to the boundary of D. A value $u(x)$ is indicated at point x.</p>
Base	Φ_j , (T-complete function)	$U(x, s) = \ln r$, $r = x-s $
G. E.	$\nabla^2 u(x) = 0$	$\nabla^2 u(x) = 0$
Match B. C.	<i>Determine c_j</i>	<i>Determine w_j</i>
M is the number of complete functions N is the number of source points in the MFS		

The simplest image method

1-D String

$$x = 0$$



$$x$$

$$x = 0$$

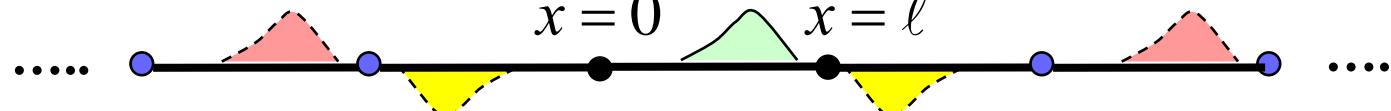
fixed end



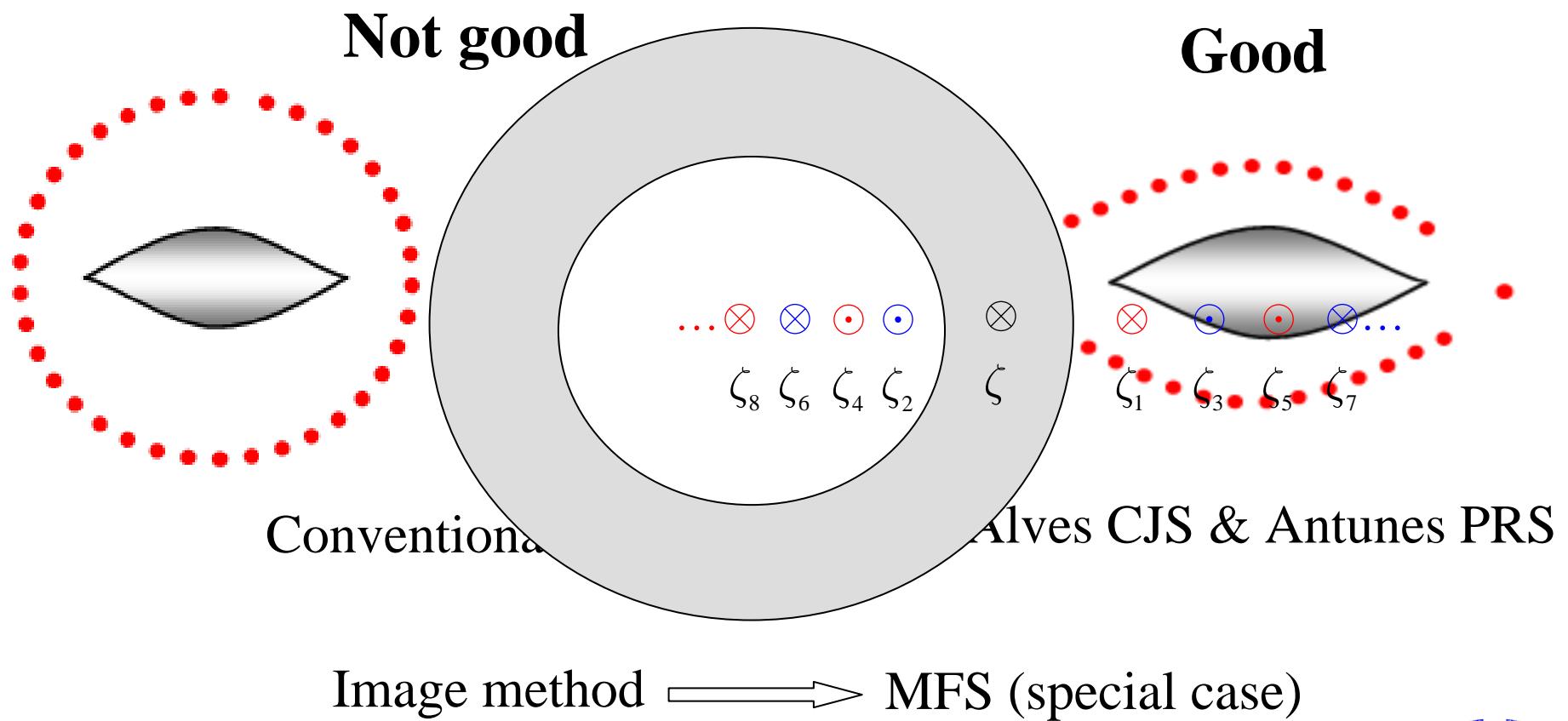
$$x$$

$$x = 0$$

$$x = \ell$$

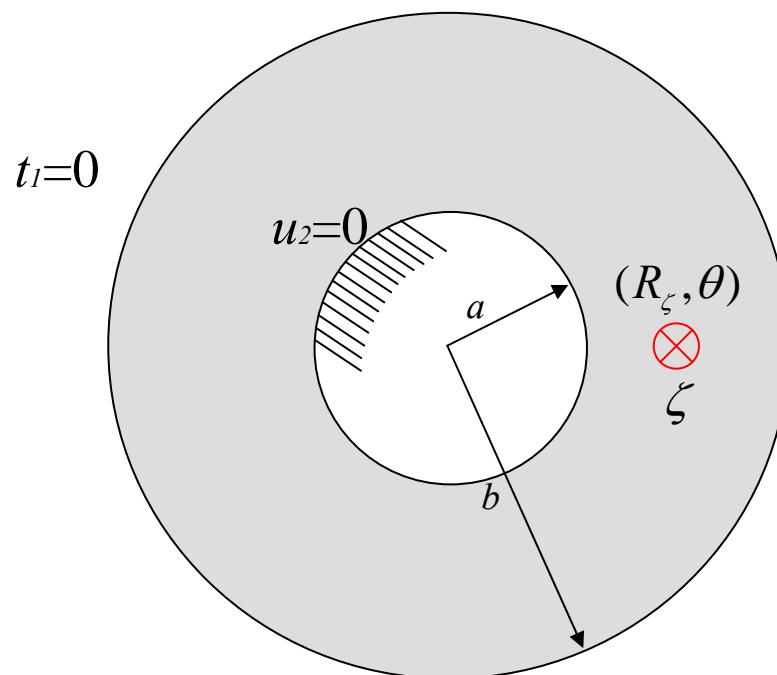


Optimal source location



Illustrative examples

Case 1 Fixed-free annular problem



Governing equation :

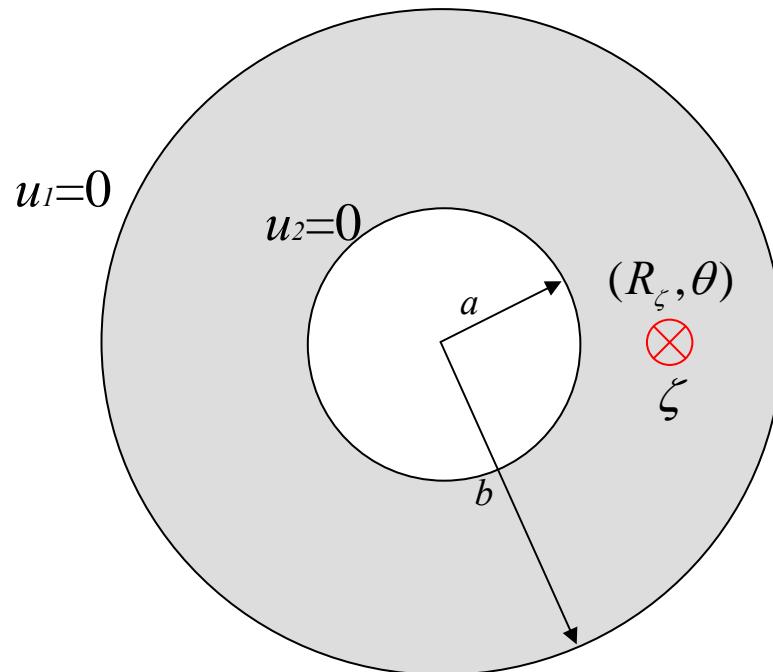
$$\nabla^2 G(x, \zeta) = \delta(x - \zeta), x \in \Omega$$

Boundary condition :

Fixed-free boundary

Illustrative examples

Case 2 Fixed-fixed annular problem



Governing equation :

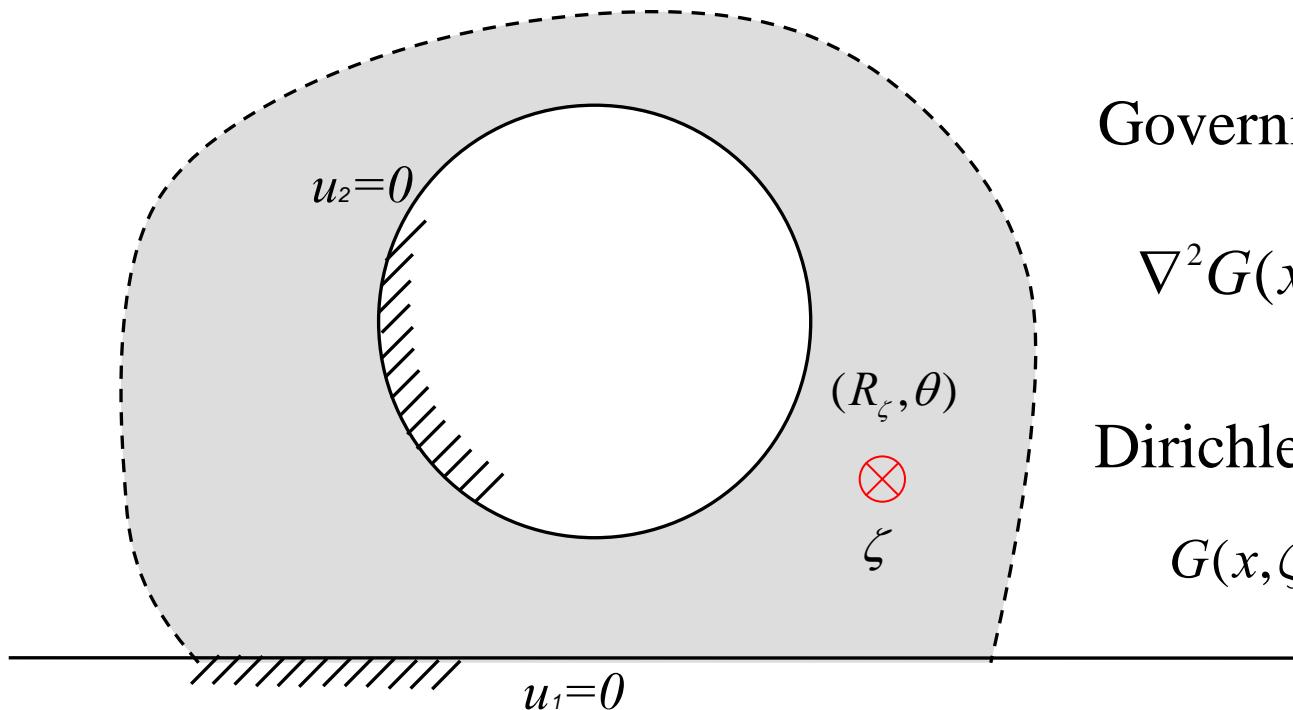
$$\nabla^2 G(x, \zeta) = \delta(x - \zeta), x \in \Omega$$

Boundary condition :

Fixed-fixed boundary

Illustrative examples

Case 3 Half-plane problem



Governing equation :

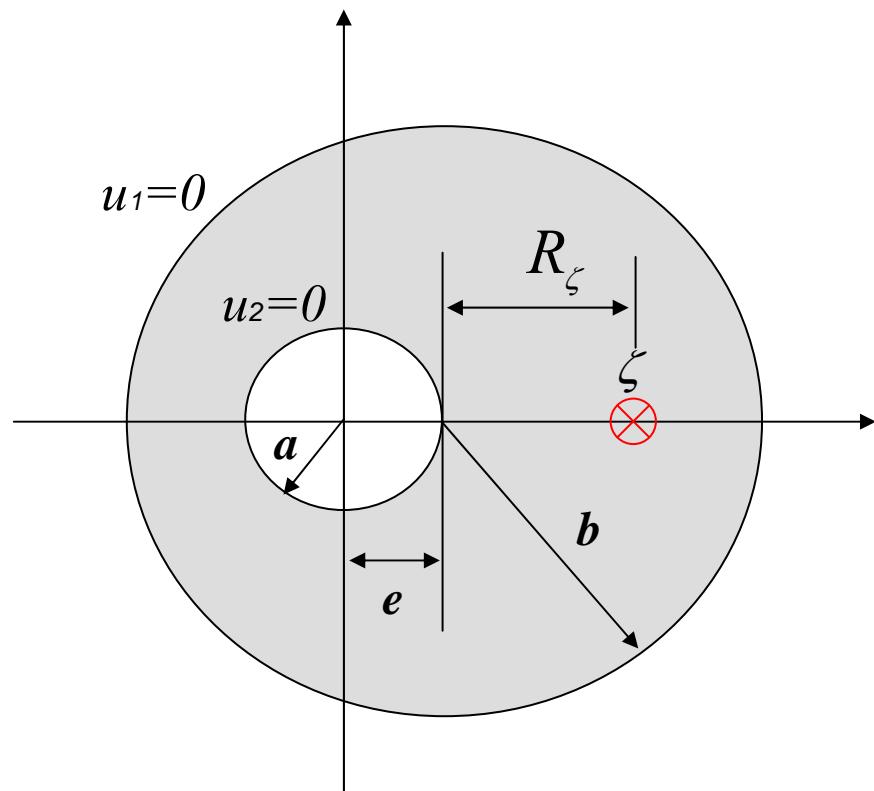
$$\nabla^2 G(x, \zeta) = \delta(x - \zeta), x \in \Omega$$

Dirichlet boundary condition :

$$G(x, \zeta) = 0, x \in B$$

Illustrative examples

Case 4 Eccentric problem



Governing equation :

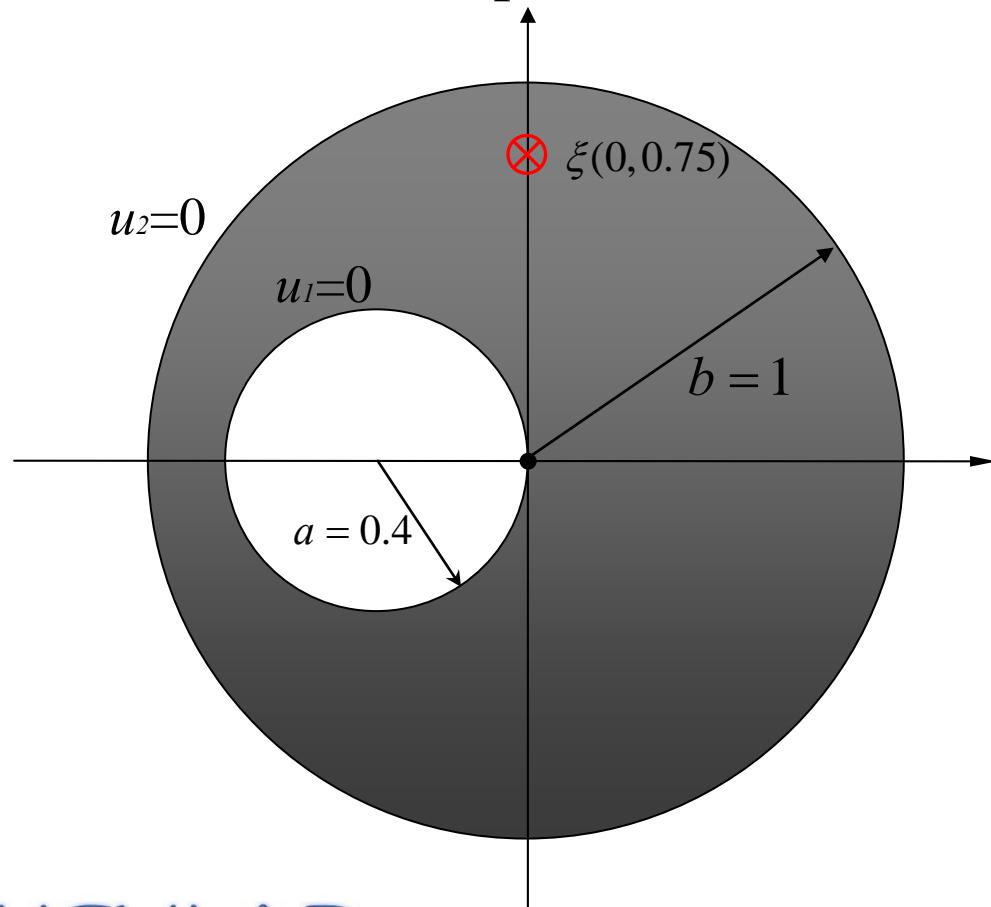
$$\nabla^2 G(x, \zeta) = \delta(x - \zeta), x \in \Omega$$

Dirichlet boundary condition :

$$G(x, \zeta) = 0, x \in B$$

Illustrative examples

Case 5 Eccentric problem



Governing equation :

$$\nabla^2 G(x, \zeta) = \delta(x - \zeta), x \in \Omega$$

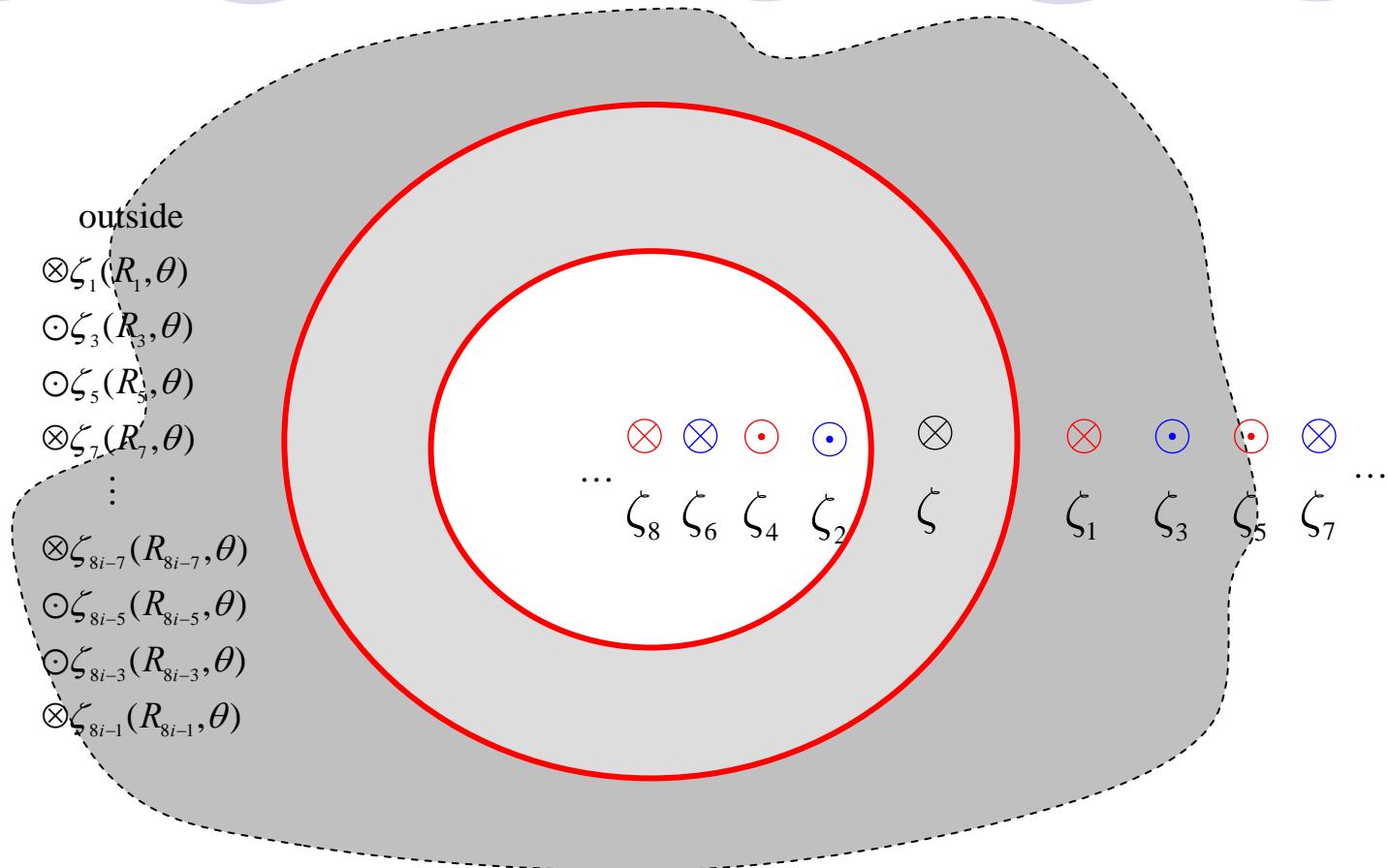
Dirichlet boundary condition :

$$G(x, \zeta) = 0, x \in B$$

Image location: case 1

inside
 $\odot\zeta_2(R_2, \theta)$
 $\odot\zeta_4(R_4, \theta)$
 $\otimes\zeta_6(R_6, \theta)$
 $\otimes\zeta_8(R_8, \theta)$
 \vdots
 $\odot\zeta_{8i-6}(R_{8i-6}, \theta)$
 $\odot\zeta_{8i-4}(R_{8i-4}, \theta)$
 $\otimes\zeta_{8i-2}(R_{8i-2}, \theta)$
 $\otimes\zeta_{8i}(R_{8i}, \theta)$

outside
 $\otimes\zeta_1(R_1, \theta)$
 $\odot\zeta_3(R_3, \theta)$
 $\odot\zeta_5(R_5, \theta)$
 $\otimes\zeta_7(R_7, \theta)$
 \vdots
 $\otimes\zeta_{8i-7}(R_{8i-7}, \theta)$
 $\odot\zeta_{8i-5}(R_{8i-5}, \theta)$
 $\odot\zeta_{8i-3}(R_{8i-3}, \theta)$
 $\otimes\zeta_{8i-1}(R_{8i-1}, \theta)$



Addition theorem & degenerate kernel

Addition theorem	Subtraction theorem
<ul style="list-style-type: none"> ▣ $e^{x+s} = e^x \cdot e^s$ ▣ $\cos(x + s) = \cos x \cos s - \sin x \sin s$ ▣ $\sin(x + s) = \sin x \cos s + \cos x \sin s$ 	<ul style="list-style-type: none"> ◆ $e^{x-s} = e^x / e^s$ ◆ $\cos(x - s) = \cos x \cos s + \sin x \sin s$ ◆ $\sin(x - s) = \sin x \cos s - \cos x \sin s$

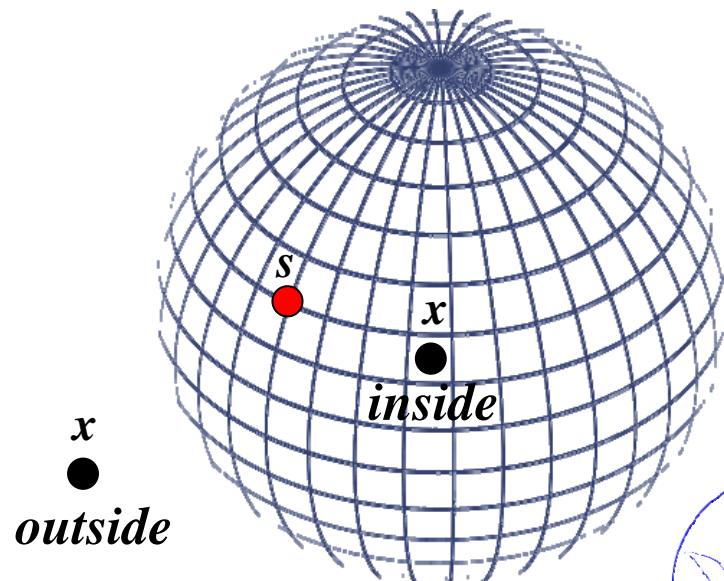
	Degenerate kernel for Laplace problem
1-D	$r = \begin{cases} x - s, & \text{if } x > s \\ s - x, & \text{if } x < s \end{cases}$
2-D	$\ln r = \begin{cases} \ln R - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{\rho}{R}\right)^m \cos m(\theta - \phi), & R \geq \rho \\ \ln \rho - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R}{\rho}\right)^m \cos m(\theta - \phi), & R < \rho \end{cases}$

3-D degenerate kernel

$$\frac{-1}{r} = \begin{cases} U^i = \frac{-1}{R} - \sum_{n=1}^{\infty} \sum_{m=0}^n \varepsilon_m \frac{(n-m)!}{(n+m)!} \cos(m(\bar{\phi} - \phi)) P_n^m(\cos \bar{\theta}) P_n^m(\cos \theta) \frac{\rho^n}{R^{n+1}}, & R \geq \rho \\ U^e = \frac{-1}{\rho} - \sum_{n=1}^{\infty} \sum_{m=0}^n \varepsilon_m \frac{(n-m)!}{(n+m)!} \cos(m(\bar{\phi} - \phi)) P_n^m(\cos \bar{\theta}) P_n^m(\cos \theta) \frac{R^n}{\rho^{n+1}}, & R < \rho \end{cases}$$

$$\varepsilon_m = \begin{cases} 1, & m = 0 \\ 2, & m = 1, 2, \dots, \infty \end{cases}$$

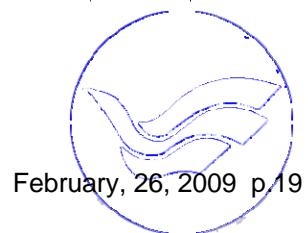
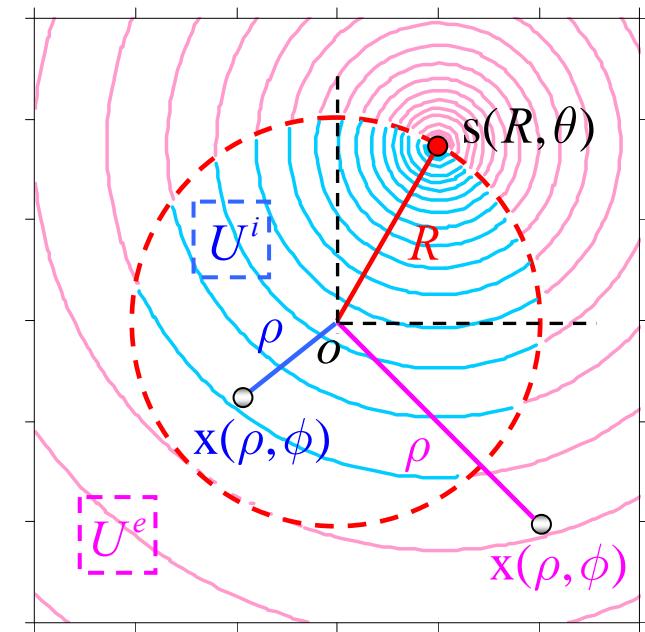
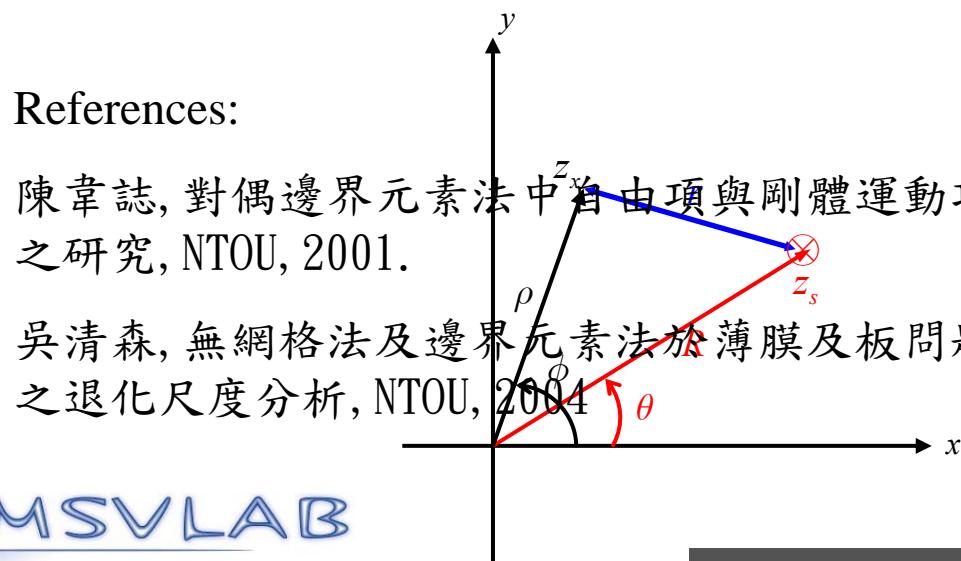
$$\begin{cases} x = (\rho, \phi, \theta) \\ s = (R, \bar{\phi}, \bar{\theta}) \end{cases}$$



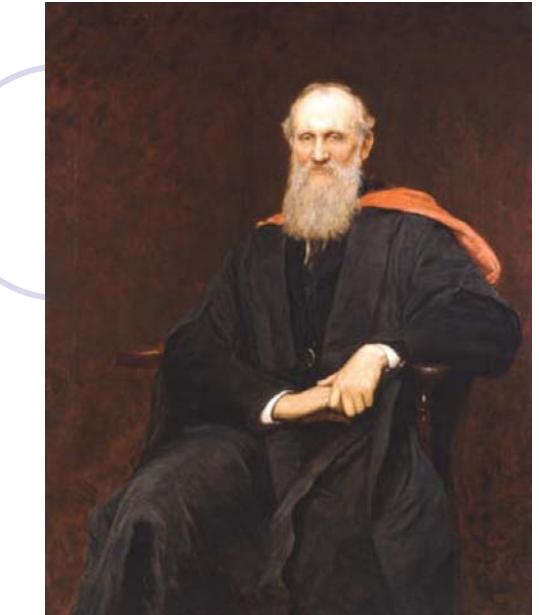
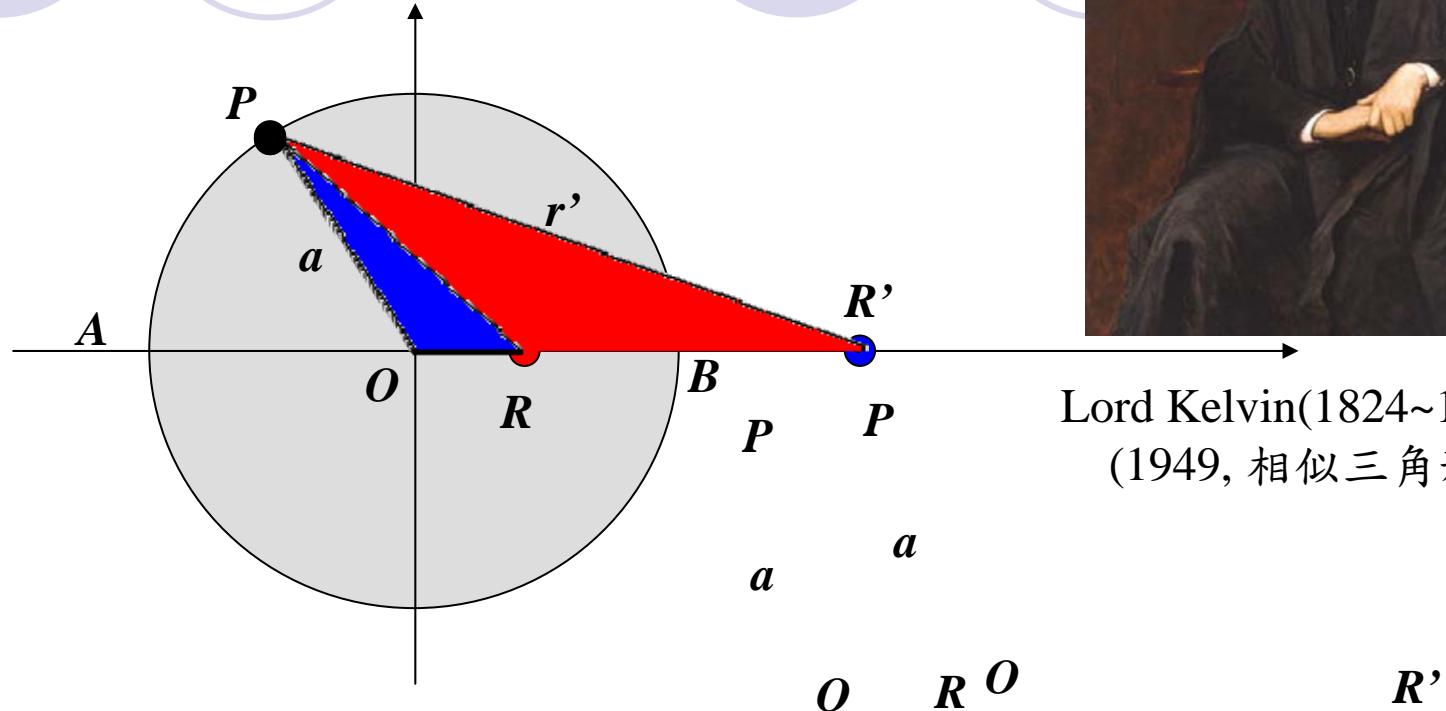
2-D Degenerate kernal

$$\operatorname{Re}\{\ln(z_x - z_s)\} = \ln r$$

$$\ln r = \begin{cases} \ln R - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{\rho}{R}\right)^m \cos m(\theta - \phi), & R \geq \rho \\ \ln \rho - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R}{\rho}\right)^m \cos m(\theta - \phi), & R < \rho \end{cases}$$



Conventional method to determine the image location



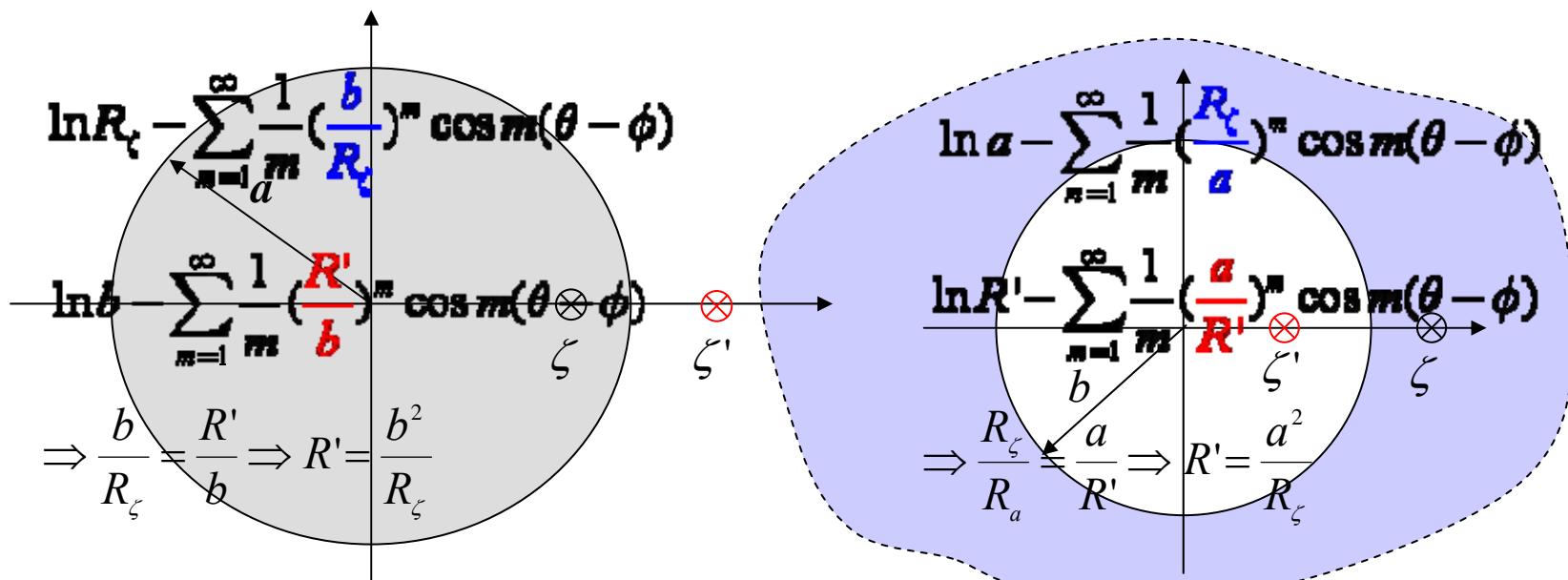
Lord Kelvin(1824~1907)
(1949, 相似三角形)

$$\frac{RP}{R'P} = \frac{a + OR}{a + OR'} = \frac{a - OR}{OR' - a} \quad \longleftrightarrow \quad \frac{OR}{a} = \frac{a}{OR'} \Rightarrow OR' = \frac{a^2}{OR}$$

Greenberg (1971, 取巧法)

Chen and Wu-新觀點 (2006)

$$U(x, \zeta) = \begin{cases} \ln \rho - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R_\zeta}{\rho} \right)^m \cos m(\theta - \phi) \\ \ln R_\zeta - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{\rho}{R_\zeta} \right)^m \cos m(\theta - \phi) \end{cases}$$



MFS-Image group

$$R_1 = \frac{b^2}{R_\zeta}, R_9 = \frac{b^2}{R_\zeta} \frac{b^4}{a^4} \dots \dots \dots R_{8i-7} = \frac{b^2}{R_\zeta} \left(\frac{b^4}{a^4}\right)^{i-1}$$

$$R_2 = \frac{a^2}{R_\zeta}, R_{10} = \frac{a^2}{R_\zeta} \frac{a^4}{b^4} \dots \dots \dots R_{8i-6} = \frac{a^2}{R_\zeta} \left(\frac{a^4}{b^4}\right)^{i-1}$$

$$R_3 = \frac{b^2 R_\zeta}{a^2}, R_{11} = \frac{b^2 R_\zeta}{a^2} \frac{b^4}{a^4} \dots \dots R_{8i-5} = \frac{b^2 R_\zeta}{a^2} \left(\frac{b^4}{a^4}\right)^{i-1}$$

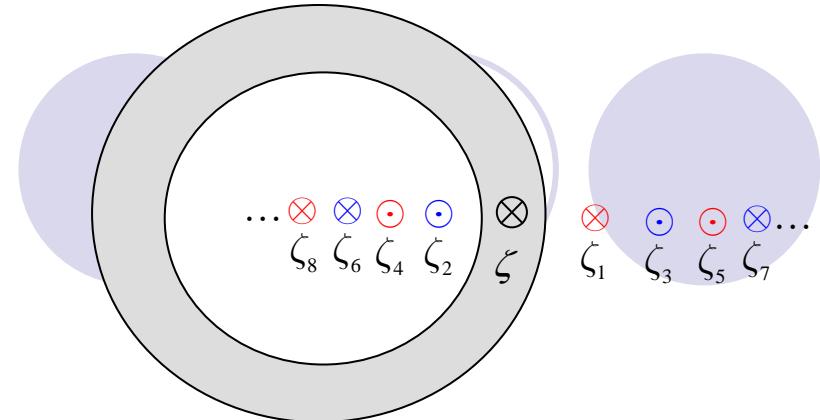
$$R_4 = \frac{a^2 R_\zeta}{b^2}, R_{12} = \frac{a^2 R_\zeta}{b^2} \frac{a^4}{b^4} \dots \dots R_{8i-4} = \frac{a^2 R_\zeta}{b^2} \left(\frac{a^4}{b^4}\right)^{i-1}$$

$$R_5 = \frac{b^4}{a^2 R_\zeta}, R_{13} = \frac{b^4}{a^2 R_\zeta} \frac{b^4}{a^4} \dots \dots R_{8i-3} = \frac{b^4}{a^2 R_\zeta} \left(\frac{b^4}{a^4}\right)^{i-1}$$

$$R_6 = \frac{a^4}{b^2 R_\zeta}, R_{14} = \frac{a^4}{b^2 R_\zeta} \frac{a^4}{b^4} \dots \dots R_{8i-2} = \frac{a^4}{b^2 R_\zeta} \left(\frac{a^4}{b^4}\right)^{i-1}$$

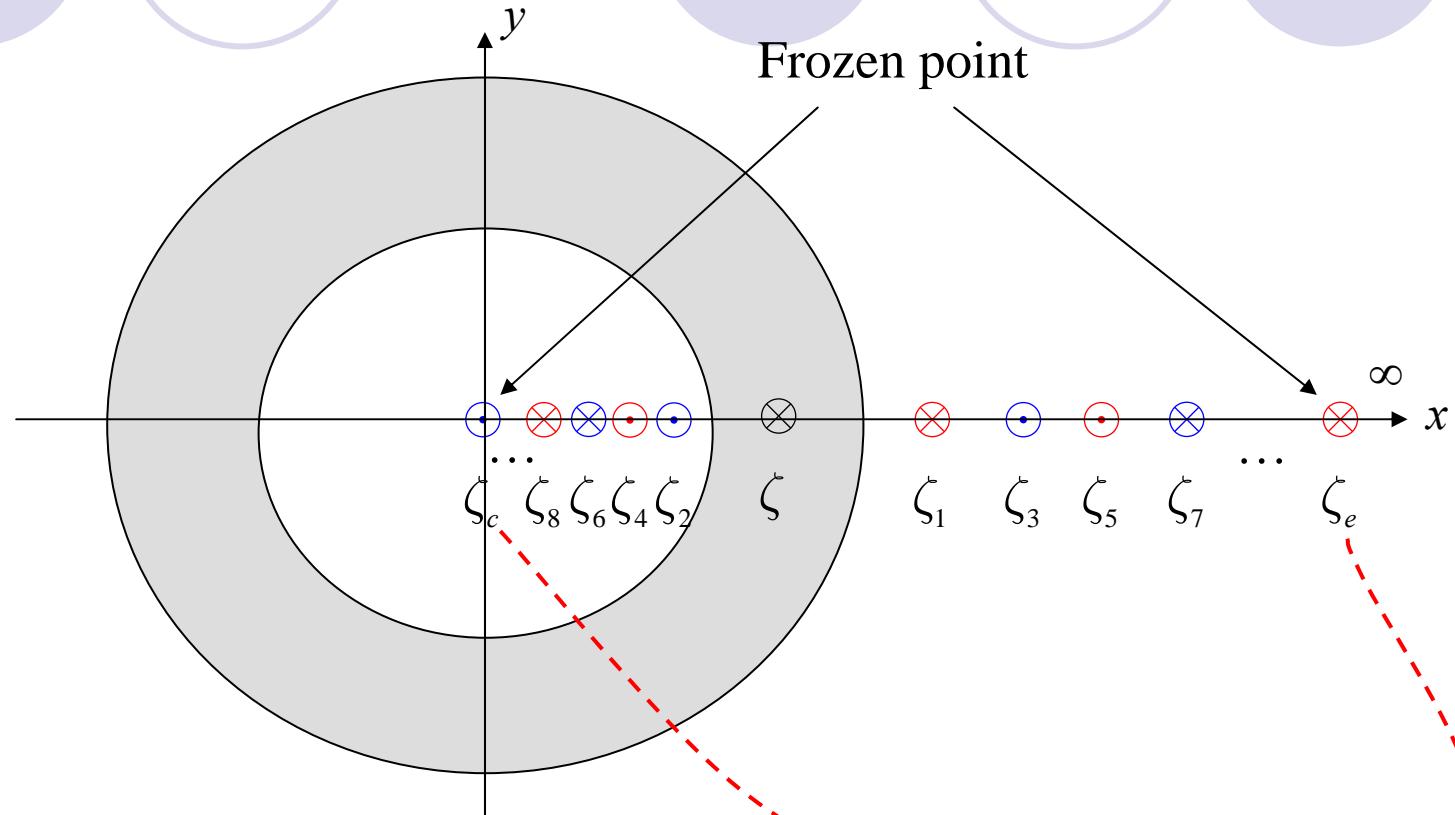
$$R_7 = \frac{b^4 R_\zeta}{a^4}, R_{15} = \frac{b^4 R_\zeta}{a^4} \frac{b^4}{a^4} \dots \dots R_{8i-1} = \frac{b^4 R_\zeta}{a^4} \left(\frac{b^4}{a^4}\right)^{i-1}$$

$$R_8 = \frac{a^4 R_\zeta}{b^4}, R_{16} = \frac{a^4 R_\zeta}{b^4} \frac{a^4}{b^4} \dots \dots R_{8i} = \frac{a^4 R_\zeta}{b^4} \left(\frac{a^4}{b^4}\right)^{i-1}$$



$$\begin{aligned} G_m(x, \zeta) = & \frac{1}{2\pi} \{ \ln|x - \zeta| + \lim_{N \rightarrow \infty} [\sum_{i=1}^N (\ln|x - \zeta_{8i-7}| \\ & - \ln|x - \zeta_{8i-6}| - \ln|x - \zeta_{8i-5}| - \ln|x - \zeta_{8i-4}| \\ & - \ln|x - \zeta_{8i-3}| + \ln|x - \zeta_{8i-2}| + \ln|x - \zeta_{8i-1}| \\ & + \ln|x - \zeta_{8i}|)] \} \end{aligned}$$

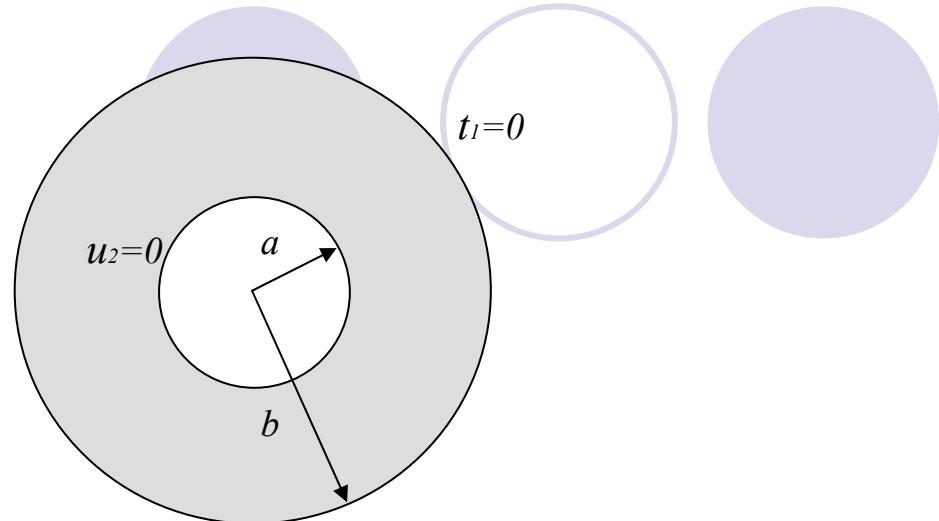
Analytical derivation



$$G(x, \zeta) = \frac{1}{2\pi} \left\{ \ln|x - \zeta| + \lim_{N \rightarrow \infty} \left[\sum_{i=1}^N (\ln|x - \zeta_{8i-7}| - \ln|x - \zeta_{8i-6}| - \ln|x - \zeta_{8i-5}| - \ln|x - \zeta_{8i-4}| - \ln|x - \zeta_{8i-3}| + \ln|x - \zeta_{8i-2}| + \ln|x - \zeta_{8i-1}| + \ln|x - \zeta_{8i}|) + c(N) \ln \rho + e(N) \right] \right\}$$

Numerical solution

$$\begin{cases} \rho = a \Rightarrow G(x_a, \zeta) = 0 \\ \rho = b \Rightarrow G(x_b, \zeta) = 0 \end{cases}$$



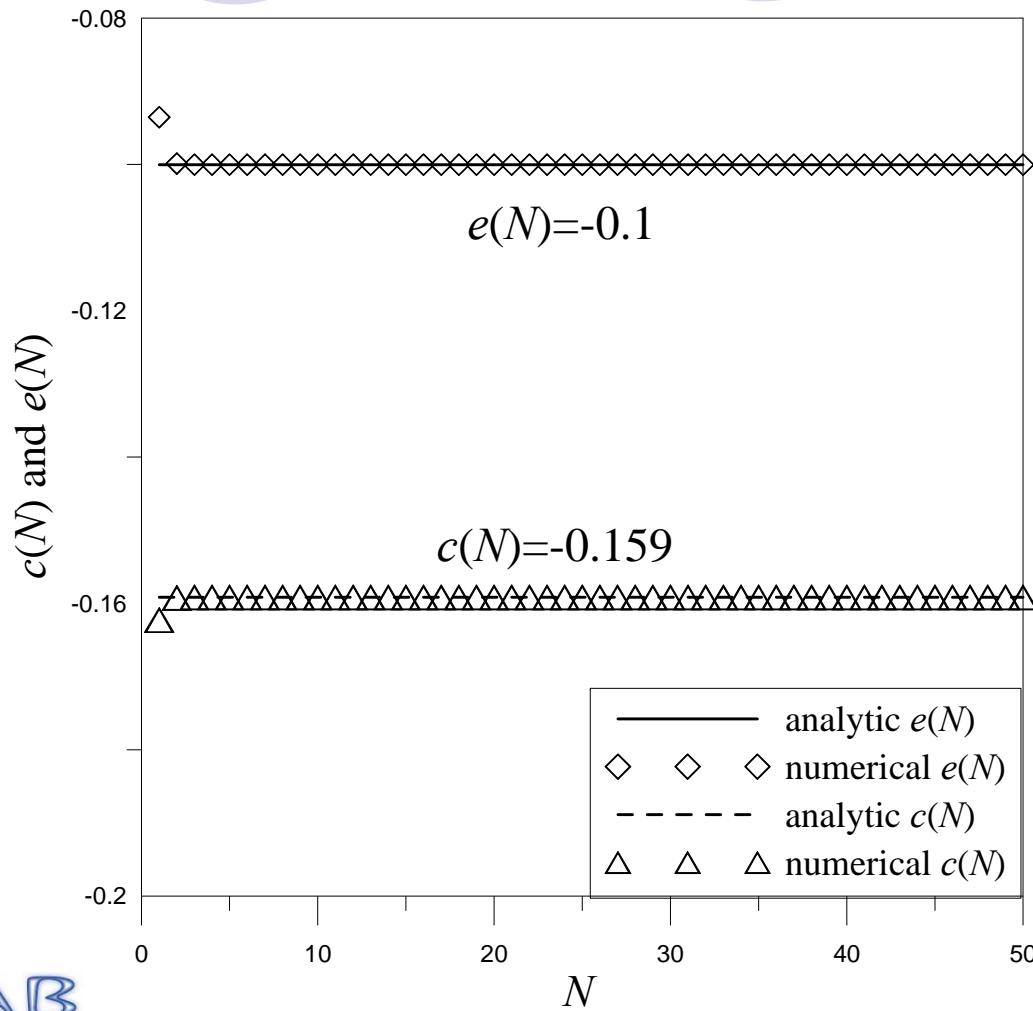
$$G(x, \zeta)|_{x=x_a} \Rightarrow \frac{1}{2\pi} \left\{ \ln|x - \zeta| + \lim_{N \rightarrow \infty} \left[\sum_{i=1}^N (\ln|x - \zeta_{8i-7}| - \ln|x - \zeta_{8i-6}| - \ln|x - \zeta_{8i-5}| - \ln|x - \zeta_{8i-4}| - \ln|x - \zeta_{8i-3}| + \ln|x - \zeta_{8i-2}| + \ln|x - \zeta_{8i-1}| + \ln|x - \zeta_{8i}|) + c(N) \ln x + e(N)] \right] \right\}_{x=x_a} = 0$$

$$\frac{\partial G(x, \zeta)}{\partial x} \Big|_{x=x_b} \Rightarrow \frac{1}{2\pi} \frac{\partial}{\partial x} \left|_{x=x_b} \left\{ \ln|x - \zeta| + \lim_{N \rightarrow \infty} \left[\sum_{i=1}^N (\ln|x - \zeta_{8i-7}| - \ln|x - \zeta_{8i-6}| - \ln|x - \zeta_{8i-5}| - \ln|x - \zeta_{8i-4}| - \ln|x - \zeta_{8i-3}| + \ln|x - \zeta_{8i-2}| + \ln|x - \zeta_{8i-1}| + \ln|x - \zeta_{8i}|) + c(N) \ln x + e(N)] \right] \right\}_{x=x_b} = 0$$



$$\left\{ \begin{array}{l} \left[\ln|x - s| - \sum_{i=1}^N (\ln|x - \zeta_{8i-7}| + \dots + \ln|x - \zeta_{8i}|) \right] \Big|_{x=x_a} \\ \left. \left\{ \frac{\partial}{\partial x} \left[\ln|x - s| - \sum_{i=1}^N (\ln|x - \zeta_{8i-7}| + \dots + \ln|x - \zeta_{8i}|) \right] \right\} \right|_{x=x_b} \end{array} \right\} + \begin{bmatrix} (\ln x)|_{x=x_a} & 1 \\ \frac{\partial}{\partial x}(\ln x)|_{x=x_b} & \frac{\partial}{\partial x}(1) \end{bmatrix} \begin{bmatrix} c(N) \\ e(N) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Numerical and analytic ways to determine $c(N)$ and $e(N)$

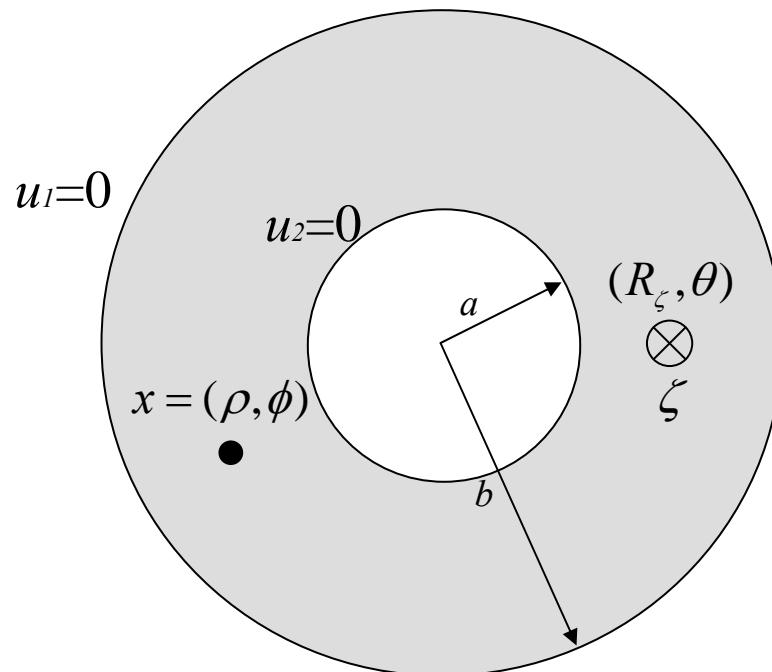


$$e(N) = \frac{\ln a - \ln R_\zeta}{2\pi}$$

$$c(N) = \frac{-1}{2\pi}$$

Case 2: analytical derivation the annular case subject to Dirichlet BCs

Analytical solution



$$G(x, \zeta) = \frac{1}{2\pi} \left\{ \ln|x - \zeta| - \lim_{N \rightarrow \infty} \left[\sum_{i=1}^N (\ln|x - \zeta_{4i-3}| + \ln|x - \zeta_{4i-2}| - \ln|x - \zeta_{4i-1}| - \ln|x - \zeta_{4i}|) - (N \ln \frac{R_\zeta^2}{a^2} + \ln b \frac{\ln a - \ln R_\zeta}{\ln a - \ln b} - \frac{\ln b - \ln R_\zeta}{(\ln b - \ln a)} \ln \rho) \right] \right\}$$

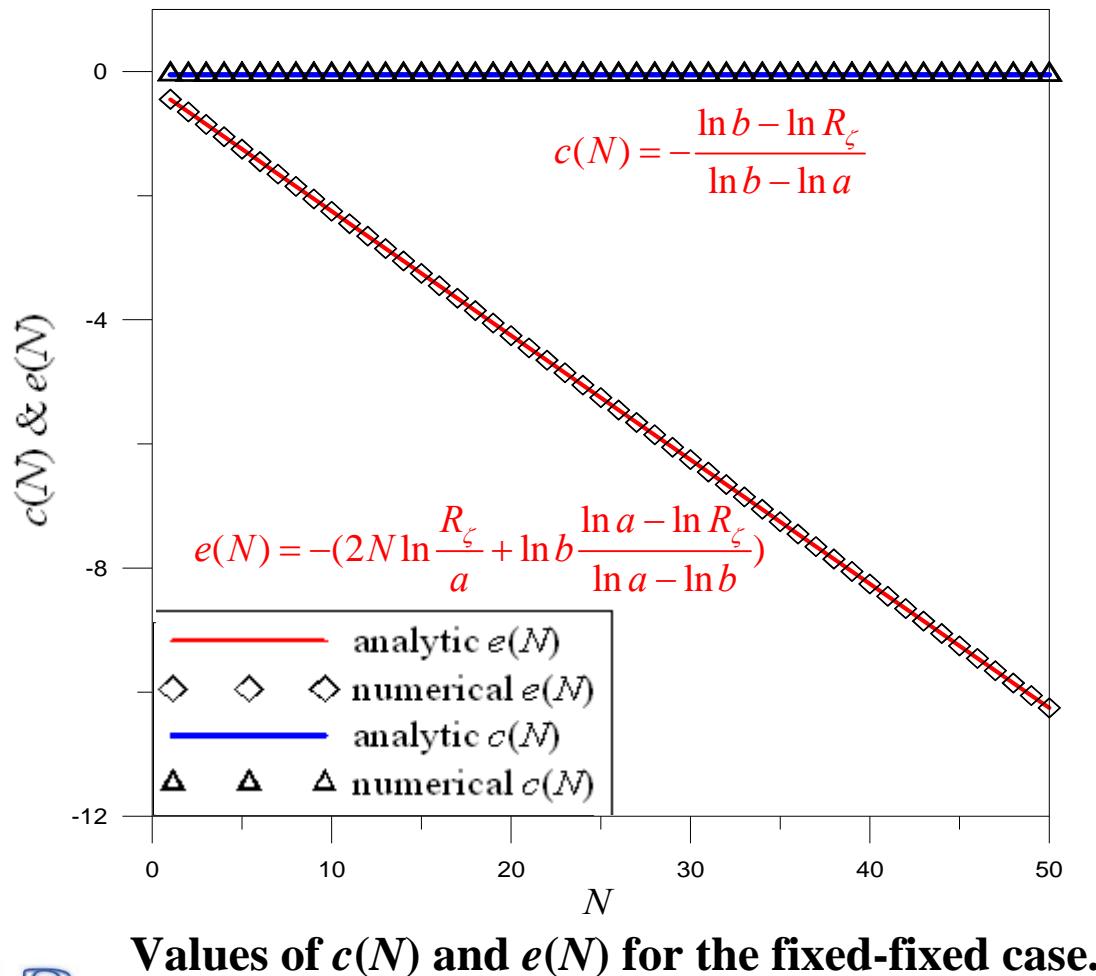
Reviewer comment of EABE :

The N in Eq. to tend to infinity , but in Eq. N is still present as a finite number. Really, what is $2N \ln(\frac{R_\zeta}{a})$ when $N \rightarrow \infty$?

Reply : Euler constant

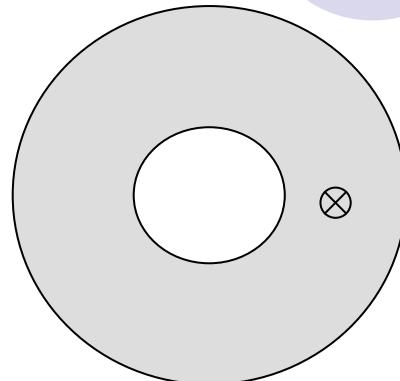
$$\lim_{N \rightarrow \infty} \left(\sum_{m=1}^N \frac{1}{m} - \ln N \right) = \gamma$$

Numerical and analytic ways to determine $c(N)$ and $e(N)$

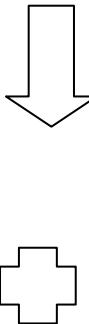


Trefftz Method: case 1

PART 1



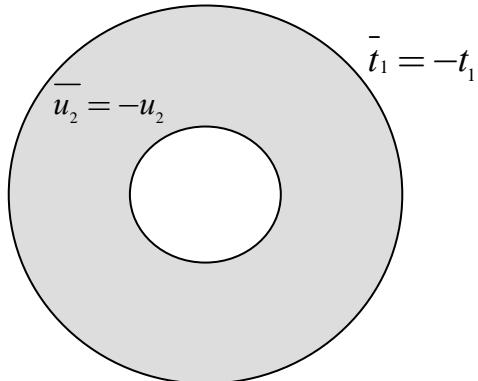
$$U(x, \zeta) = \begin{cases} \ln R_\zeta - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{\rho}{R_\zeta} \right)^m \cos m(\theta - \phi), & R_\zeta \geq \rho \\ \ln \rho - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R_\zeta}{\rho} \right)^m \cos m(\theta - \phi), & R_\zeta < \rho \end{cases}$$



$$2\pi u(x) = U(x, \zeta)$$

$$u(x) = \begin{cases} \frac{1}{2\pi} \left[\ln R_\zeta - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{\rho}{R_\zeta} \right)^m \cos m(\theta - \phi) \right], & R_\zeta \geq \rho \\ \frac{1}{2\pi} \left[\ln \rho - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R_\zeta}{\rho} \right)^m \cos m(\theta - \phi) \right], & R_\zeta < \rho \end{cases}$$

Boundary value problem



$$G_T(x,s) = \sum_{j=1}^{N_T} c_j \Phi_j,$$

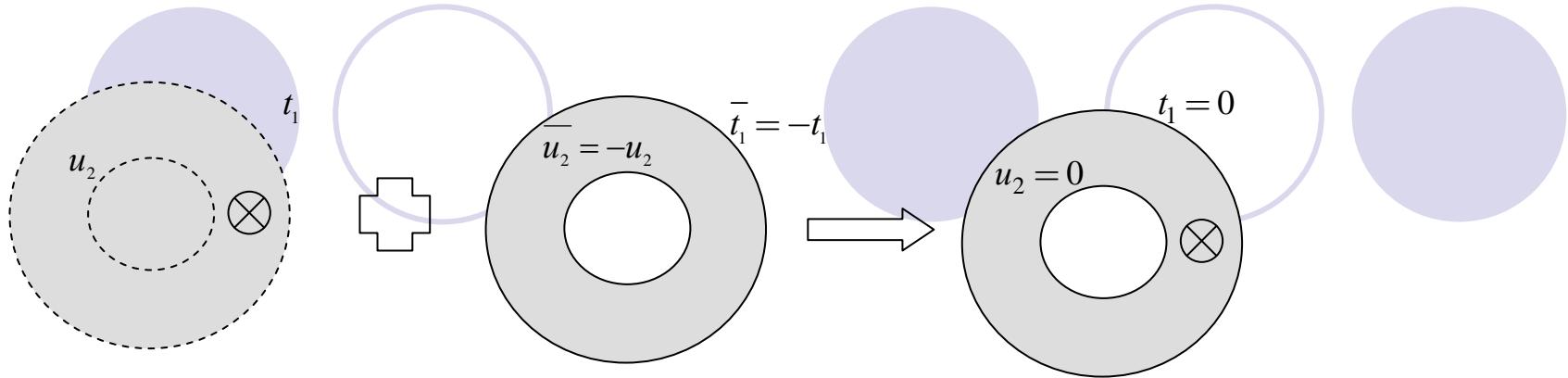
interior $\rightarrow 1, \rho^m \cos m\phi, \rho^m \sin m\phi$

exterior $\rightarrow \ln \rho, \rho^{-m} \cos m\phi, \rho^{-m} \sin m\phi$



PART 2 $G_T(x,\zeta) = p_0 + \bar{p}_0 \ln \rho + \sum_{m=1}^{\infty} [(p_m \rho^m + \bar{p}_m \rho^{-m}) \cos m\phi + (q_m \rho^m + \bar{q}_m \rho^{-m}) \sin m\phi] = -u(x)$

$$\left\{ \frac{p_0}{\bar{p}_0} \right\} = \frac{1}{2\pi} \begin{pmatrix} \ln a - \ln R_\zeta \\ -1 \end{pmatrix} \left\{ \frac{p_m}{\bar{p}_m} \right\} = \begin{Bmatrix} \frac{\cos m\theta \left[a^m \left(\frac{a}{R_\zeta} \right)^m - R_\zeta^{-m} \right]}{2m\pi(b^{2m} + a^{2m})} \\ \frac{a^m b^m \cos m\theta \left[b^m \left(\frac{a}{R_\zeta} \right)^m + a^m \left(\frac{R_\zeta}{b} \right)^m \right]}{2m\pi(b^{2m} + a^{2m})} \end{Bmatrix} \left\{ \frac{q_m}{\bar{q}_m} \right\} = \begin{Bmatrix} \frac{\sin m\theta \left[a^m \left(\frac{a}{R_\zeta} \right)^m - R_\zeta^{-m} \right]}{2m\pi(b^{2m} + a^{2m})} \\ \frac{a^m b^m \sin m\theta \left[b^m \left(\frac{a}{R_\zeta} \right)^m + a^m \left(\frac{R_\zeta}{b} \right)^m \right]}{2m\pi(b^{2m} + a^{2m})} \end{Bmatrix}$$



PART 1 + PART 2 :

$$G(x, \zeta) = u + \bar{u}$$

$$u(x) = \begin{cases} \frac{1}{2\pi} \left[\ln R_\zeta - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{\rho}{R_\zeta} \right)^m \cos m(\theta - \phi) \right], & R_\zeta \geq \rho \\ \frac{1}{2\pi} \left[\ln \rho - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R_\zeta}{\rho} \right)^m \cos m(\theta - \phi) \right], & R_\zeta < \rho \end{cases}$$

$$\bar{u}(x) = \frac{1}{2\pi} \left\{ p_0 + \bar{p}_0 \ln \rho + \sum_{m=1}^{\infty} [(p_m \rho^m + \bar{p}_m \rho^{-m}) \cos m\phi + (q_m \rho^m + \bar{q}_m \rho^{-m}) \sin m\phi] \right\}$$



$$G(x, \zeta) = \frac{1}{2\pi} \left\{ \ln |x - \zeta| + p_0 + \bar{p}_0 \ln \rho + \sum_{m=1}^{\infty} [(p_m \rho^m + \bar{p}_m \rho^{-m}) \cos m\phi + (q_m \rho^m + \bar{q}_m \rho^{-m}) \sin m\phi] \right\}$$

Mathematical equivalence of solutions derived by using the Trefftz method and MFS for annular case

MFS(Image method)

$$G(x, \zeta) = \frac{1}{2\pi} \left\{ \ln|x - \zeta| + \lim_{N \rightarrow \infty} \sum_{i=1}^N \{ \ln|x - \zeta_{8i-7}| - \ln|x - \zeta_{8i-6}| - \ln|x - \zeta_{8i-5}| \right.$$

$$- \ln|x - \zeta_{8i-4}| - \ln|x - \zeta_{8i-3}| + \ln|x - \zeta_{8i-2}| + \ln|x - \zeta_{8i-1}| + \ln|x - \zeta_{8i}| \}$$

+ $\ln a - \ln R_\zeta$

$$\left. - \ln \rho \right\}, \quad a \leq \rho \leq b$$

The same

Trefftz method

$$\begin{Bmatrix} p_0 \\ \bar{p}_0 \end{Bmatrix} = \frac{1}{2\pi} \begin{bmatrix} \ln a - \ln R_\zeta \\ -1 \end{bmatrix}$$

MSVLAB

HRE, HTOU

Trefftz method series expansion

$$\begin{Bmatrix} p_m \\ \bar{p}_m \end{Bmatrix} = \begin{Bmatrix} \cos m\theta \left[a^m \left(\frac{a}{R_\zeta} \right)^m - R_\zeta^m \right] \\ \frac{2m\pi(b^{2m} + a^{2m})}{a^m b^m \cos m\theta \left[b^m \left(\frac{a}{R_\zeta} \right)^m + a^m \left(\frac{R_\zeta}{b} \right)^m \right]} \\ \frac{2m\pi(b^{2m} + a^{2m})}{a^m b^m \sin m\theta \left[b^m \left(\frac{a}{R_\zeta} \right)^m + a^m \left(\frac{R_\zeta}{b} \right)^m \right]} \end{Bmatrix}$$

$$\begin{Bmatrix} q_m \\ \bar{q}_m \end{Bmatrix} = \begin{Bmatrix} \sin m\theta \left[a^m \left(\frac{a}{R_\zeta} \right)^m - R_\zeta^m \right] \\ \frac{2m\pi(b^{2m} + a^{2m})}{a^m b^m \sin m\theta \left[b^m \left(\frac{a}{R_\zeta} \right)^m + a^m \left(\frac{R_\zeta}{b} \right)^m \right]} \\ \frac{2m\pi(b^{2m} + a^{2m})}{a^m b^m \cos m\theta \left[b^m \left(\frac{a}{R_\zeta} \right)^m + a^m \left(\frac{R_\zeta}{b} \right)^m \right]} \end{Bmatrix}$$

Without loss of generality

$$\theta = 0 \quad \longrightarrow \quad \left(\frac{\left(\frac{a^2}{R_\zeta} \right)^m \rho^m}{b^{2m} + a^{2m}} - \frac{R_\zeta^m \rho^m}{b^{2m} + a^{2m}} + \frac{\left(\frac{b^2 a^2}{R_\zeta} \right)^m \rho^{-m}}{b^{2m} + a^{2m}} + \frac{a^{2m} R_\zeta^m \rho^{-m}}{b^{2m} + a^{2m}} \right) \cos(m\phi)$$



Image method series expansion

$$\dots \otimes \zeta_8 \otimes \zeta_6 \otimes \zeta_4 \otimes \zeta_2 \otimes \zeta_1 \otimes \zeta_3 \otimes \zeta_5 \otimes \zeta_7 \dots$$

$$\left\{ \begin{array}{l} \otimes \zeta_{8i-7} \Rightarrow -\left[\left(\frac{\rho}{R_1} \right)^m + \left(\frac{\rho}{R_9} \right)^m + \dots \right] = -\left[\left(\frac{\rho R_\zeta}{b^2} \right)^m + \left(\frac{\rho R_\zeta}{b^2} \frac{a^4}{b^4} \right)^m + \dots \right] = -\frac{\left(\frac{\rho R_\zeta}{b^2} \right)^m}{1 - \left(\frac{a}{b} \right)^{4m}} \\ \odot \zeta_{8i-3} \Rightarrow \left(\frac{\rho}{R_5} \right)^m + \left(\frac{\rho}{R_{13}} \right)^m + \dots = \left(\frac{a^2 \rho R_\zeta}{b^4} \right)^m + \left(\frac{a^2 \rho R_\zeta}{b^4} \frac{a^4}{b^4} \right)^m + \dots = \frac{\left(\frac{a^2 \rho R_\zeta}{b^4} \right)^m}{1 - \left(\frac{a}{b} \right)^{4m}} \end{array} \right.$$

$$\otimes \zeta_{8i-7} + \odot \zeta_{8i-3} = -\frac{\left(\frac{\rho R_\zeta}{b^2} \right)^m}{1 - \left(\frac{a}{b} \right)^{4m}} + \frac{\left(\frac{a^2 \rho R_\zeta}{b^4} \right)^m}{1 - \left(\frac{a}{b} \right)^{4m}} = -\frac{\rho^m R_\zeta^m (b^{2m} - a^{2m})}{(b^{2m} - a^{2m})(b^{2m} + a^{2m})} = \boxed{-\frac{\rho^m R_\zeta^m}{(b^{2m} + a^{2m})}}$$

Treffitz series expansion



$$\left\{ \frac{\left(\frac{a^2}{R_\zeta} \right)^m \rho^m}{b^{2m} + a^{2m}} - \boxed{\frac{R_\zeta^m \rho^m}{b^{2m} + a^{2m}}} + \frac{\left(\frac{b^2 a^2}{R_\zeta} \right)^m \rho^{-m}}{b^{2m} + a^{2m}} + \frac{a^{2m} R_\zeta^m \rho^{-m}}{b^{2m} + a^{2m}} \right\}$$

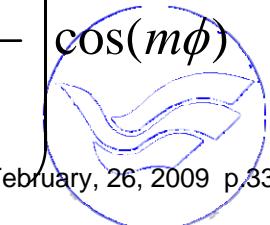
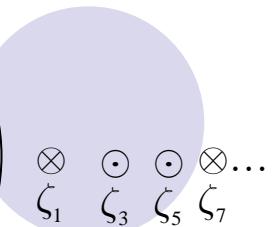
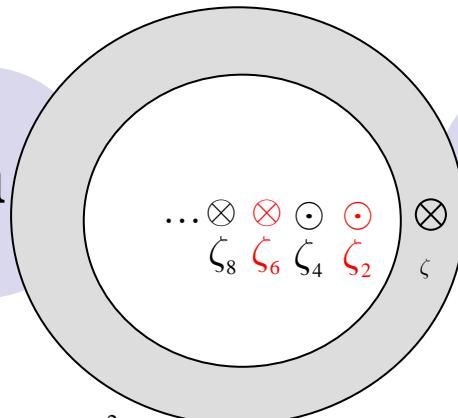


Image method series expansion



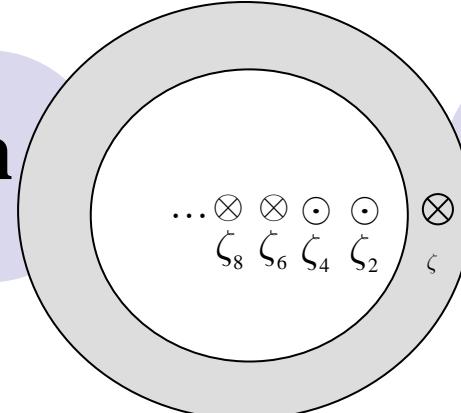
$$\left\{ \begin{array}{l} \odot \zeta_{8i-6} \Rightarrow \left(\frac{R_2}{\rho} \right)^m + \left(\frac{R_{10}}{\rho} \right)^m + \dots = \left(\frac{a^2}{R_\zeta \rho} \right)^m + \left(\frac{a^2}{R_\zeta \rho} \frac{a^4}{b^4} \right)^m + \dots = \frac{\left(\frac{a^2}{R_\zeta \rho} \right)^m}{1 - \left(\frac{a}{b} \right)^{4m}} \\ \\ \otimes \zeta_{8i-2} \Rightarrow - \left[\left(\frac{R_6}{\rho} \right)^m + \left(\frac{R_{14}}{\rho} \right)^m + \dots \right] = - \left[\left(\frac{a^4}{b^2 R_\zeta \rho} \right)^m + \left(\frac{a^4}{b^2 R_\zeta \rho} \frac{a^4}{b^4} \right)^m + \dots \right] = - \frac{\left(\frac{a^4}{b^2 R_\zeta \rho} \right)^m}{1 - \left(\frac{a}{b} \right)^{4m}} \\ \\ \odot \zeta_{8i-6} + \otimes \zeta_{8i-2} = \frac{\left(\frac{a^2}{R_\zeta \rho} \right)^m}{1 - \left(\frac{a}{b} \right)^{4m}} - \frac{\left(\frac{a^4}{b^2 R_\zeta \rho} \right)^m}{1 - \left(\frac{a}{b} \right)^{4m}} = \frac{\left(\frac{a^2 b^2}{R_\zeta \rho} \right)^m (b^{2m} - a^{2m})}{(b^{2m} - a^{2m})(b^{2m} + a^{2m})} = \boxed{\frac{\left(\frac{a^2 b^2}{R_\zeta \rho} \right)^m}{(b^{2m} + a^{2m})}} \end{array} \right.$$

Treffitz series expansion



$$\left(\frac{\left(\frac{a^2}{R_\zeta} \right)^m \rho^m}{b^{2m} + a^{2m}} - \frac{R_\zeta^m \rho^m}{b^{2m} + a^{2m}} + \boxed{\frac{\left(\frac{b^2 a^2}{R_\zeta} \right)^m \rho^{-m}}{b^{2m} + a^{2m}}} + \frac{a^{2m} R_\zeta^m \rho^{-m}}{b^{2m} + a^{2m}} \right)$$

Image method series expansion



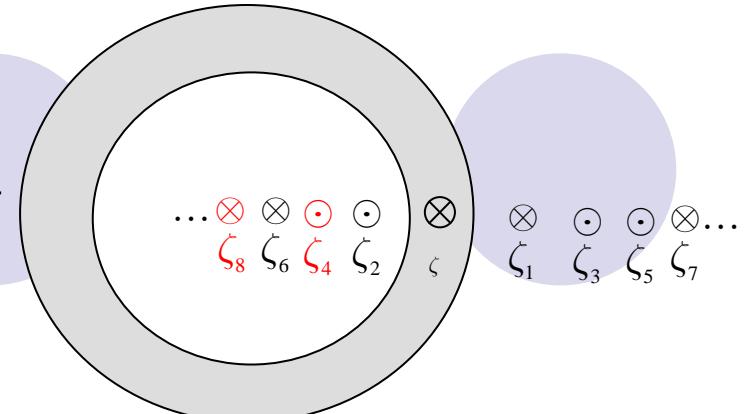
$$\left\{ \begin{array}{l} \odot \zeta_{8i-5} \Rightarrow \left(\frac{\rho}{R_3} \right)^m + \left(\frac{\rho}{R_{11}} \right)^m + \dots = \left(\frac{a^2 \rho}{b^2 R_\zeta} \right)^m + \left(\frac{a^2 \rho}{b^2 R_\zeta} \frac{a^4}{b^4} \right)^m + \dots = \frac{\left(\frac{a^2 \rho}{b^2 R_\zeta} \right)^m}{1 - \left(\frac{a}{b} \right)^{4m}} \\ \otimes \zeta_{8i-1} \Rightarrow - \left[\left(\frac{\rho}{R_7} \right)^m + \left(\frac{\rho}{R_{15}} \right)^m + \dots \right] = - \left[\left(\frac{a^4 \rho}{b^4 R_\zeta} \right)^m + \left(\frac{a^4 \rho}{b^4 R_\zeta} \frac{a^4}{b^4} \right)^m + \dots \right] = - \frac{\left(\frac{a^4 \rho}{b^4 R_\zeta} \right)^m}{1 - \left(\frac{a}{b} \right)^{4m}} \\ \odot \zeta_{8i-5} + \otimes \zeta_{8i-1} = \frac{\left(\frac{a^2 \rho}{b^2 R_\zeta} \right)^m}{1 - \left(\frac{a}{b} \right)^{4m}} - \frac{\left(\frac{a^4 \rho}{b^4 R_\zeta} \right)^m}{1 - \left(\frac{a}{b} \right)^{4m}} = \frac{\left(\frac{a^2 \rho}{R_\zeta} \right)^m (b^{2m} - a^{2m})}{(b^{2m} - a^{2m})(b^{2m} + a^{2m})} = \boxed{\left(\frac{a^2 \rho}{R_\zeta} \right)^m} \end{array} \right.$$

Trefftz series expansion



$$\left(\frac{\left(\frac{a^2}{R_\zeta} \right)^m \rho^m}{b^{2m} + a^{2m}} - \frac{R_\zeta^m \rho^m}{b^{2m} + a^{2m}} + \frac{\left(\frac{b^2 a^2}{R_\zeta} \right)^m \rho^{-m}}{b^{2m} + a^{2m}} + \frac{a^{2m} R_\zeta^m \rho^{-m}}{b^{2m} + a^{2m}} \right) \cos(m\phi)$$

Image method series expansion



$$\left\{ \begin{array}{l} \odot \zeta_{8i-4} \Rightarrow \left(\frac{R_4}{\rho} \right)^m + \left(\frac{R_{12}}{\rho} \right)^m + \dots = \left(\frac{a^2 R_\zeta}{b^2 \rho} \right)^m + \left(\frac{a^2 R_\zeta}{b^2 \rho} \frac{a^4}{b^4} \right)^m + \dots = \frac{\left(\frac{a^2 R_\zeta}{b^2 \rho} \right)^m}{1 - \left(\frac{a}{b} \right)^{4m}} \\ \\ \otimes \zeta_{8i} \Rightarrow - \left[\left(\frac{R_8}{\rho} \right)^m + \left(\frac{R_{16}}{\rho} \right)^m + \dots \right] = - \left[\left(\frac{a^4 R_\zeta}{b^4 \rho} \right)^m + \left(\frac{a^4 R_\zeta}{b^4 \rho} \frac{a^4}{b^4} \right)^m + \dots \right] = - \frac{\left(\frac{a^4 R_\zeta}{b^4 \rho} \right)^m}{1 - \left(\frac{a}{b} \right)^{4m}} \\ \\ \odot \zeta_{8i-4} + \otimes \zeta_{8i} = \frac{\left(\frac{a^2 R_\zeta}{b^2 \rho} \right)^m}{1 - \left(\frac{a}{b} \right)^{4m}} - \frac{\left(\frac{a^4 R_\zeta}{b^4 \rho} \right)^m}{1 - \left(\frac{a}{b} \right)^{4m}} = \frac{\left(\frac{a^2 R_\zeta}{b^2 \rho} \right)^m (b^{2m} - a^{2m})}{(b^{2m} - a^{2m})(b^{2m} + a^{2m})} = \boxed{\frac{\left(\frac{a^2 R_\zeta}{b^2 \rho} \right)^m}{(b^{2m} + a^{2m})}} \end{array} \right.$$

Trefftz series expansion



$$\left(\frac{\left(\frac{a^2}{R_\zeta} \right)^m \rho^m}{b^{2m} + a^{2m}} - \frac{R_\zeta^m \rho^m}{b^{2m} + a^{2m}} + \frac{\left(\frac{b^2 a^2}{R_\zeta} \right)^m \rho^{-m}}{b^{2m} + a^{2m}} + \boxed{\frac{a^{2m} R_\zeta^m \rho^{-m}}{b^{2m} + a^{2m}}} \right)$$

Mathematical equivalence of solutions derived by using the Trefftz method and MFS

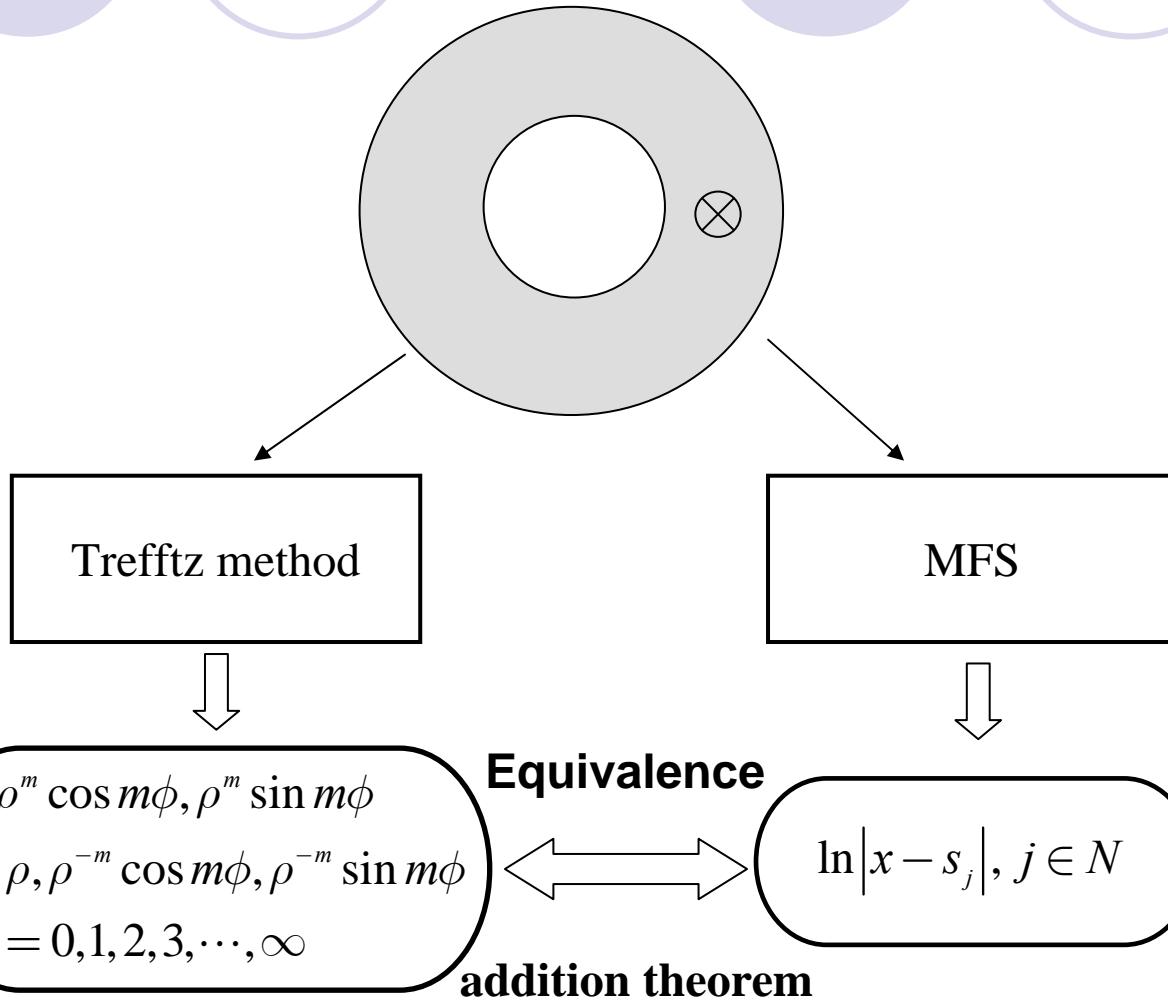


Image method of interior, exterior and annular problems

	Interior Dirichlet problem	Exterior Neumann problem	Annular problem
Problems			
Solution of image parts	$G(x, \xi; \xi') = \frac{1}{2\pi} [\ln x - \xi - \ln x - \xi']$	$G(x, \xi; \xi') = \frac{1}{2\pi} [\ln x - \xi + \ln x - \xi']$	$G(x, \xi; \xi') = \frac{1}{2\pi} (\ln x - \xi + \lim_{n \rightarrow \infty} \sum_{k=1}^n [\ln x - \xi_{k+1} - \ln x - \xi_k] - \ln x - \xi_n - \ln x - \xi_1 + \ln x - \xi_{n+1} + \ln x - \xi_n), a < \rho < b$
Extra terms of complementary solutions	$\frac{1}{2\pi} [(\ln a - \ln R) \cdot 1]$	$\frac{1}{2\pi} [(\ln a) \cdot (-1)]$	$\frac{1}{2\pi} [(\ln a - \ln R) \cdot 1 + (-1) \cdot \ln a]$

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Mathematical equivalence for the solution

工程數學裡一個簡單的問題：

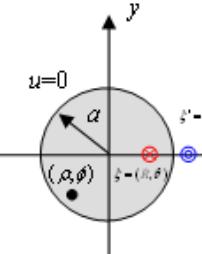
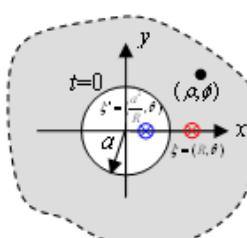
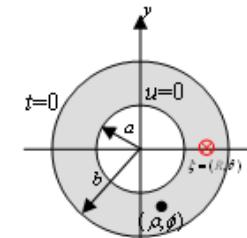
Solve $y''(x) - y(x) = 0$

$$\Rightarrow \begin{cases} y(x) = c_1 e^x + c_2 e^{-x} \\ y(x) = b_1 \cosh x + b_2 \sinh x \end{cases}$$

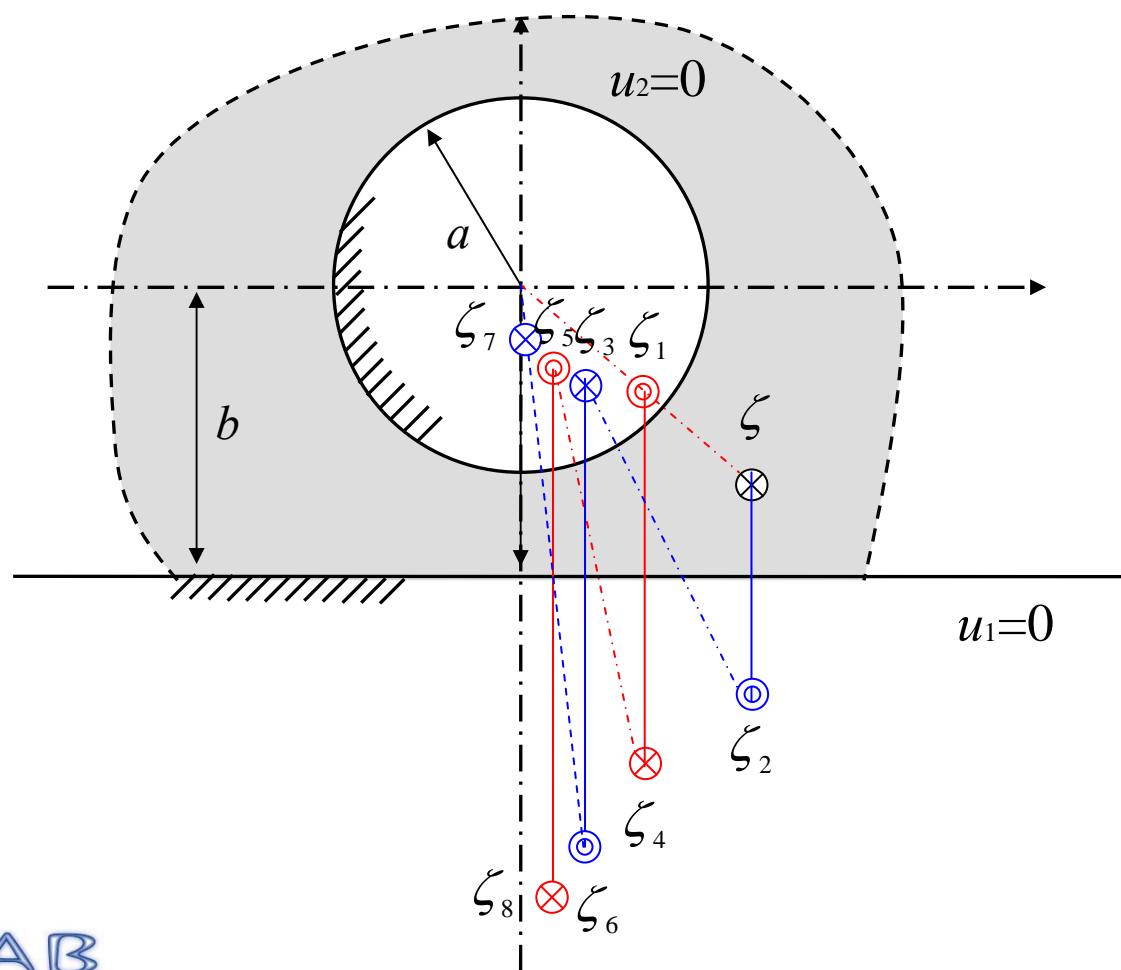
Equivalence

Treffitz & MFS

解的數學等效性

Problems \ Methods	Treffitz method		Special MFS (image method)
Interior Dirichlet case	$G(x, \xi) = \frac{\ln x-\xi }{2\pi} - \frac{\ln a}{2\pi} + \sum_{m=1}^{\infty} \left[\frac{R^m \rho^m \cos m\theta}{2m\pi a^{2m}} \cos m\phi + \frac{R^m \rho^m \sin m\theta}{2m\pi a^{2m}} \sin m\phi \right]$		$G(x, \xi) = \frac{1}{2\pi} [\ln x-\xi - \ln x-\xi' - \ln a + \ln R]$
	Constant term	$\frac{-1}{2\pi} \ln a$	$\frac{-1}{2\pi} \ln a$
	Series terms	$\sum_{m=1}^{\infty} \frac{R^m \rho^m \cos m\theta}{2m\pi a^{2m}} \cos m\phi + \frac{R^m \rho^m \sin m\theta}{2m\pi a^{2m}} \sin m\phi$	$\sum_{m=1}^{\infty} \frac{R^m \rho^m \cos m\theta}{2m\pi a^{2m}} \cos m\phi + \frac{R^m \rho^m \sin m\theta}{2m\pi a^{2m}} \sin m\phi$
Exterior Neumann case	$G(x, \xi) = \frac{\ln x-\xi }{2\pi} - \sum_{m=1}^{\infty} \left[\frac{a^{2m} \cos m\theta}{2m\pi R^m \rho^m} \cos(m\phi) + \frac{a^{2m} \sin m\theta}{2m\pi R^m \rho^m} \cos(m\phi) \right]$		$G(x, \xi) = \frac{1}{2\pi} [\ln x-\xi + \ln x-\xi' - \ln \rho]$
	Constant term	Constant=0	Constant=0
	Series terms	$\sum_{m=1}^{\infty} \frac{-a^{2m} \cos m\theta}{2m\pi R^m \rho^m} \cos m\phi - \frac{a^{2m} \sin m\theta}{2m\pi R^m \rho^m} \sin m\phi$	$\sum_{m=1}^{\infty} \frac{-a^{2m} \cos m\theta}{2m\pi R^m \rho^m} \cos m\phi - \frac{a^{2m} \sin m\theta}{2m\pi R^m \rho^m} \sin m\phi$
Annular case	$G(x, \xi) = \frac{\ln x-\xi }{2\pi} + \frac{\ln a - \ln R - \ln \rho}{2\pi}$ $+ \sum_{m=1}^{\infty} \left(\frac{(\frac{a^2 \rho}{R})^m}{b^{2m} + a^{2m}} - \frac{(R\rho)^m}{b^{2m} + a^{2m}} + \frac{(\frac{b^2 \rho}{R})^m}{b^{2m} + a^{2m}} + \frac{(\frac{a^2 R}{\rho})^m}{b^{2m} + a^{2m}} \right) \cos(m\theta) \cos(m\phi)$		$G(x, \xi) = \frac{1}{2\pi} \{ \ln x-\xi + \lim_{n \rightarrow \infty} \sum_{m=1}^n [\ln x-\xi_{m-1} - \ln x-\xi_m - \ln x-\xi_{m-1}' + \ln x-\xi_m'] + \ln a - \ln R - \ln \rho \}$
 source point  image point  	Constant term	$p_0 + \bar{p}_0 \ln \rho = \frac{1}{2\pi} (\ln a - \ln R - \ln \rho)$	$\frac{1}{2\pi} (\ln a - \ln R - \ln \rho)$
	Series terms	$\left(\frac{(\frac{a^2 \rho}{R})^m}{b^{2m} + a^{2m}} - \frac{(R\rho)^m}{b^{2m} + a^{2m}} + \frac{(\frac{b^2 \rho}{R})^m}{b^{2m} + a^{2m}} + \frac{(\frac{a^2 R}{\rho})^m}{b^{2m} + a^{2m}} \right) \cos(m\theta) \cos(m\phi)$ $+ \left(\frac{(\frac{a^2 \rho}{R})^m}{b^{2m} + a^{2m}} - \frac{(R\rho)^m}{b^{2m} + a^{2m}} + \frac{(\frac{b^2 \rho}{R})^m}{b^{2m} + a^{2m}} + \frac{(\frac{a^2 R}{\rho})^m}{b^{2m} + a^{2m}} \right) \sin(m\theta) \sin(m\phi)$	$\left(\frac{(\frac{a^2 \rho}{R})^m}{b^{2m} + a^{2m}} - \frac{(R\rho)^m}{b^{2m} + a^{2m}} + \frac{(\frac{b^2 \rho}{R})^m}{b^{2m} + a^{2m}} + \frac{(\frac{a^2 R}{\rho})^m}{b^{2m} + a^{2m}} \right) \cos(m\theta) \cos(m\phi)$ $+ \left(\frac{(\frac{a^2 \rho}{R})^m}{b^{2m} + a^{2m}} - \frac{(R\rho)^m}{b^{2m} + a^{2m}} + \frac{(\frac{b^2 \rho}{R})^m}{b^{2m} + a^{2m}} + \frac{(\frac{a^2 R}{\rho})^m}{b^{2m} + a^{2m}} \right) \sin(m\theta) \sin(m\phi)$

Semi-analytical solution: case 3



MFS-Image group

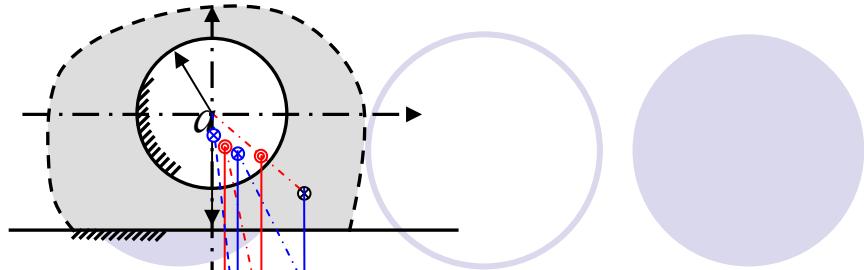
$$\otimes \zeta \rightarrow \begin{cases} \ln R_\zeta - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{a}{R_\zeta}\right)^m \cos m(\theta - \phi), & a < R_\zeta \\ \ln \rho - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R_\zeta}{\rho}\right)^m \cos m(\theta - \phi), & \rho < R_\zeta \end{cases}$$

$$\odot \zeta_1 \rightarrow \begin{cases} \ln a - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R_1}{a}\right)^m \cos m(\theta_1 - \phi), & a > R_1 \\ \ln \rho - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R_1}{\rho}\right)^m \cos m(\theta_1 - \phi), & \rho > R_1 \end{cases}$$

$$\frac{R_1}{a} = \frac{a}{R_\zeta} \Rightarrow R_1 = \frac{a^2}{R_\zeta}$$

$$\otimes \zeta_3 \rightarrow \begin{cases} \ln a - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R_3}{a}\right)^m \cos m(\theta_2 - \phi), & a > R_3 \\ \ln \rho - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R_3}{\rho}\right)^m \cos m(\theta_2 - \phi), & \rho > R_3 \end{cases}$$

$$\frac{R_3}{a} = \frac{a}{R_2} \Rightarrow R_3 = \frac{a^2}{R_2}$$



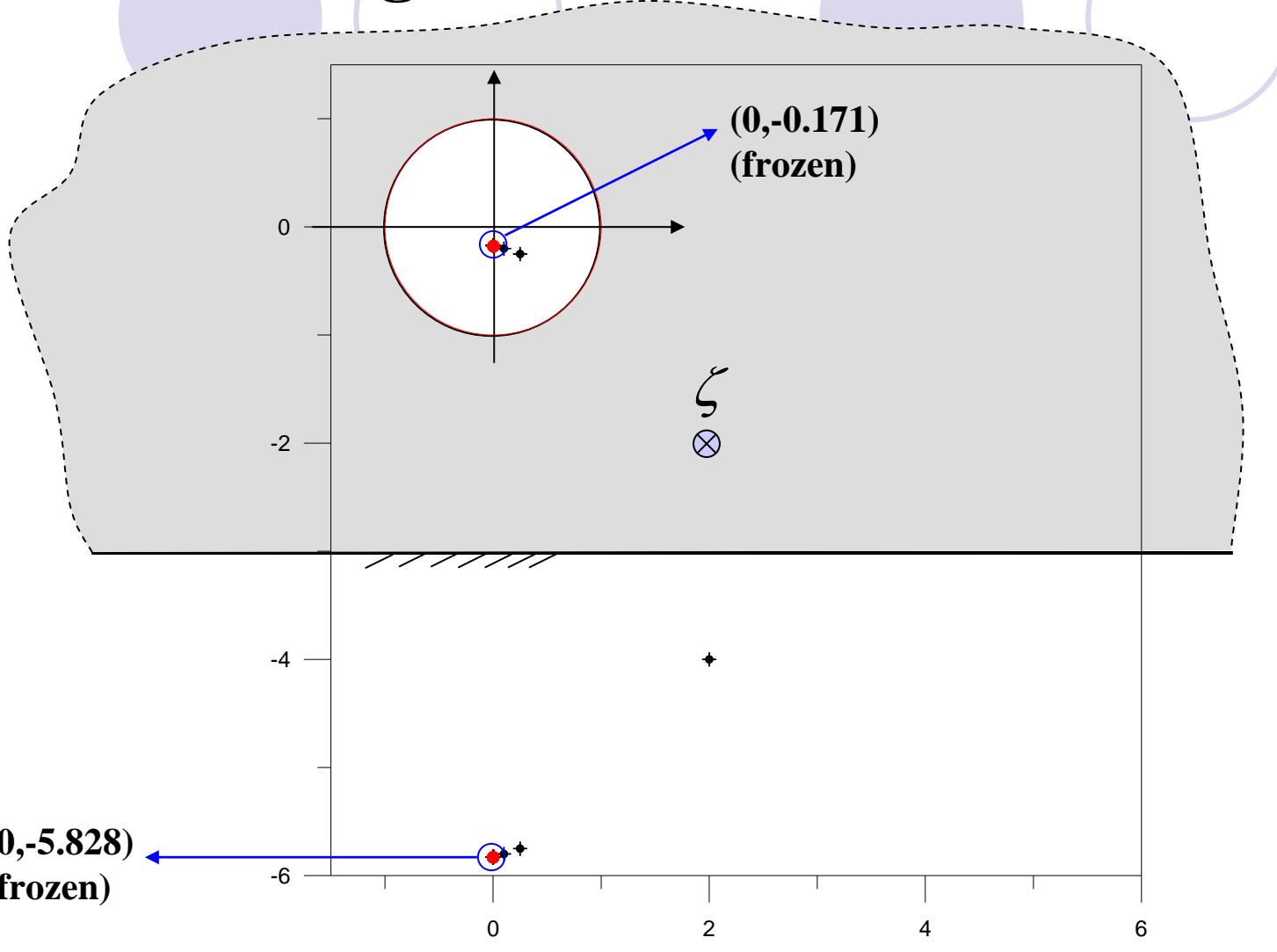
$$\odot \zeta_2 \rightarrow \begin{cases} \ln R_2 - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{a}{R_2}\right)^m \cos m(\theta_2 - \phi), & a < R_2 \\ \ln R_2 - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{\rho}{R_2}\right)^m \cos m(\theta_2 - \phi), & \rho < R_2 \end{cases}$$

$$\theta_2 = \tan^{-1} \frac{2b - R_\zeta \sin \theta_1}{R_\zeta \cos \theta_1}, \quad R_2 = \frac{R_\zeta \cos \theta_1}{\cos \theta_2}$$

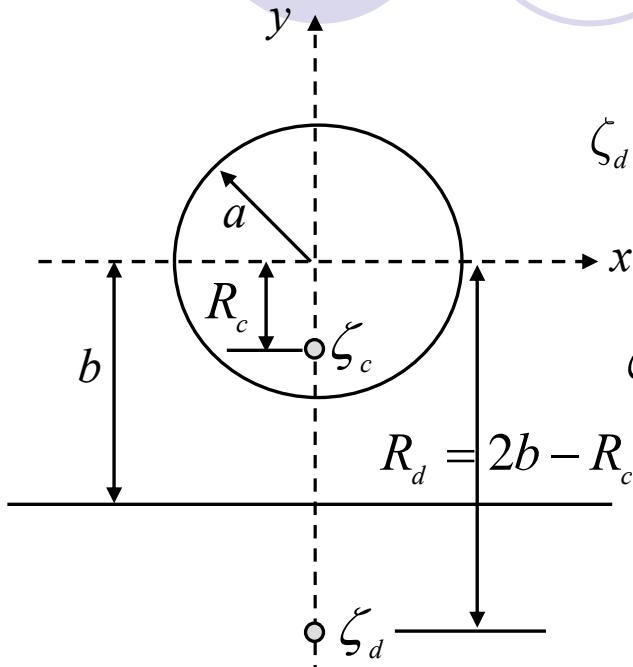
$$\otimes \zeta_4 \rightarrow \begin{cases} \ln R_4 - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{a}{R_4}\right)^m \cos m(\theta_3 - \phi), & a < R_4 \\ \ln R_4 - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{\rho}{R_4}\right)^m \cos m(\theta_3 - \phi), & \rho < R_4 \end{cases}$$

$$\theta_3 = \tan^{-1} \frac{2b - R_1 \sin \theta_1}{R_1 \cos \theta_1}, \quad R_4 = \frac{R_1 \cos \theta_1}{\cos \theta_3}$$

Frozen image location



Analytical derivation of location for the two frozen points



$$\zeta_d \rightarrow \ln|x - \zeta_d| = \ln R_d - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{a}{R_d}\right)^m \cos m(\psi_d - \phi), a < R_d$$

$$\zeta_c \rightarrow \ln|x - \zeta_c| = \ln a - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R_c}{a}\right)^m \cos m(\psi_d - \phi), a > R_c$$

↓

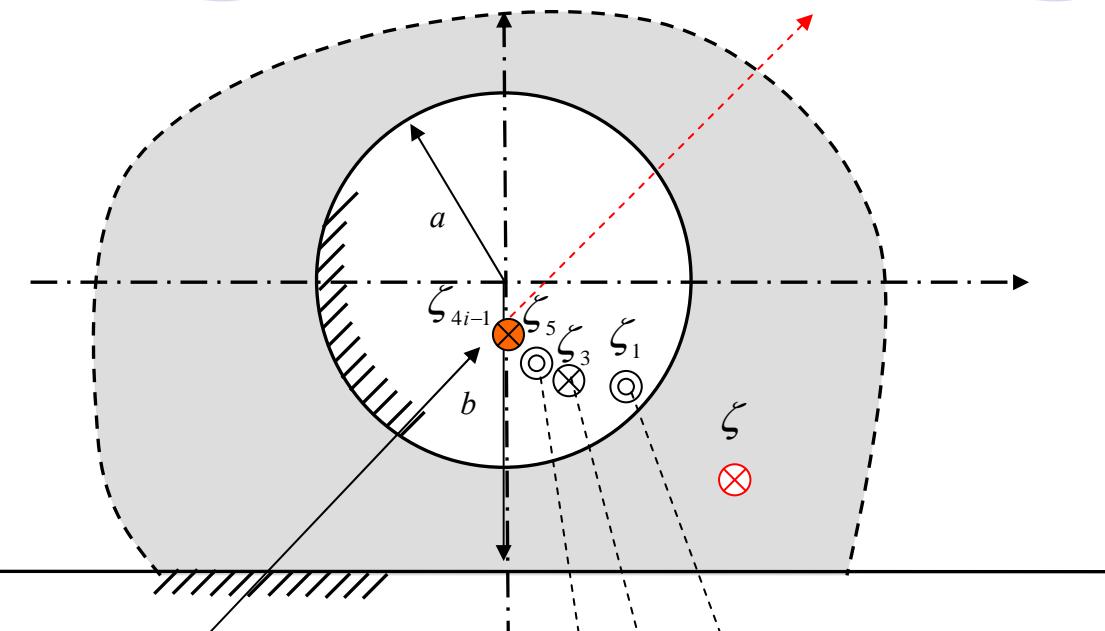
$$\frac{R_c}{a} = \frac{a}{R_d} \Rightarrow R_c = \frac{a^2}{R_d}$$

$$\therefore R_c = \frac{a^2}{2b - R_c}$$

$$\Rightarrow R_c^2 - 6R_c + 1 = 0$$

$$\Rightarrow R_c = 3 \pm 2\sqrt{2} \quad (0.171 \text{ & } 5.828)$$

Series of images



The final two frozen images

$$\odot \zeta_{4i-3}, i \in N \Rightarrow \lim_{N \rightarrow \infty} \ln |x - \zeta_c|$$

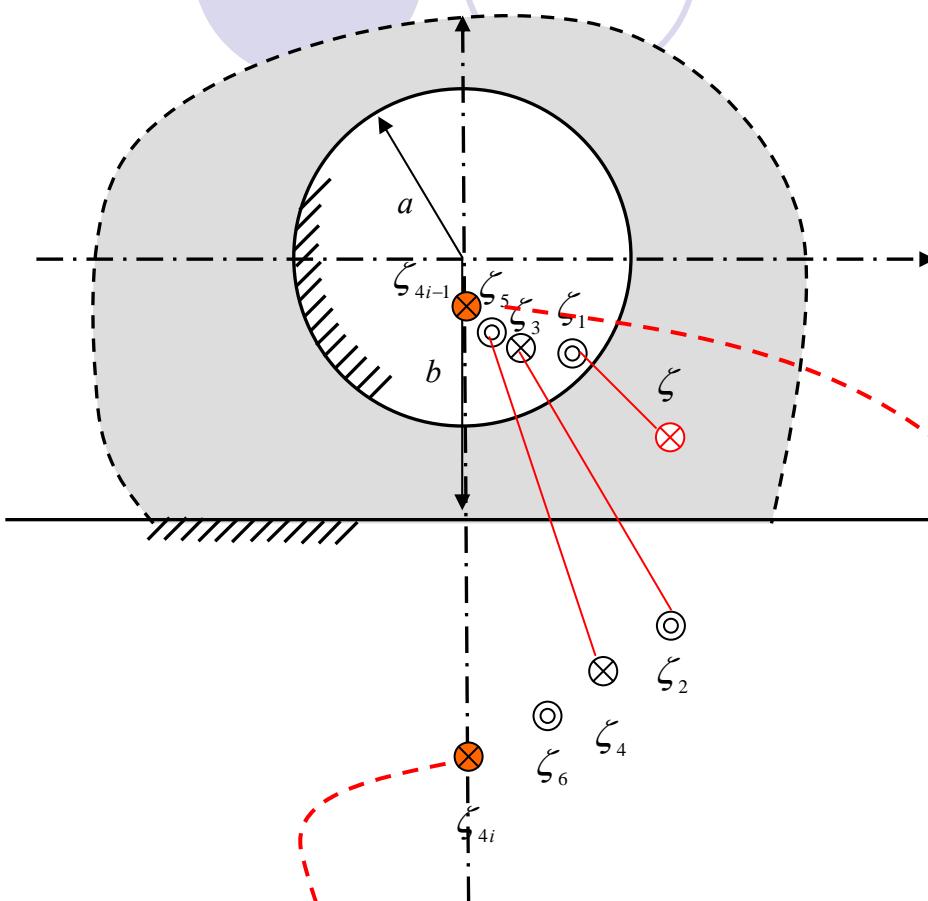
$$\odot \zeta_{4i-2}, i \in N \Rightarrow \lim_{N \rightarrow \infty} \ln |x - \zeta_d|$$

frozen $\zeta_d = (0, -5.828)$

MSVLAB

HRE, HTOU

Rigid body term



$$G(x, \zeta) = \frac{1}{2\pi} \left\{ \ln|x - \zeta| - \lim_{N \rightarrow \infty} \left[\sum_{i=1}^N \left(\ln|x - \zeta_{4i-3}| + \ln|x - \zeta_{4i-2}| - \ln|x - \zeta_{4i-1}| - \ln|x - \zeta_{4i}| \right) + c(N) \ln|x - \zeta_c| + d(N) \ln|x - \zeta_d| + e(N) \right] \right\}$$

MSVLAB
HRE, HTOU

$$\begin{cases} \otimes \zeta \Rightarrow \ln R_\zeta - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{a}{R_\zeta} \right)^m \cos m(\psi - \phi), \rho \in B_1 \\ \odot \zeta_1 \Rightarrow \ln a - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R_1}{a} \right)^m \cos m(\psi_1 - \phi), \rho \in B_1 \end{cases}$$

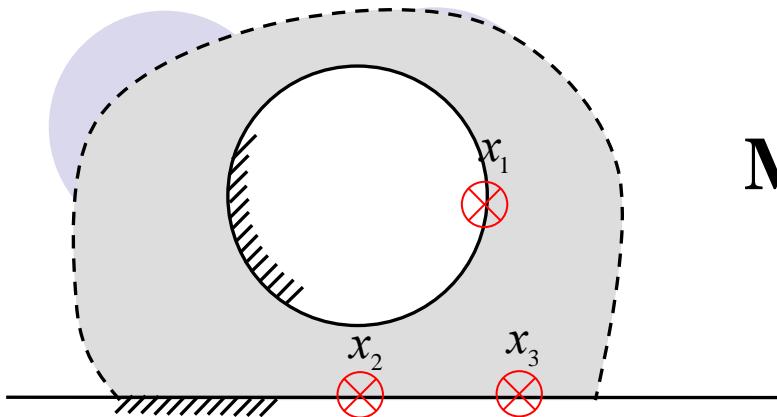
$$\because R_1 = \frac{a^2}{R_\zeta} \therefore \ln|x - s_\zeta| - \ln|x - s_1| = \ln R_\zeta - \ln a$$

$$\begin{cases} \odot \zeta_2 \Rightarrow \ln R_2 - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{a}{R_2} \right)^m \cos m(\psi_2 - \phi), \rho \in B_1 \\ \otimes \zeta_3 \Rightarrow \ln a - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R_3}{a} \right)^m \cos m(\psi_2 - \phi), \rho \in B_1 \end{cases}$$

$$\because R_3 = \frac{a^2}{R_2} \therefore -\ln|x - s_2| + \ln|x - s_3| = \ln a - \ln R_2$$

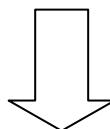
$$\vdots$$

$$\therefore \ln R_\zeta - \ln a + \ln a + \ln R_2 + \dots \Rightarrow e(N)$$



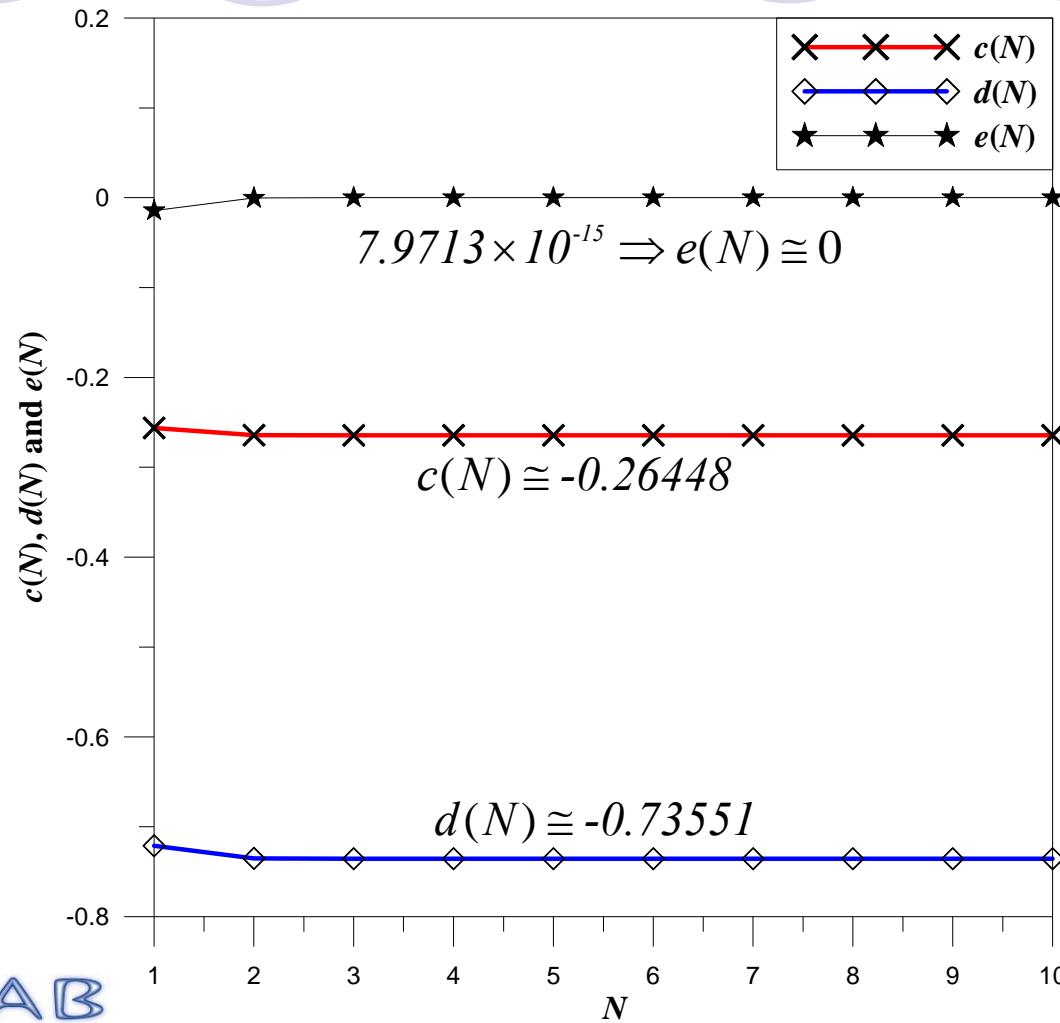
Matching BCs to determine three coefficient

$$\begin{cases} \ln|x_1 - \zeta| - \lim_{N \rightarrow \infty} \left[\sum_{i=1}^N (\ln|x_1 - \zeta_{4i-3}| + \ln|x_1 - \zeta_{4i-2}| - \ln|x_1 - \zeta_{4i-1}| - \ln|x_1 - \zeta_{4i}|) + c(N) \ln|x_1 - \zeta_c| + d(N) \ln|x_1 - \zeta_d| + e(N) \right] = 0 \\ \frac{1}{2\pi} \left[\ln|x_2 - \zeta| - \lim_{N \rightarrow \infty} \left[\sum_{i=1}^N (\ln|x_2 - \zeta_{4i-3}| + \ln|x_2 - \zeta_{4i-2}| - \ln|x_2 - \zeta_{4i-1}| - \ln|x_2 - \zeta_{4i}|) + c(N) \ln|x_2 - \zeta_c| + d(N) \ln|x_2 - \zeta_d| + e(N) \right] \right] = 0 \\ \ln|x_3 - \zeta| - \lim_{N \rightarrow \infty} \left[\sum_{i=1}^N (\ln|x_3 - \zeta_{4i-3}| + \ln|x_3 - \zeta_{4i-2}| - \ln|x_3 - \zeta_{4i-1}| - \ln|x_3 - \zeta_{4i}|) + c(N) \ln|x_3 - \zeta_c| + d(N) \ln|x_3 - \zeta_d| + e(N) \right] = 0 \end{cases}$$

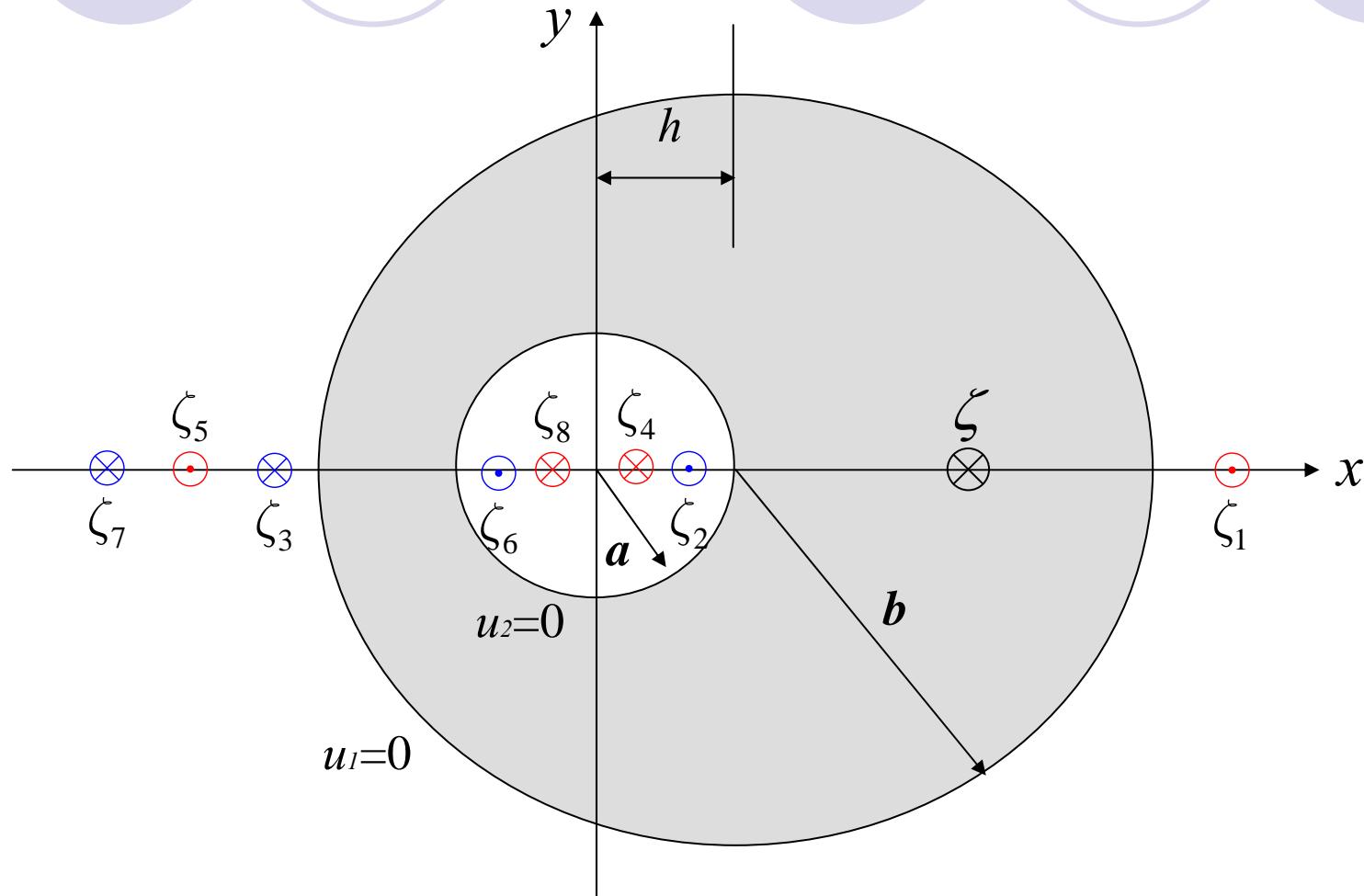


$$\begin{cases} \ln|x_1 - \zeta| - \sum_{i=1}^N (\ln|x_1 - \zeta_{4i-3}| + \ln|x_1 - \zeta_{4i-2}| - \ln|x_1 - \zeta_{4i-1}| - \ln|x_1 - \zeta_{4i}|) \\ \ln|x_2 - \zeta| - \sum_{i=1}^N (\ln|x_2 - \zeta_{4i-3}| + \ln|x_2 - \zeta_{4i-2}| - \ln|x_2 - \zeta_{4i-1}| - \ln|x_2 - \zeta_{4i}|) \\ \ln|x_3 - \zeta| - \sum_{i=1}^N (\ln|x_3 - \zeta_{4i-3}| + \ln|x_3 - \zeta_{4i-2}| - \ln|x_3 - \zeta_{4i-1}| - \ln|x_3 - \zeta_{4i}|) \end{cases} + \begin{bmatrix} \ln|x_1 - \zeta_c| & \ln|x_1 - \zeta_d| & 1 \\ \ln|x_2 - \zeta_c| & \ln|x_2 - \zeta_d| & 1 \\ \ln|x_3 - \zeta_c| & \ln|x_3 - \zeta_d| & 1 \end{bmatrix} \begin{bmatrix} c(N) \\ d(N) \\ e(N) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Numerical approach to determine $c(N)$, $d(N)$ and $e(N)$



Semi-analytical solution: case 4



MFS-Image group

$$\otimes \zeta(R_\zeta + h, \theta)$$

$$U(\zeta, x) = \ln b - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R_\zeta}{b} \right)^m \cos(m(\theta_\zeta - \phi_1))$$

$$U(\zeta, x) = \ln R_\zeta - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{a}{R_\zeta + h} \right)^m \cos(m(\theta_\zeta - \phi_2))$$

$$\odot \zeta_1(R_1, \theta_1)$$

$$U(\zeta_1, x) = \ln R_1 - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{b}{R_1} \right)^m \cos(m(\theta_1 - \phi))$$

$$U(\zeta_1, x) = \ln R_1 - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{a}{R_1} \right)^m \cos(m(\theta_1 - \phi))$$

$$R_1 = \frac{b^2}{R_\zeta - h} + h \quad R_5 = \frac{b^2}{h - R_4} - h \quad R_9 = \frac{b^2}{R_8 + e} - e \quad R_{13} = \frac{b^2}{R_{12} + h} - h$$

$$R_2 = \frac{a^2}{R_\zeta}$$

$$R_6 = \frac{a^2}{R_3}$$

$$R_{10} = \frac{a^2}{R_7}$$

$$R_{14} = \frac{a^2}{R_{11}}$$

$$R_3 = \frac{b^2}{h - R_2} - h$$

$$R_7 = \frac{b^2}{R_6 + h} - h$$

$$R_{11} = \frac{b^2}{R_{10} + e} - e$$

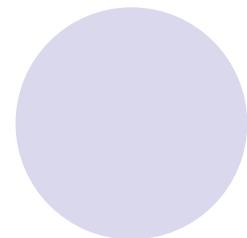
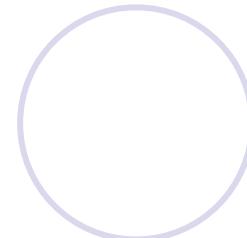
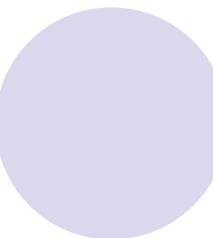
$$R_{15} = \frac{b^2}{R_{14} + h} - h \dots$$

$$R_4 = \frac{a^2}{R_1}$$

$$R_8 = \frac{a^2}{R_5}$$

$$R_{12} = \frac{a^2}{R_9}$$

$$R_{16} = \frac{a^2}{R_{13}}$$

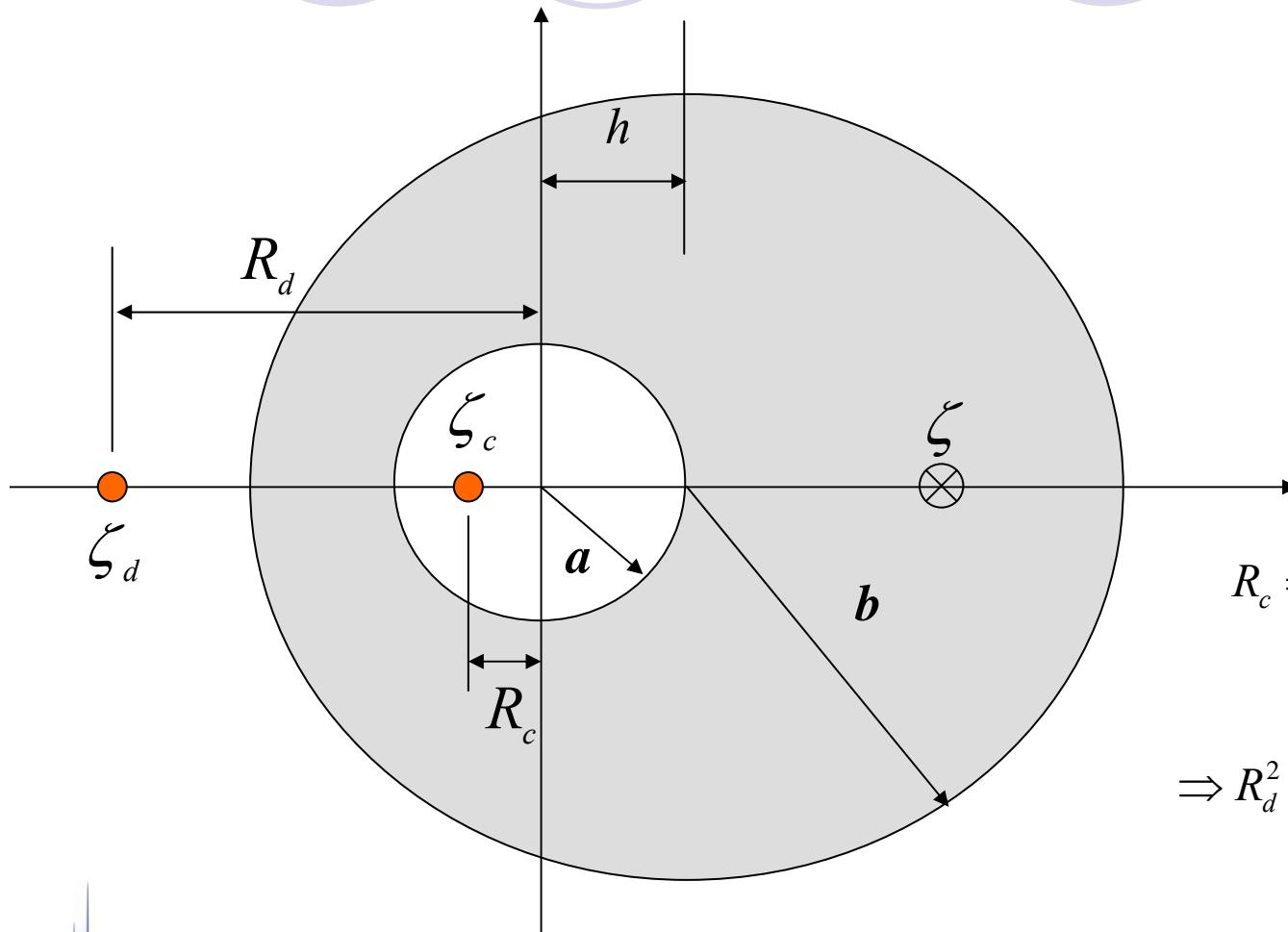


$$\odot \zeta_2(R_2, \theta_2)$$

$$U(\zeta_2, x) = \ln b - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R_2}{b} \right)^m \cos(m(\theta_2 - \phi_2))$$

$$U(\zeta_2, x) = \ln a - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R_2}{a} \right)^m \cos(m(\theta_2 - \phi_2))$$

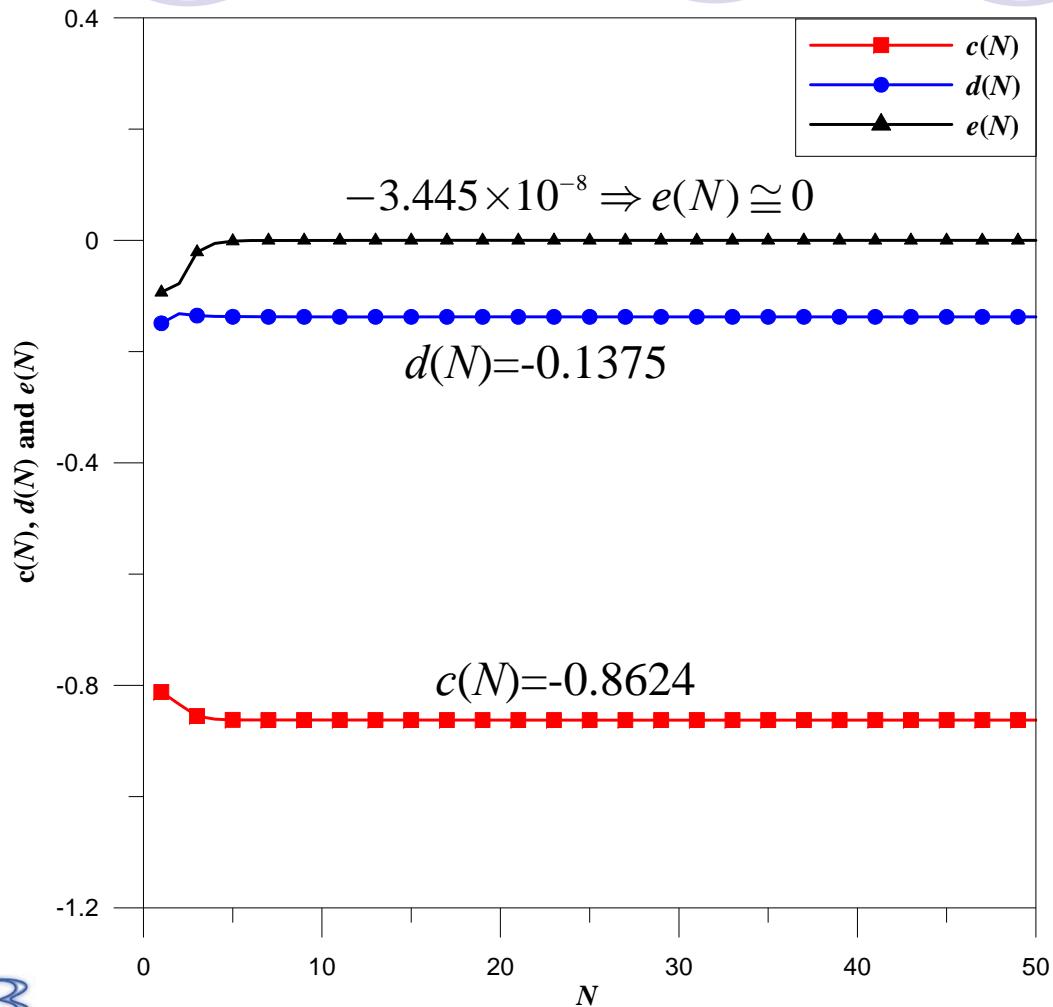
Analytical derivation of location for the two frozen points



$$R_c = \frac{a^2}{R_d}, \quad R_d = \frac{b^2}{R_c + h} - h$$

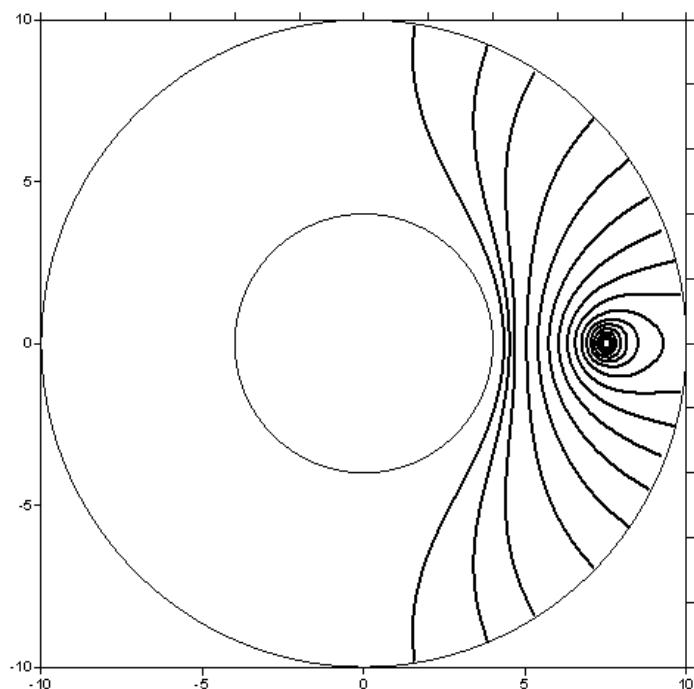
$$\Rightarrow R_d^2 + \frac{(a^2 - b^2 + h^2)R_d}{h} + a^2 = 0$$

Numerical approach to determine $c(N)$, $d(N)$ and $e(N)$



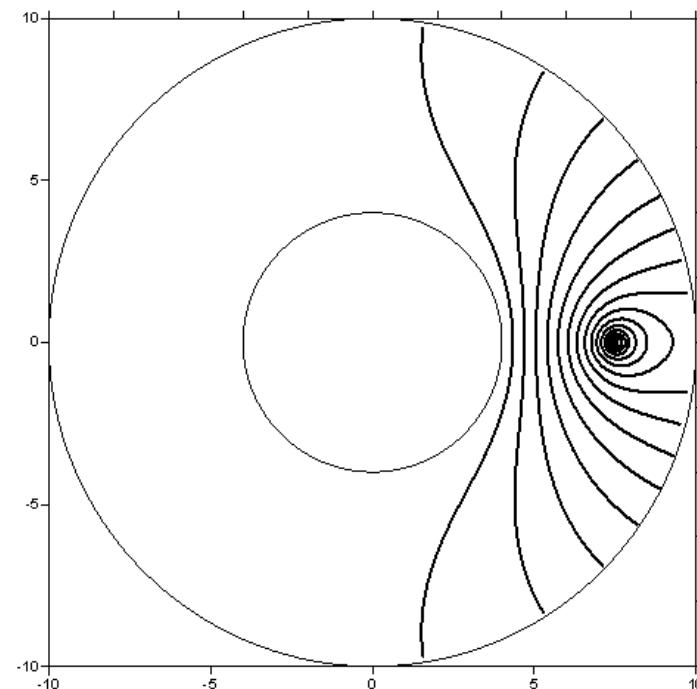
Numerical results: case 1

Fixed-free boundary for the annular case



m=20

(a) Trefftz method



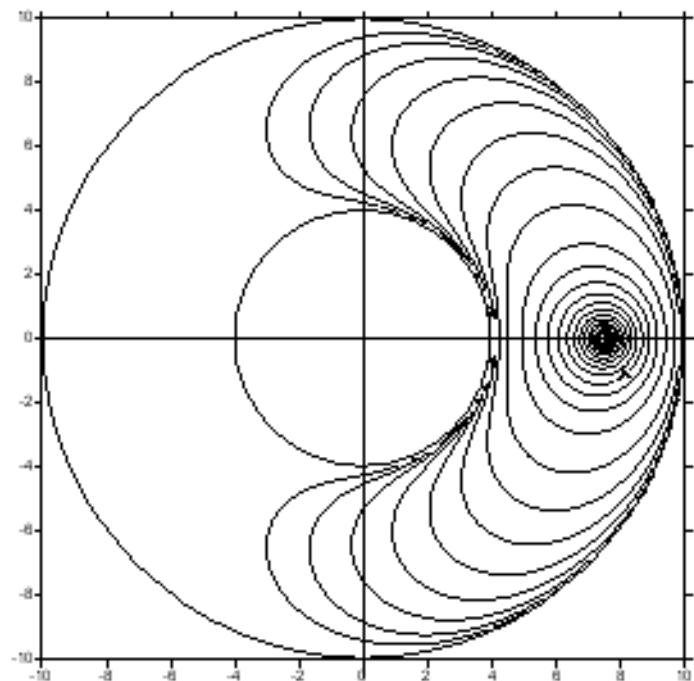
N=20

(b) Image method

Contour plot for the analytical solution ($m=N$).

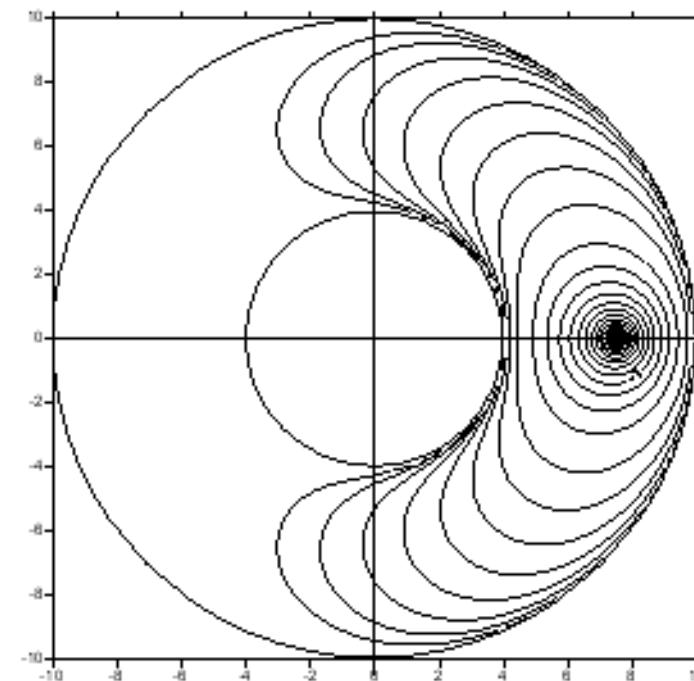
Numerical results: case 2

Fixed-fixed boundary for the annular case



m=20

(a) Trefftz method

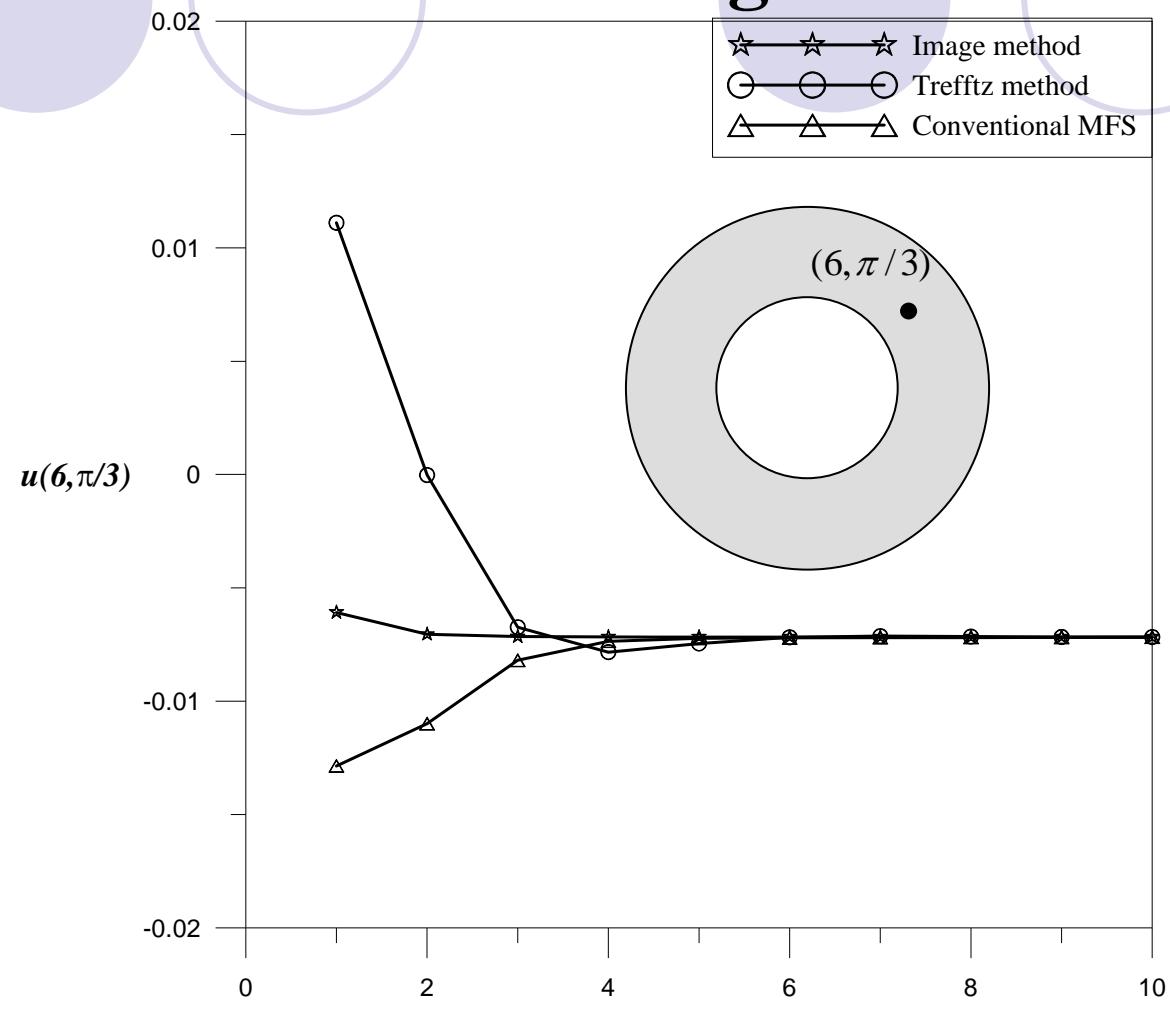


N=20

(b) Image method

Contour plot for the analytical solution ($m=N$).

Numerical results: convergence



Numerical results: convergence rate

Best

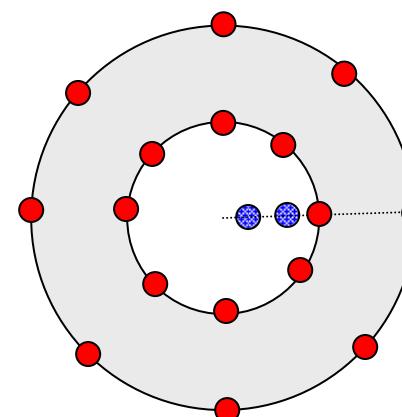
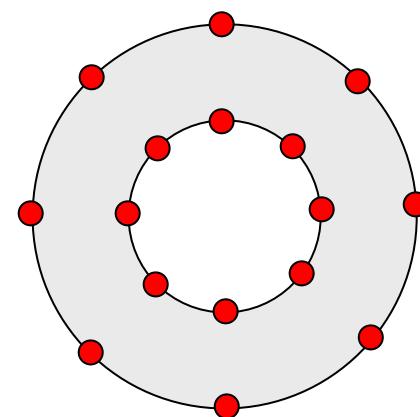
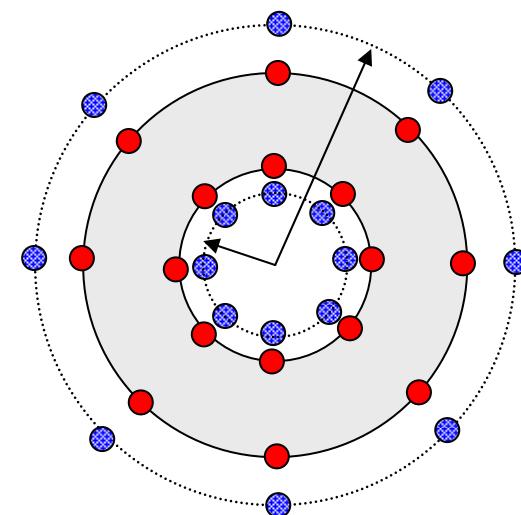


Image method



Trefftz method



Conventional MFS

Numerical results: case 3

Dirichlet boundary for the half-plane case

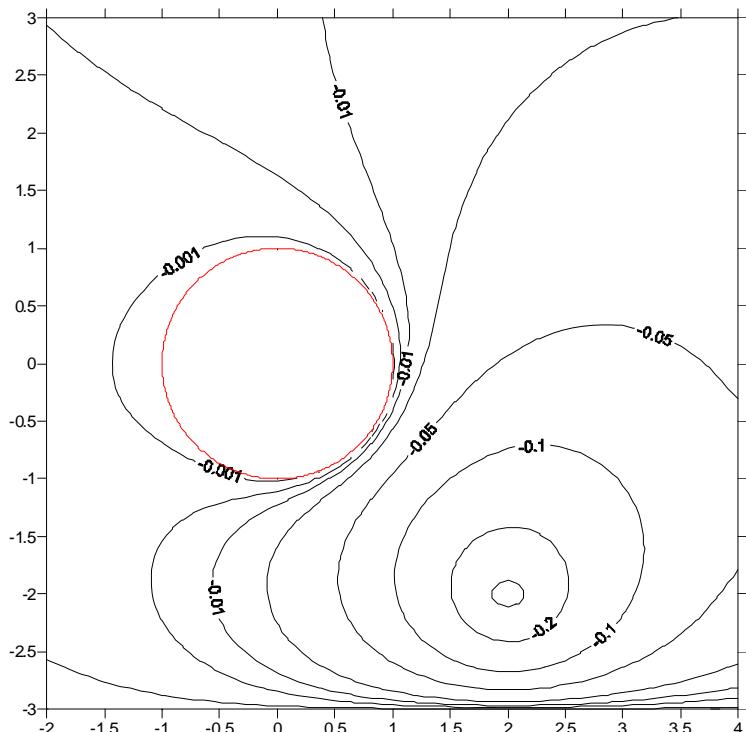
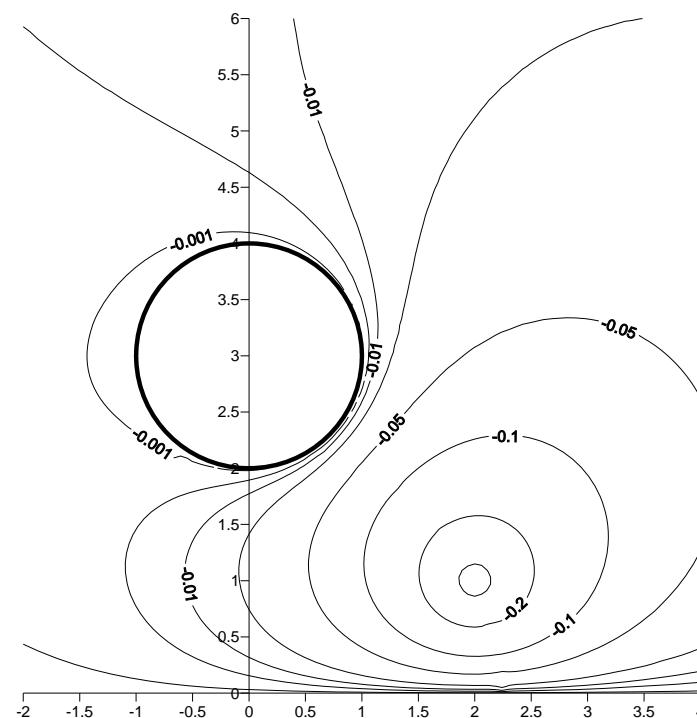


Image method
40+2 points

MSVLAB

HRE, HTOU



Null-field BIE approach (addition theorem
and superposition technique) (M=50)

Numerical results: case 4

Dirichlet boundary for the eccentric case

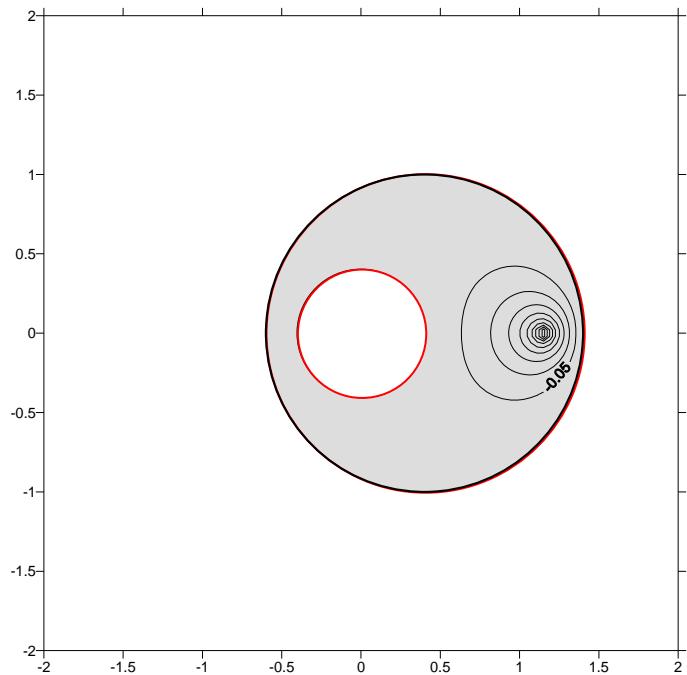
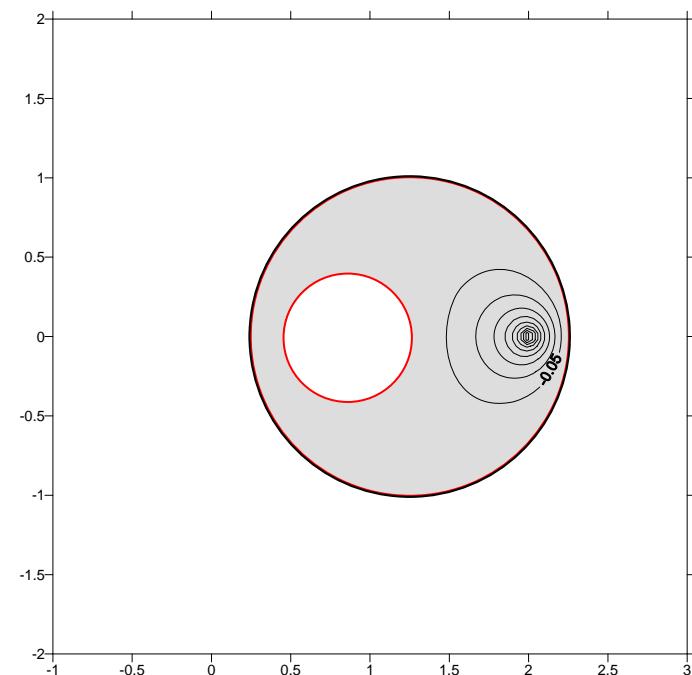


image method



analytical solution

(bi-polar coordinate)



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Numerical results: case 5

Dirichlet boundary for the eccentric case

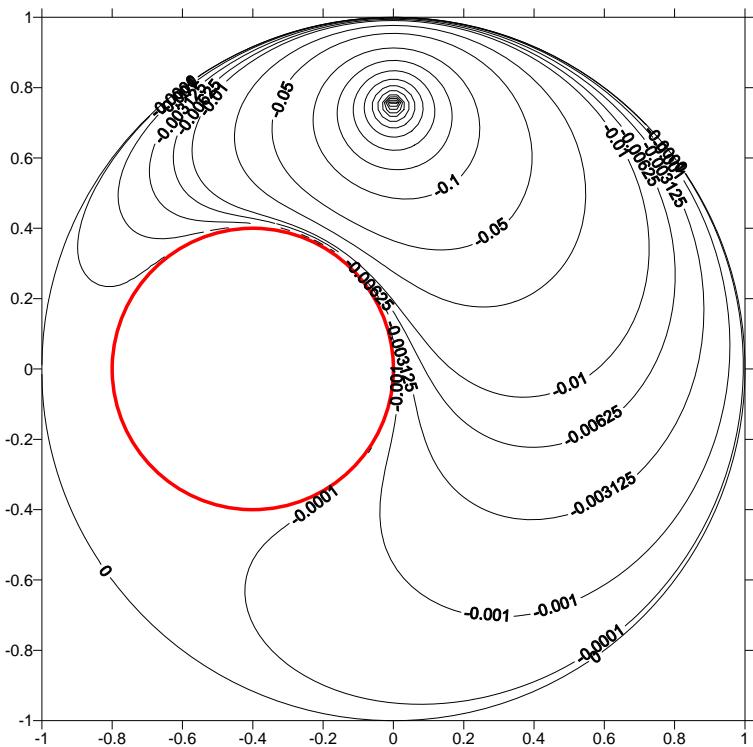


Image method (50+2 point)

MSVLAB

HRE, HTOU

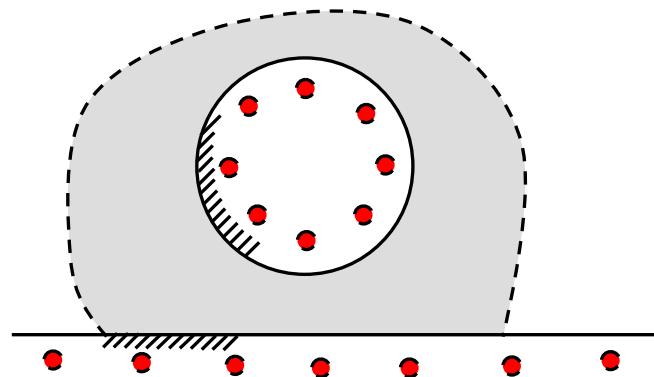
Null-field BIE approach (addition theorem
and superposition technique) (M=50)

Conclusions

- The analytical solutions derived by the Trefftz method and MFS were proved to be **mathematically equivalent** for the annular Green's functions.
- We can find final two **frozen image points** (one at origin and one at infinity). Their singularity strength can be determined numerically and analytically in a consistent manner.
- The image method can be seen as a **special case** for method of fundamental solution with optimal locations of sources.



Image method versus MFS

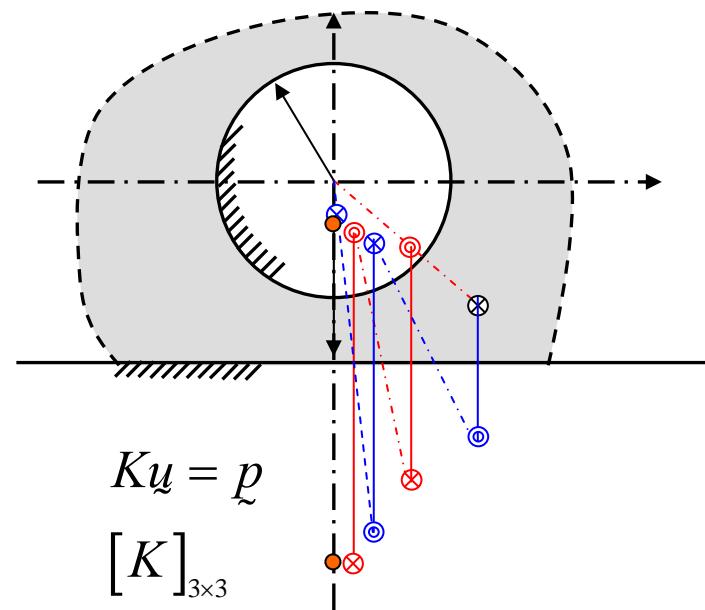


All the strength need to be determined.

$$K\mathbf{\tilde{u}} = \mathbf{\tilde{p}}$$

$$[K]_{N \times N}$$

$N \rightarrow$ large

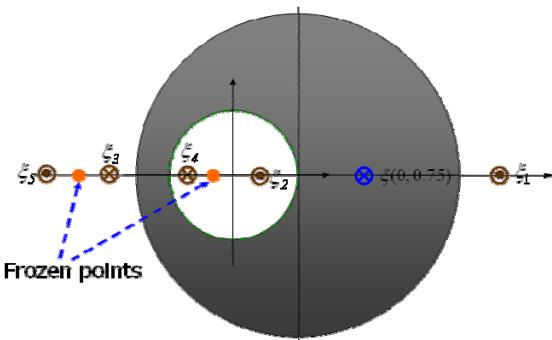


Only three coefficients are required
to be determined.

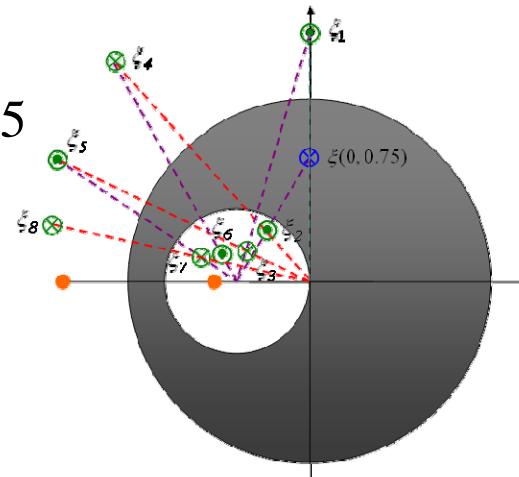
Optimal location of MFS

- Depends on loading

Case 4

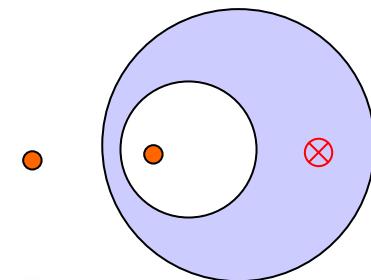


Case 5

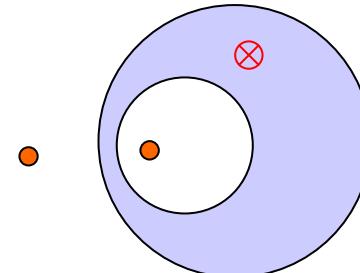


- Depends on geometry

Case 4



Case 5



心得—三個故事

- 馬哲儒與虞兆中校長的一則故事
- 莒光日案例
- 帶學生做研究的辛酸與喜樂

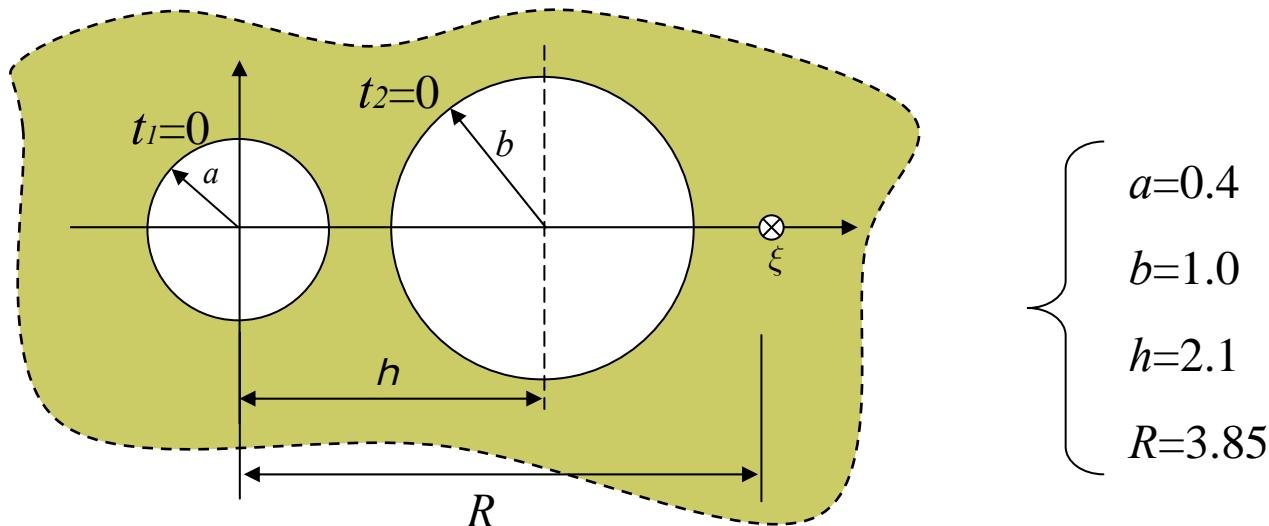


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- J.T. Chen, Y.T. Lee and S.C. Shieh, Image method and method of fundamental solution with optimal location of sources, (2009), submitted
- J. T. Chen, K. H. Chou and S. K. Kao, Derivation of Green's function using addition theorem, *MRC*, (2009), in press.
- J.T. Chen, M.H. Tsai and C.S. Liu, Conformal mapping and bipolar coordinate for eccentric Laplace problems, *CAEE*, (2009), Accepted.

Homework (小試身手-海大能，台大一定能!)

Please use the image method to solve the 2-D Laplace problem.



有做出來的同學歡迎寄到我的信箱或MSN

(jtchen@mail.ntou.edu.tw & jt-chen@hotmail.com)

我會義務幫你們核對答案，並為楊老師義務幫你們改作業

MSVLAB

HRE, HTOU



NTOU/MSV Lab's web- <http://msvlab.hre.ntou.edu.tw/>

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教學良心事



Chinese Version English Version



Acknowledgement

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- + 中華顧問
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- + COE, Japan
- + IST, Portugal

- + 台大土木系 楊德良與洪宏基
終身特聘教授
- + 中山科學院 王政盛博士
- + 高海大造船系 陳義麟博士
- + 宜大土木系 陳桂鴻 博士
- + 中華機械系 李為民 博士
- + 中華機械系 呂學育 博士
- + 中山科學院 全湘偉博士
- + NTOU/MSV group members





Thanks for your kind attentions

You can get more information from our website

<http://msvlab.hre.ntou.edu.tw/>

